

# Transductions

Emmanuel Filiot<sup>a</sup> and Pierre-Alain Reynier<sup>b</sup>

<sup>a</sup> Université libre de Bruxelles & FNRS

<sup>b</sup> LIS, Aix-Marseille Université & CNRS

EJCIM School

# Specification

**Describe** properties

# Computation

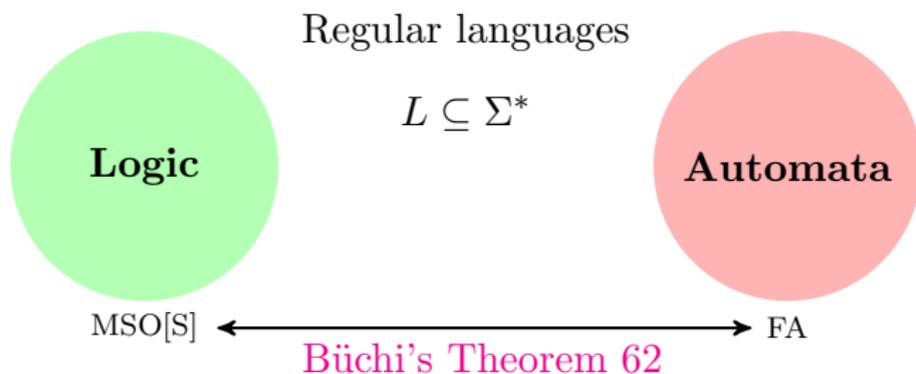
**Decide** those properties

## Specification

**Describe** properties

## Computation

**Decide** those properties



## Specification

**Describe** properties

## Computation

**Decide** those properties



**Many extensions:** infinite words, finite and infinite trees, graphs, other logics ...

## Specification

**Describe** properties

## Computation

**Decide** those properties



**Many extensions:** infinite words, finite and infinite trees, graphs, other logics ...

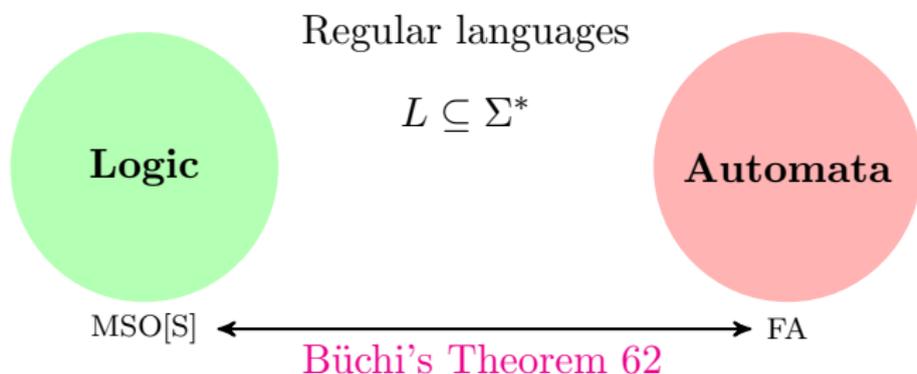
**Famous application:** Model-checking  $A \models \phi$  ?

## Specification

**Describe** properties

## Computation

**Decide** those properties



**Many extensions:** infinite words, finite and infinite trees, graphs, other logics ...

**Famous application:** Model-checking  $A \models \phi$  ?

$$L(A) \cap L(A_{\neg\phi}) = \emptyset$$

## Objective of the talk

What about transductions ?

$$f : \Sigma^* \hookrightarrow \Sigma^*$$

## Objective of the talk

What about transductions ?

$$f : \Sigma^* \hookrightarrow \Sigma^*$$

Append a #

*abbab*  $\mapsto$  *abbab*#

## Objective of the talk

What about transductions ?

$$f : \Sigma^* \hookrightarrow \Sigma^*$$

Append a #

$$abbab \mapsto abbab\#$$

Delete all  $b$

$$abbab \mapsto aa$$

## Objective of the talk

What about transductions ?

$$f : \Sigma^* \hookrightarrow \Sigma^*$$

Append a #

*abbab*  $\mapsto$  *abbab*#

Delete all *b*

*abbab*  $\mapsto$  *aa*

Squeeze all white space sequences  $\geq 2$

*ejcim\_ \_ \_19*  $\mapsto$  *ejcim\_19*

## Objective of the talk

What about transductions ?

$$f : \Sigma^* \hookrightarrow \Sigma^*$$

Append a #

*abbab*  $\mapsto$  *abbab#*

Delete all *b*

*abbab*  $\mapsto$  *aa*

Squeeze all white space sequences  $\geq 2$

*ejcim\_ \_ \_ 19*  $\mapsto$  *ejcim\_19*

Add a parity bit

*0100101*  $\mapsto$  *10100101*

## Objective of the talk

What about transductions ?

$$f : \Sigma^* \hookrightarrow \Sigma^*$$

Append a #

*abbab*  $\mapsto$  *abbab#*

Delete all *b*

*abbab*  $\mapsto$  *aa*

Squeeze all white space sequences  $\geq 2$

*ejcim\_ \_ \_19*  $\mapsto$  *ejcim\_19*

Add a parity bit

*0100101*  $\mapsto$  *10100101*

Mirror the input word

*ejcim*  $\mapsto$  *micje*

## Objective of the talk

# What about transductions ?

$$f : \Sigma^* \hookrightarrow \Sigma^*$$

Append a #

*abbab*  $\mapsto$  *abbab#*

Delete all *b*

*abbab*  $\mapsto$  *aa*

Squeeze all white space sequences  $\geq 2$

*ejcim\_ \_ \_19*  $\mapsto$  *ejcim\_19*

Add a parity bit

*0100101*  $\mapsto$  *10100101*

Mirror the input word

*ejcim*  $\mapsto$  *micje*

Copy the input word

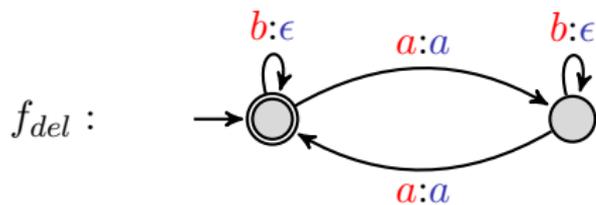
*yes*  $\mapsto$  *yesyes*

# Outline

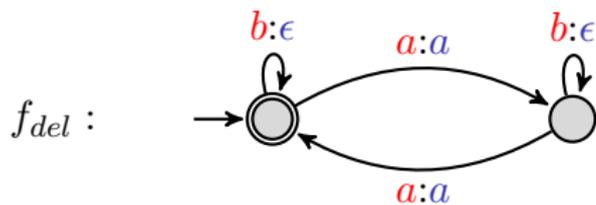
1. automata for transductions
2. closure properties and decision problems
3. logics for transductions
4. a more expressive class of functions
5. recent results

# Automata models for transductions

# Automata for transductions: transducers

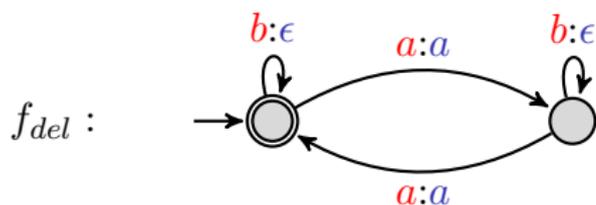


## Automata for transductions: transducers



$aabaa \mapsto aaaa$

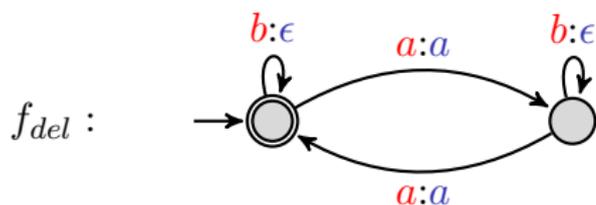
## Automata for transductions: transducers



$aabaa \mapsto aaaa$

$aaba \mapsto \text{undefined}$

## Automata for transductions: transducers

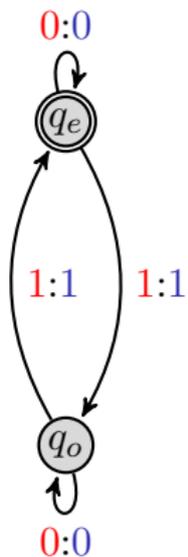


$aabaa \mapsto aaaa$

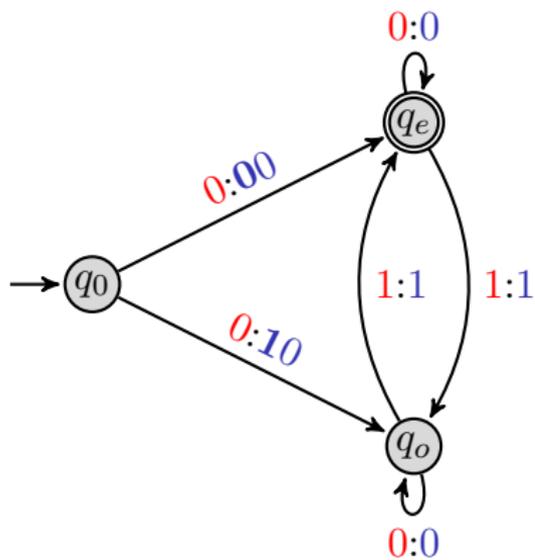
$aaba \mapsto \text{undefined}$

$\text{dom}(f_{del}) = \text{'even number of } a \text{'}$

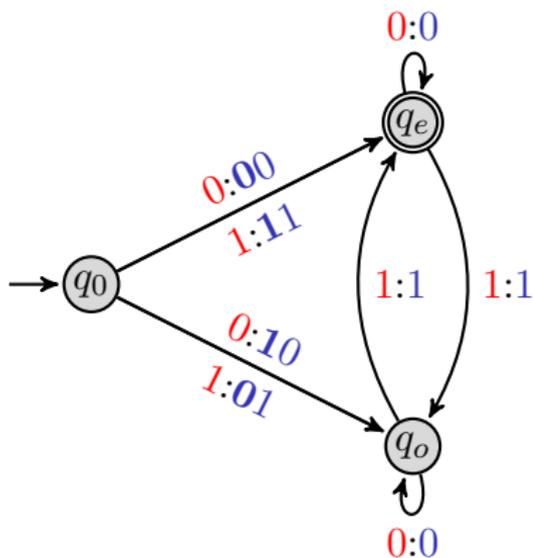
## Parity bit

 $01101 \mapsto 101101, 01111 \mapsto 001111$ 

## Parity bit

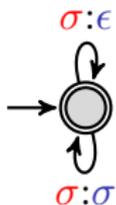
 $01101 \mapsto 101101, 01111 \mapsto 001111$ 

## Parity bit

 $01101 \mapsto 101101, 01111 \mapsto 001111$ 


# Non-determinism and relations

In general, transducers define binary *relations* in  $\Sigma^* \times \Sigma^*$



realizes  $\{(u, v) \mid v \text{ is a subword of } u\}$

## Formal Definition

### Definition

A transducer is a tuple  $T = (\Sigma, Q, I, F, \Delta)$  where:

- ▶  $\Sigma$  is a finite alphabet
- ▶  $Q$  is a finite set of states
- ▶  $I \subseteq Q$  are the initial states and  $F \subseteq Q$  are the final states
- ▶  $\Delta \subseteq Q \times \Sigma \times \Sigma^* \times Q$  is the transition relation.

## Formal Definition

### Definition

A transducer is a tuple  $T = (\Sigma, Q, I, F, \Delta)$  where:

- ▶  $\Sigma$  is a finite alphabet
- ▶  $Q$  is a finite set of states
- ▶  $I \subseteq Q$  are the initial states and  $F \subseteq Q$  are the final states
- ▶  $\Delta \subseteq Q \times \Sigma \times \Sigma^* \times Q$  is the transition relation.

### Semantics

A run is a sequence of transitions

$$r = q_0 \xrightarrow{\sigma_1:v_1} q_1 \dots q_{n-1} \xrightarrow{\sigma_n:v_n} q_n \quad \sigma_i \in \Sigma$$

Its input is  $in(r) = \sigma_1 \dots \sigma_n$  and its output  $out(r) = v_1 \dots v_n$ .

The (rational) relation defined by  $T$  is:

$$\llbracket T \rrbracket = \{(in(r), out(r)) \mid r \text{ is an accepting run}\}$$

# Closure Properties: Domain and Co-Domain

Given  $R \subseteq \Sigma^* \times \Sigma^*$ :

- ▶  $dom(R) = \{u \mid \exists(u, v) \in R\}$
- ▶  $codom(R) = \{v \mid \exists(u, v) \in R\}$

## Closure Properties: Domain and Co-Domain

Given  $R \subseteq \Sigma^* \times \Sigma^*$ :

- ▶  $\text{dom}(R) = \{u \mid \exists (u, v) \in R\}$
- ▶  $\text{codom}(R) = \{v \mid \exists (u, v) \in R\}$

### Proposition

*The domain and co-domain of a rational relation are regular.*

# Closure Properties: Union

## Proposition

*Rational relations are closed under union.*

## Closure Properties: Intersection

1. show that  $\{(a^n b^m, a^n) \mid n, m \geq 0\}$  is rational.

## Closure Properties: Intersection

1. show that  $\{(a^n b^m, a^n) \mid n, m \geq 0\}$  is rational.
  
  
  
  
  
  
  
  
  
  
2. show that  $\{(a^n b^m, a^m) \mid n, m \geq 0\}$  is rational.

## Closure Properties: Intersection

1. show that  $\{(a^n b^m, a^n) \mid n, m \geq 0\}$  is rational.
2. show that  $\{(a^n b^m, a^m) \mid n, m \geq 0\}$  is rational.
3. are rational relations closed under intersection ? why ?

# Closure Properties: Intersection

## Proposition

*Rational relations are not closed under intersection.*

# Closure Properties: Intersection

## Proposition

*Rational relations are not closed under intersection.*

What about complement ?

# Closure Properties: Intersection

## Proposition

*Rational relations are not closed under intersection.*

What about complement ?

## Proposition

*Rational relations are not closed under complement.*

## Closure Properties: Composition

**Def:**  $R_2 \circ R_1 = \{(u, w) \mid \exists (u, v) \in R_1, (v, w) \in R_2\}$ .

## Closure Properties: Composition

**Def:**  $R_2 \circ R_1 = \{(u, w) \mid \exists (u, v) \in R_1, (v, w) \in R_2\}$ .

### Proposition

*Rational relations are closed under composition.*

# Proof

Let  $T_1 = (\Sigma, Q_1, I_1, F_1, \Delta_1)$  and  $T_2 = (\Sigma, Q_2, I_2, F_2, \Delta_2)$ .

- ▶ For all  $u \in \Sigma^*$  and  $p_2 \in Q_2$ , let

$$\text{Prod}_2(u, p_2) = \{(v, q_2) \in \Sigma^* \times Q_2 \mid p_2 \xrightarrow{u|v}_{T_2} q_2\}$$

# Proof

Let  $T_1 = (\Sigma, Q_1, I_1, F_1, \Delta_1)$  and  $T_2 = (\Sigma, Q_2, I_2, F_2, \Delta_2)$ .

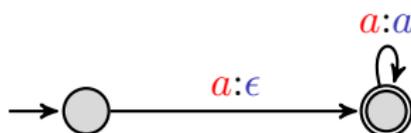
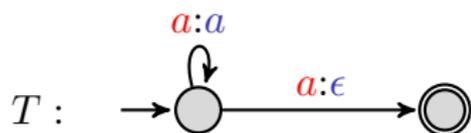
- ▶ For all  $u \in \Sigma^*$  and  $p_2 \in Q_2$ , let

$$\text{Prod}_2(u, p_2) = \{(v, q_2) \in \Sigma^* \times Q_2 \mid p_2 \xrightarrow{u|v}_{T_2} q_2\}$$

- ▶ The composition  $\llbracket T_2 \rrbracket \circ \llbracket T_1 \rrbracket$  is realised by the transducer  $T = (\Sigma, Q_1 \times Q_2, I_1 \times I_2, F_1 \times F_2, \Delta)$  where:

$$\Delta = \{(p_1, p_2) \xrightarrow{\sigma|v} (q_1, q_2) \mid \exists p_1 \xrightarrow{\sigma|u}_{T_1} q_1 \wedge (v, q_2) \in \text{Prod}_2(u, p_2)\}$$

# Transducer vs Automata



# Transducer vs Automata



- Consider  $r_1, r_2$  two runs on  $a^3$ . We have  $(in(r_1), out(r_1)) = (in(r_2), out(r_2))$  but different in-out words:

$$(a, a)(a, a)(a, \epsilon) \neq (a, \epsilon)(a, a)(a, a)$$

# Transducer vs Automata

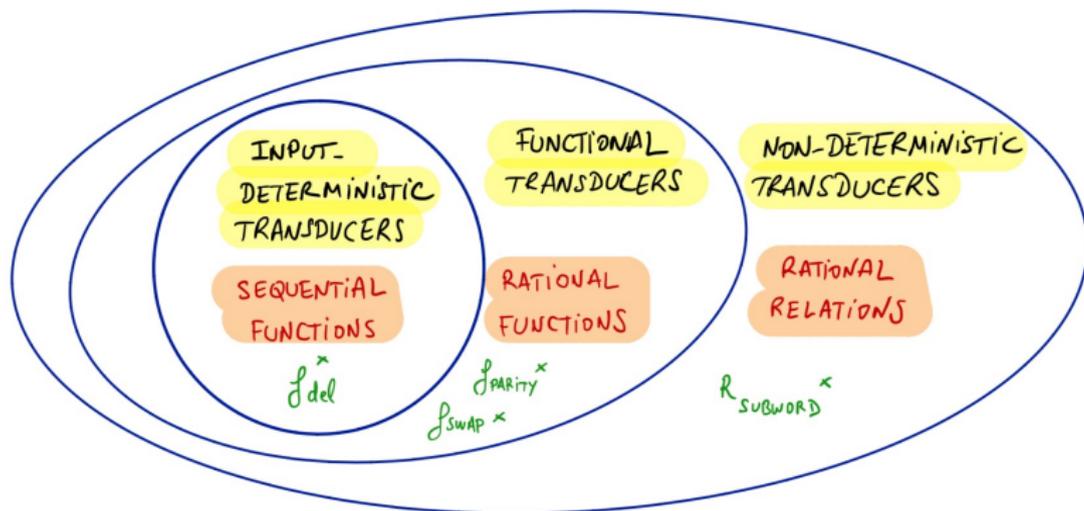


- ▶ Consider  $r_1, r_2$  two runs on  $a^3$ . We have  $(in(r_1), out(r_1)) = (in(r_2), out(r_2))$  but different in-out words:

$$(a, a)(a, a)(a, \epsilon) \neq (a, \epsilon)(a, a)(a, a)$$

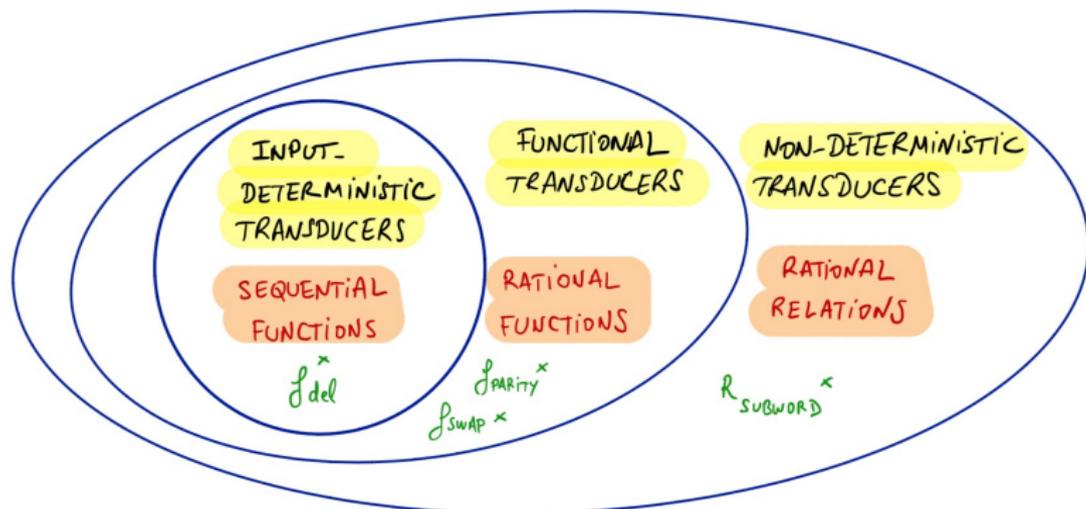
- ▶ Transducers are **asynchronous**
- ▶ Make most transducer problems conceptually difficult (and even computationally).

# Different classes of transductions



$$f_{SWAP} : u\sigma \rightarrow \sigma u \quad \sigma \in \{a, b\}, u \in \{a, b\}^*$$

## Different classes of transductions



Are the classes of sequential and rational functions decidable ?

### Class Membership Problems (for transductions)

Given  $T$  a non-deterministic transducer:

**Functionality** decide if  $\llbracket T \rrbracket$  is a function,

**Determinizability** decide if  $T$  is equivalent to some input-deterministic transducer.

## Some application of the functionality problem

Testing unambiguity of NFA.

## Another Fundamental Problem: Equivalence

**Def** Given two transducers  $T_1, T_2$ , does  $\llbracket T_1 \rrbracket = \llbracket T_2 \rrbracket$  hold?

Case of functional transducers

Equivalence reduces to functionality:

1. test whether  $dom(T_1) = dom(T_2)$
2. test whether  $T_1 \uplus T_2$  is functional.

## Functionality problem: Results

**Lem** (Schützenberger) Non-functionality is witnessed by runs  $r_1, r_2$  such that

- (1)  $r_1, r_2$  are over the same input
- (2)  $r_1, r_2$  produce different outputs
- (3)  $r_1, r_2$  have polynomial length

## Functionality problem: Results

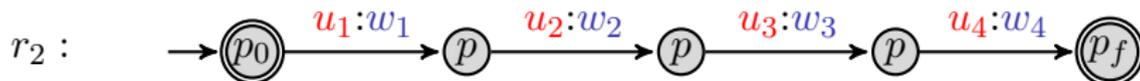
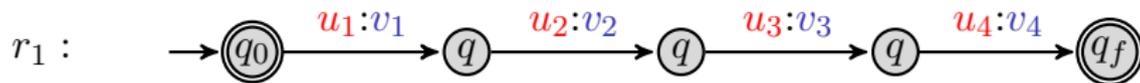
**Lem** (Schützenberger) Non-functionality is witnessed by runs  $r_1, r_2$  such that

- (1)  $r_1, r_2$  are over the same input
- (2)  $r_1, r_2$  produce different outputs
- (3)  $r_1, r_2$  have polynomial length

**Coro** Functionality is decidable in PSPACE.

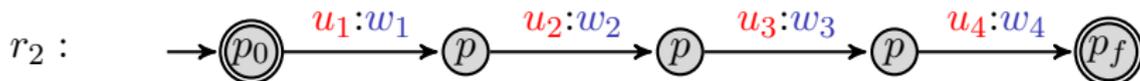
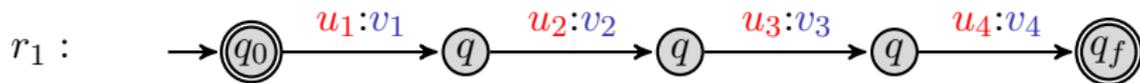
## Proof of the Lemma

Assume  $(u, v), (u, w) \in R$  where  $v \neq w$ , given by runs  $r_1, r_2$  resp. If  $u$  is long enough:



## Proof of the Lemma

Assume  $(u, v), (u, w) \in R$  where  $v \neq w$ , given by runs  $r_1, r_2$  resp. If  $u$  is long enough:



Show  $v_1v_2v_3v_4 \neq w_1w_2w_3w_4 \implies$

$$v_1v_4 \neq w_1w_4 \vee v_1v_2v_4 \neq w_1w_2w_4 \vee v_1v_3v_4 \neq w_1w_3w_4$$

# Proof (Ced)

$$(v_1 v_4 = w_1 w_4 \wedge v_1 v_2 v_4 = w_1 w_2 w_4 \wedge v_1 v_3 v_4 = w_1 w_3 w_4) \implies v_1 v_2 v_3 v_4 = w_1 w_2 w_3 w_4$$

1. Wlog, assume that  $v_1 = \epsilon$ . If not, assume  $v_1$  prefix of  $w_1$ , i.e.  $w_1 = v_1 w'_1$  and eliminate  $v_1$  from all rhs (the case  $w_1$  prefix of  $v_1$  is symmetric). So, we want

$$(v_4 = w_1 w_4 \wedge v_2 v_4 = w_1 w_2 w_4 \wedge v_3 v_4 = w_1 w_3 w_4) \implies v_2 v_3 v_4 = w_1 w_2 w_3 w_4$$

# Proof (Ced)

$$(v_1 v_4 = w_1 w_4 \wedge v_1 v_2 v_4 = w_1 w_2 w_4 \wedge v_1 v_3 v_4 = w_1 w_3 w_4) \implies v_1 v_2 v_3 v_4 = w_1 w_2 w_3 w_4$$

1. Wlog, assume that  $v_1 = \epsilon$ . If not, assume  $v_1$  prefix of  $w_1$ , i.e.  $w_1 = v_1 w'_1$  and eliminate  $v_1$  from all rhs (the case  $w_1$  prefix of  $v_1$  is symmetric). So, we want

$$(v_4 = w_1 w_4 \wedge v_2 v_4 = w_1 w_2 w_4 \wedge v_3 v_4 = w_1 w_3 w_4) \implies v_2 v_3 v_4 = w_1 w_2 w_3 w_4$$

2. In  $v_2 v_4 = w_1 w_2 w_4$ , replace  $v_4$  by  $w_1 w_4$ , then we get  $v_2 w_1 w_4 = w_1 w_2 w_4$ . Similarly, one gets  $v_3 w_1 w_4 = w_1 w_3 w_4$ . Simplify by  $w_4$  and we get:

$$v_2 w_1 = w_1 w_2 \quad (1) \quad v_3 w_1 = w_1 w_3 \quad (2)$$

# Proof (Ced)

$$(v_1 v_4 = w_1 w_4 \wedge v_1 v_2 v_4 = w_1 w_2 w_4 \wedge v_1 v_3 v_4 = w_1 w_3 w_4) \implies v_1 v_2 v_3 v_4 = w_1 w_2 w_3 w_4$$

1. Wlog, assume that  $v_1 = \epsilon$ . If not, assume  $v_1$  prefix of  $w_1$ , i.e.  $w_1 = v_1 w'_1$  and eliminate  $v_1$  from all rhs (the case  $w_1$  prefix of  $v_1$  is symmetric). So, we want

$$(v_4 = w_1 w_4 \wedge v_2 v_4 = w_1 w_2 w_4 \wedge v_3 v_4 = w_1 w_3 w_4) \implies v_2 v_3 v_4 = w_1 w_2 w_3 w_4$$

2. In  $v_2 v_4 = w_1 w_2 w_4$ , replace  $v_4$  by  $w_1 w_4$ , then we get  $v_2 w_1 w_4 = w_1 w_2 w_4$ . Similarly, one gets  $v_3 w_1 w_4 = w_1 w_3 w_4$ . Simplify by  $w_4$  and we get:

$$v_2 w_1 = w_1 w_2 \quad (1) \quad v_3 w_1 = w_1 w_3 \quad (2)$$

3. Finally:

$$\begin{aligned} v_2 v_3 v_4 &= v_2 v_3 w_1 w_4 && \text{by } v_4 = w_1 w_4 \\ &= v_2 w_1 w_3 w_4 && \text{by (2)} \\ &= w_1 w_2 w_3 w_4 && \text{by (1)} \end{aligned}$$



# Functionality Problem in PTIME

**Thm (Gurari,Ibarra,83).** Functionality is decidable in PTIME.

- ▶ reversal-bounded counter machines
- ▶ emptiness in PTIME if fixed number of counters
- ▶ later shown with a direct proof by  
Carton,Beal,Prieur,Sakarovitch (Squaring Transducers)

# Squaring Transducers Carton, Beal, Prieur, Sakarovitch, 01

## Some Definitions

Given a transducer  $T = (\Sigma, Q, I, F, \Delta)$ ,

- ▶  $q \in Q$  is co-accessible by  $u$  if  $q \xrightarrow{u|v} q_f \in F$  for some  $v$
- ▶  $\text{CoAcc} = \{(p, q) \in Q^2 \mid p, q \text{ co-accessible by some } u\}$

# Squaring Transducers Carton, Beal, Prieur, Sakarovitch, 01

## Some Definitions

Given a transducer  $T = (\Sigma, Q, I, F, \Delta)$ ,

- ▶  $q \in Q$  is co-accessible by  $u$  if  $q \xrightarrow{u|v} q_f \in F$  for some  $v$
- ▶  $\text{CoAcc} = \{(p, q) \in Q^2 \mid p, q \text{ co-accessible by some } u\}$
- ▶ Let  $u, v \in \Sigma^*$ ,  $u \wedge v$  is the longest common prefix of  $u$  and  $v$

# Squaring Transducers Carton, Beal, Prieur, Sakarovitch,

## 01

### Some Definitions

Given a transducer  $T = (\Sigma, Q, I, F, \Delta)$ ,

- ▶  $q \in Q$  is co-accessible by  $u$  if  $q \xrightarrow{u|v} q_f \in F$  for some  $v$
- ▶  $\text{CoAcc} = \{(p, q) \in Q^2 \mid p, q \text{ co-accessible by some } u\}$
- ▶ Let  $u, v \in \Sigma^*$ ,  $u \wedge v$  is the longest common prefix of  $u$  and  $v$
- ▶  $\text{delay}(u, v) = (u', v')$  where  $u = (u \wedge v)u'$  and  $v = (u \wedge v)v'$

# Squaring Transducers Carton, Beal, Prieur, Sakarovitch, 01

## Some Definitions

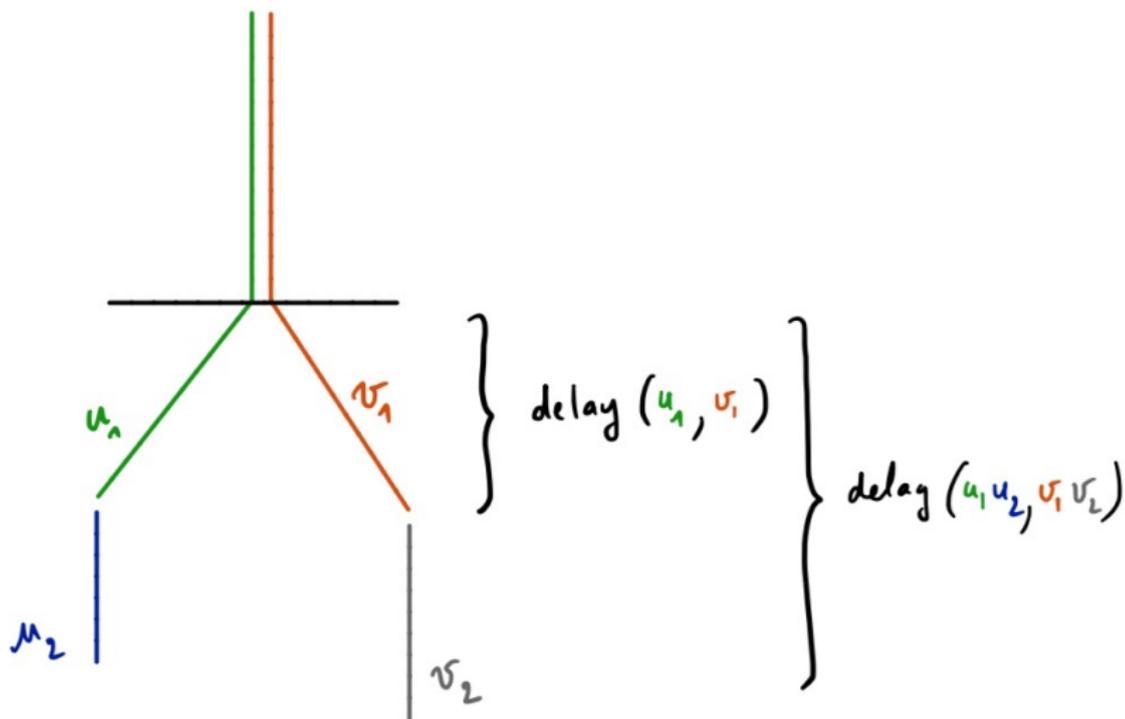
Given a transducer  $T = (\Sigma, Q, I, F, \Delta)$ ,

- ▶  $q \in Q$  is co-accessible by  $u$  if  $q \xrightarrow{u|v} q_f \in F$  for some  $v$
- ▶  $\text{CoAcc} = \{(p, q) \in Q^2 \mid p, q \text{ co-accessible by some } u\}$
- ▶ Let  $u, v \in \Sigma^*$ ,  $u \wedge v$  is the longest common prefix of  $u$  and  $v$
- ▶  $\text{delay}(u, v) = (u', v')$  where  $u = (u \wedge v)u'$  and  $v = (u \wedge v)v'$

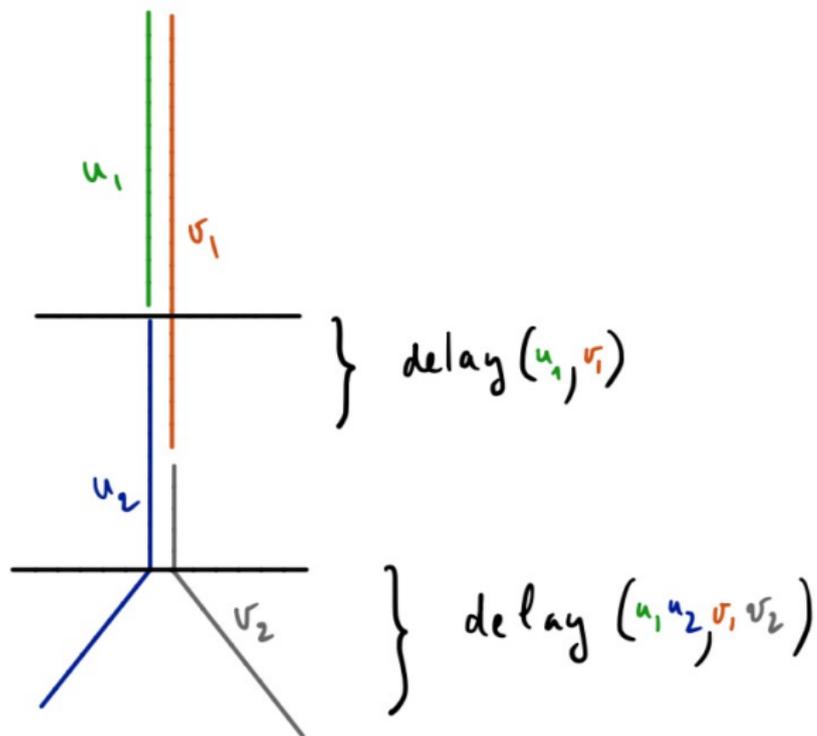
Lemma (The delay is compositional)

$$\text{delay}(u_1 u_2, v_1 v_2) = \text{delay}(\text{delay}(u_1, u_2). (v_1, v_2)).$$

# The Delay is Compositional (“Proof”)



# The Delay is Compositional (“Proof”)



# Squaring Transducers

## State delays

$$\text{delays}(p, q) = \{\text{delay}(v, w) \mid \exists u \in \Sigma^* \exists p_0 \xrightarrow{u|v} p \exists q_0 \xrightarrow{u|w} q\}$$

# Squaring Transducers

## State delays

$$\text{delays}(p, q) = \{\text{delay}(v, w) \mid \exists u \in \Sigma^* \exists p_0 \xrightarrow{u|v} p \exists q_0 \xrightarrow{u|w} q\}$$

## First observation

$T$  is functional iff for all states  $(p_f, q_f) \in F^2 \cap \text{Acc}$ ,

$$\text{delays}(p_f, q_f) = \{(\epsilon, \epsilon)\}$$

# Squaring Transducers

## State delays

$$\text{delays}(p, q) = \{\text{delay}(v, w) \mid \exists u \in \Sigma^* \exists p_0 \xrightarrow{u|v} p \exists q_0 \xrightarrow{u|w} q\}$$

## First observation

$T$  is functional iff for all states  $(p_f, q_f) \in F^2 \cap \text{Acc}$ ,

$$\text{delays}(p_f, q_f) = \{(\epsilon, \epsilon)\}$$

## Second observation

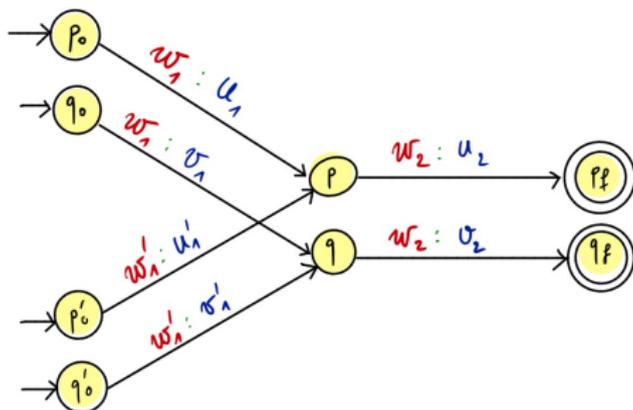
Let  $(p, q) \in \text{CoAcc}$ . If  $|\text{delays}(p, q)| > 1$  then  $T$  is not functional.

# Proof of the Second Observation

## Second observation

Let  $(p, q) \in \text{CoAcc}$ . If  $|\text{delays}(p, q)| > 1$  then  $T$  is not functional.

# Proof of the second observation



Assume

$$\begin{aligned}
 (\alpha_1, \beta_1) &:= \text{delay}(u_1, v_1) \\
 &\neq \\
 (\alpha'_1, \beta'_1) &:= \text{delay}(u'_1, v'_1).
 \end{aligned}$$

By contradiction, assume that  $u_1 u_2 = v_1 v_2$  and  $u'_1 u_2 = v'_1 v_2$ . Then  $\alpha_1 u_2 = \beta_1 v_2$  and  $\alpha'_1 u_2 = \beta'_1 v_2$ . As  $(\alpha_1, \beta_1)$  and  $(\alpha'_1, \beta'_1)$  are delays, the following cases may arise:

1.  $\alpha_1$  and  $\beta_1$  start with distinct letters. Impossible.
2.  $\alpha'_1$  and  $\beta'_1$  start with distinct letters. Impossible.
3.  $\alpha_1 = \alpha'_1 = \epsilon$ : then  $u_2 = \beta_1 v_2 = \beta'_1 v_2$ , hence  $\beta_1 = \beta'_1$ , impossible.
4.  $\alpha_1 = \beta'_1 = \epsilon$ , then  $u_2 = \beta_1 v_2$  and  $v_2 = \alpha'_1 u_2$ . Then  $u_2 = \beta_1 \alpha'_1 u_2$ , hence  $\beta_1 = \alpha_1 = \alpha'_1 = \beta'_1 = \epsilon$ , impossible.
5. cases  $\beta_1 = \beta'_1 = \epsilon$  and  $\beta_1 = \alpha'_1 = \epsilon$  are symmetrical.

## Squaring Transducers: Algorithm for functionality

1. compute CoAcc (quadratic time)
2. Visited =  $\{(p_0, q_0, (\epsilon, \epsilon)) \mid (p_0, q_0) \in \text{CoAcc} \cap I^2\}$
3. Waiting = Visited
4. **While** (Waiting  $\neq \emptyset$ )
  5. Remove some  $(p, q, d) \in \text{Waiting}$
  6. **For all**  $p \xrightarrow{\sigma:v} p', q \xrightarrow{\sigma:w} q'$  s.t.  $(p', q') \in \text{CoAcc}$  **do:**
    7.  $d' = \text{delay}(d.(v, w))$
    8. **if**  $(p', q', d') \notin \text{Visited}$ :
      9. **if**  $\exists (p', q', d'') \in \text{Visited}$  s.t.  $d' \neq d''$  **return** NO
      10. **if**  $(p', q') \in F^2$  and  $d' \neq (\epsilon, \epsilon)$  **return** NO
      11. add  $(p', q', d')$  to Waiting and to Visited
  12. **return** YES

# Invariant

## Lemma

*For all  $(p, q, d) \in Visited$ , there exist  $p_0, q_0 \in I$ ,  $u, v, w \in \Sigma^*$  such that:*

1.  $p_0 \xrightarrow{u:v} p$
2.  $q_0 \xrightarrow{u:w} q$
3.  $d = \text{delay}(v, w)$
4.  $(p, q) \in CoAcc$

## Correctness of the algorithm

1. if it returns NO, then by the Invariant and the two observations,  $T$  is not functional

## Correctness of the algorithm

1. if it returns NO, then by the Invariant and the two observations,  $T$  is not functional
2. conversely, if it returns YES, then we show that in the end, we have  $(\star)$

$$\text{Visited} \supseteq \{(p, q, \text{delay}(v, w)) \mid \exists p_0 \xrightarrow{u:v} p, q_0 \xrightarrow{u:w} q, (p, q) \in \text{CoAcc}\}$$

and in particular, Visited contains all such  $(p, q, \text{delay}(v, w))$  such that  $(p, q) \in F^2 \cap \text{Acc}$ .

## Correctness of the algorithm

1. if it returns NO, then by the Invariant and the two observations,  $T$  is not functional
2. conversely, if it returns YES, then we show that in the end, we have  $(\star)$

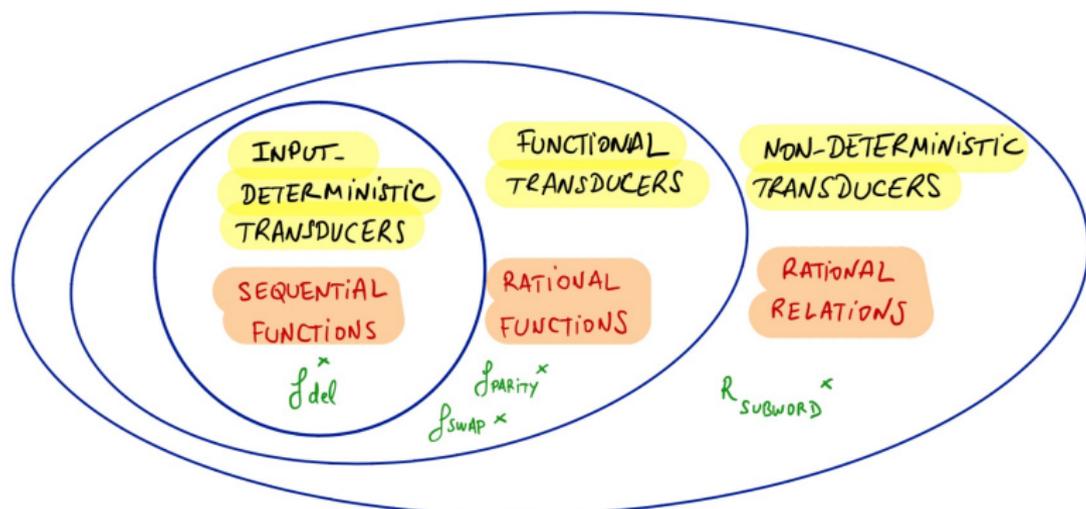
$$\text{Visited} \supseteq \{(p, q, \text{delay}(v, w)) \mid \exists p_0 \xrightarrow{u:v} p, q_0 \xrightarrow{u:w} q, (p, q) \in \text{CoAcc}\}$$

and in particular, Visited contains all such  $(p, q, \text{delay}(v, w))$  such that  $(p, q) \in F^2 \cap \text{Acc}$ .

If  $T$  is not functional, by Obs1 there exists  $(p, q, d)$  such that  $(p, q) \in F^2 \cap \text{Acc}$  and  $d \neq (\epsilon, \epsilon)$ , hence the the test at line 10 eventually fails. Contradiction.

To show  $\star$ , use induction on  $|u|$  and delay compositionality.

## Summary of yesterday's talk



Given  $T$  a non-deterministic transducer:

**Functionality** decide if  $\llbracket T \rrbracket$  is a function,

**Determinizability** decide if  $T$  is equivalent to some input-deterministic transducer.

→ We have seen that Functionality can be decided in PTime.

# Equivalence Problem: Results

For functional transducers  $T_1, T_2$

- ▶ PSPACE-C (hardness by automata equivalence)
- ▶ PTIME if  $dom(T_1) = dom(T_2)$  is known.

---

<sup>1</sup> $\exists K \forall u |T(u)| \leq K$

## Equivalence Problem: Results

For functional transducers  $T_1, T_2$

- ▶ PSPACE-C (hardness by automata equivalence)
- ▶ PTIME if  $\text{dom}(T_1) = \text{dom}(T_2)$  is known.

In general

- ▶ Undecidable (Griffith 68), even if one alphabet is unary (Ibarra 78)

---

<sup>1</sup> $\exists K \forall u |T(u)| \leq K$

## Equivalence Problem: Results

For functional transducers  $T_1, T_2$

- ▶ PSPACE-C (hardness by automata equivalence)
- ▶ PTIME if  $\text{dom}(T_1) = \text{dom}(T_2)$  is known.

In general

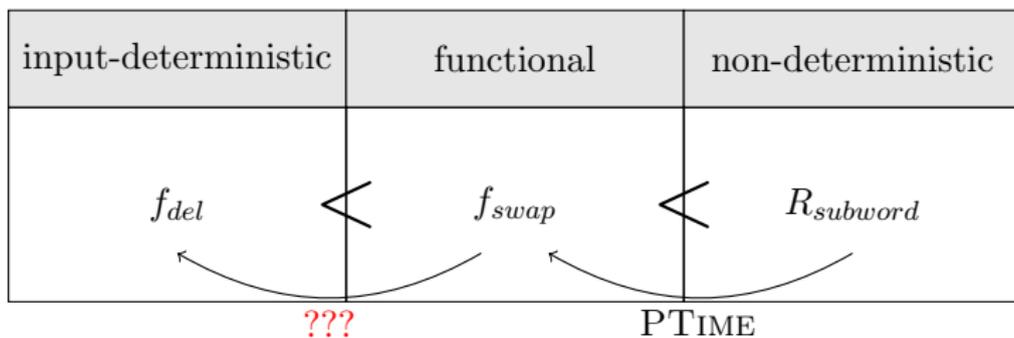
- ▶ Undecidable (Griffith 68), even if one alphabet is unary (Ibarra 78)
- ▶ Decidable for finite-valued transducers (Culik Karhumäki 86)<sup>1</sup>.

---

<sup>1</sup> $\exists K \forall u |T(u)| \leq K$

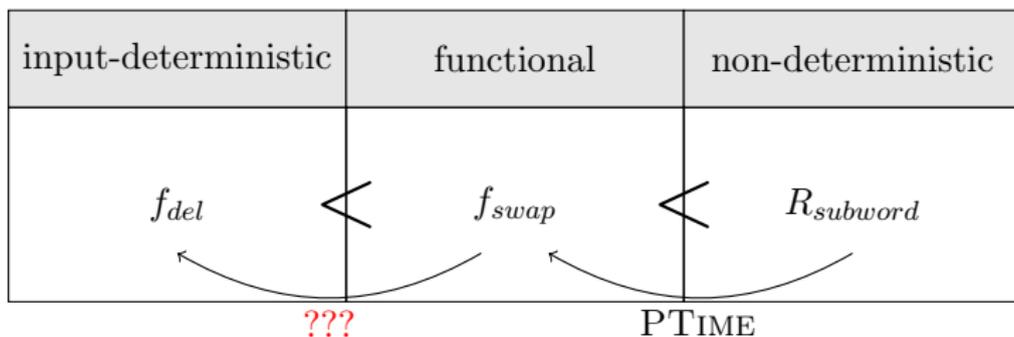
# Summary – Transducers

Expressiveness:



# Summary – Transducers

Expressiveness:



Equivalence: ( $dom(T_1) = dom(T_2)$  is known)

input-deterministic	functional	non-deterministic
P	P	undec
TIME	TIME	

# Determinizability

**Def** Given a transducer  $T$ , does there exist an input-deterministic transducer  $T'$  such that  $\llbracket T \rrbracket = \llbracket T' \rrbracket$ ?

Remark: we now assume that  $T$  is:

- ▶ functional (otherwise the answer is NO)
- ▶ trim (can be achieved in PTime)

# Determinizability

**Def** Given a transducer  $T$ , does there exist an input-deterministic transducer  $T'$  such that  $\llbracket T \rrbracket = \llbracket T' \rrbracket$ ?

Remark: we now assume that  $T$  is:

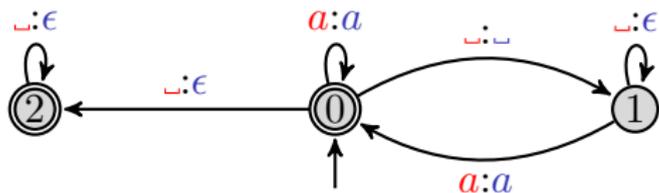
- ▶ functional (otherwise the answer is NO)
- ▶ trim (can be achieved in PTime)

**Thm** (Choffrut77, Weber,Klemm,95). Determinizability is decidable in PTIME.

- ▶ equivalent input-deterministic transducer of exp. size
- ▶ characterization based on a pattern of the transducer (twinning property) due to (Choffrut77)
- ▶ PTIME membership due to (Weber,Klemm,95)

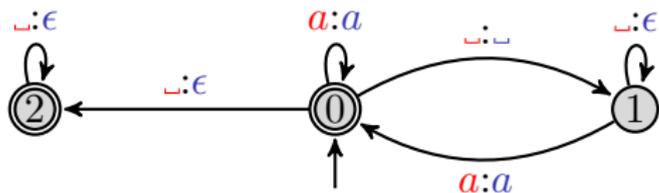
# Determinizability: example

␣ = white space



# Determinizability: example

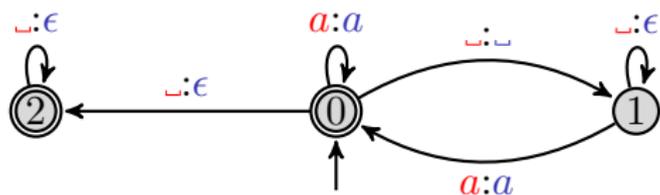
␣ = white space



$\text{␣}aa\text{␣}aa\text{␣} \mapsto \text{␣}aaa\text{␣}$

# Determinizability: example

␣ = white space

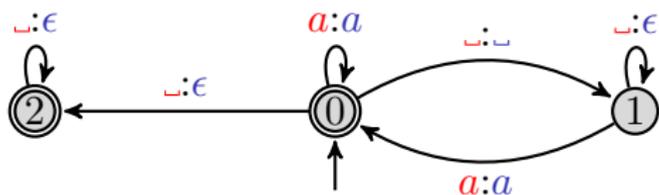


$\text{␣}aa\text{␣}aa\text{␣} \mapsto \text{␣}aa\text{␣}a$

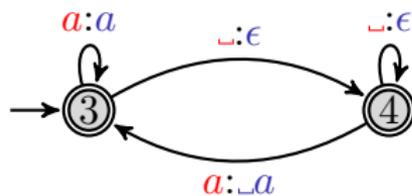
Is non-determinism needed ?

# Determinizability: example

$\_$  = white space

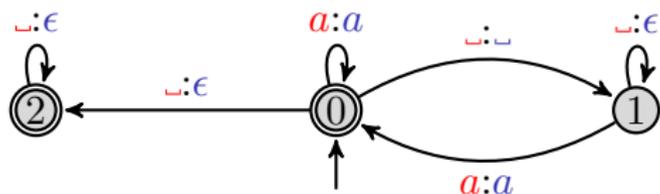


$\_aa\_aa\_ \mapsto \_aa\_a$



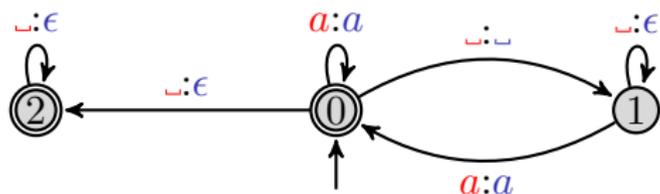
Is non-determinism needed? No.

## How to get a deterministic FT ?

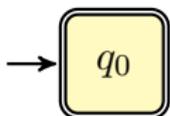


- ▶ extend automata subset construction with outputs
- ▶ output the longest common prefix

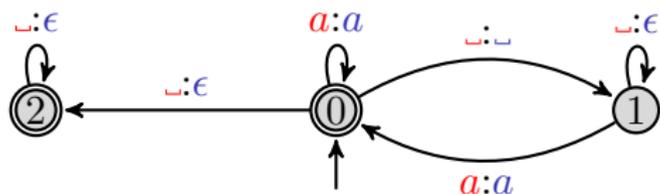
## How to get a deterministic FT ?



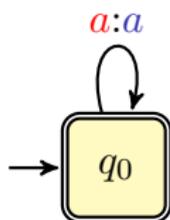
- ▶ extend automata subset construction with outputs
- ▶ output the longest common prefix



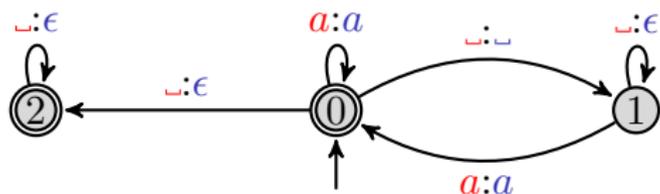
## How to get a deterministic FT ?



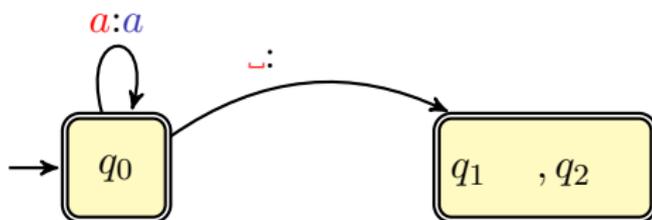
- ▶ extend automata subset construction with outputs
- ▶ output the longest common prefix



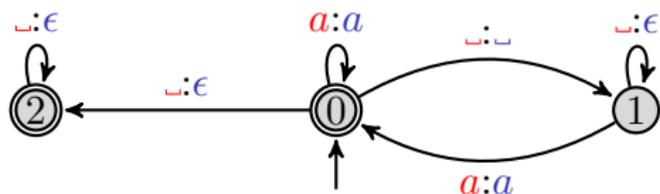
## How to get a deterministic FT ?



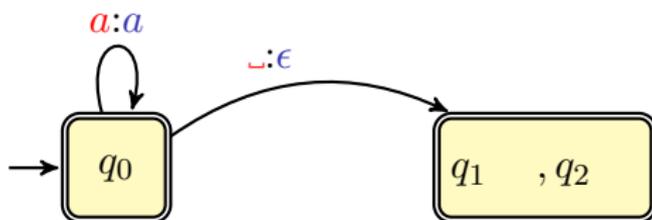
- ▶ extend automata subset construction with outputs
- ▶ output the longest common prefix



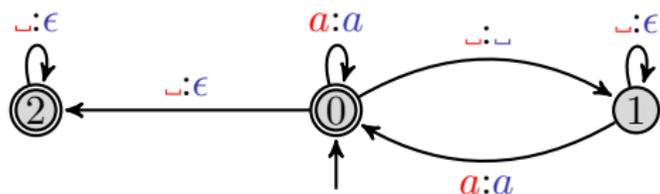
## How to get a deterministic FT ?



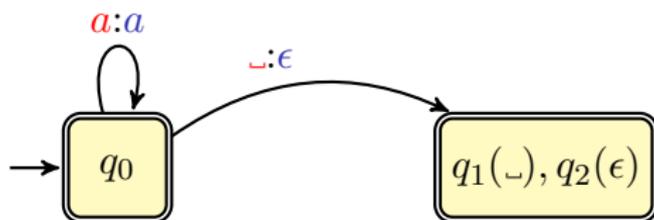
- ▶ extend automata subset construction with outputs
- ▶ output the longest common prefix



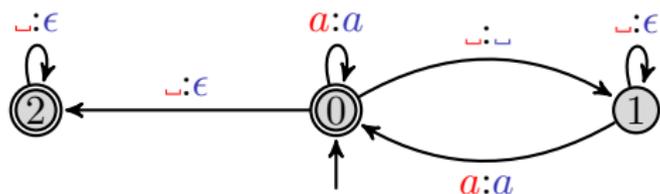
## How to get a deterministic FT ?



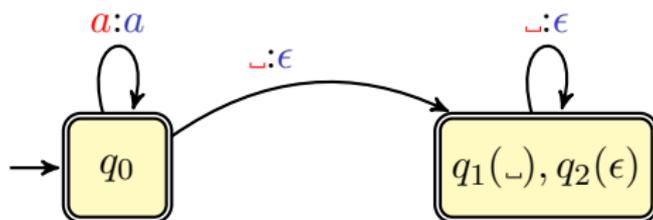
- ▶ extend automata subset construction with outputs
- ▶ output the longest common prefix



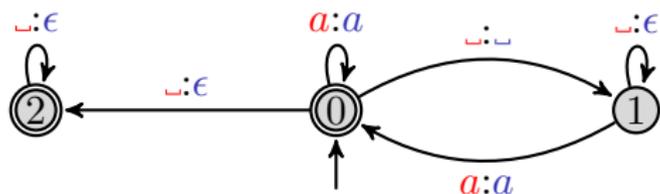
## How to get a deterministic FT ?



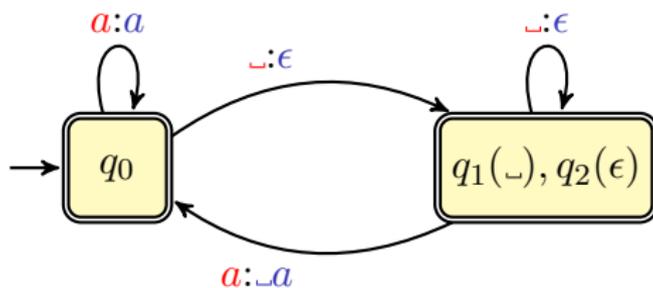
- ▶ extend automata subset construction with outputs
- ▶ output the longest common prefix



## How to get a deterministic FT ?



- ▶ extend automata subset construction with outputs
- ▶ output the longest common prefix



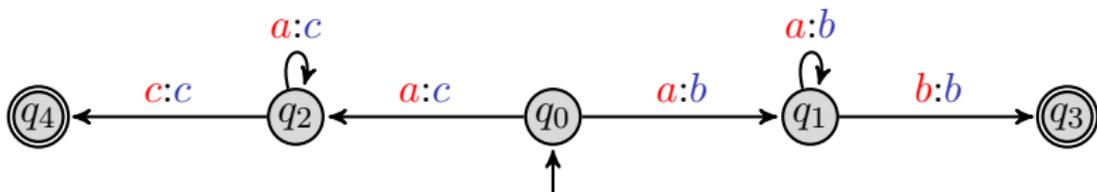
Can we always get an equivalent deterministic FT ?

## Can we always get an equivalent deterministic FT ?

- ▶ not in general: input-deterministic transducers are less expressive than functional ones

# Can we always get an equivalent deterministic FT ?

- ▶ not in general: input-deterministic transducers are less expressive than functional ones

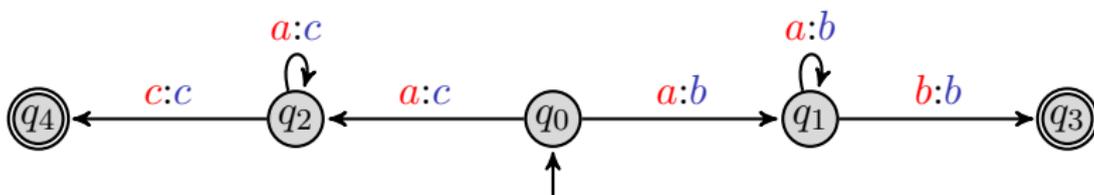


## Semantics

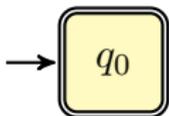
$$\llbracket T \rrbracket : \begin{cases} a^n b \mapsto b^{n+1} \\ a^n c \mapsto c^{n+1} \end{cases}$$

functional but not determinizable

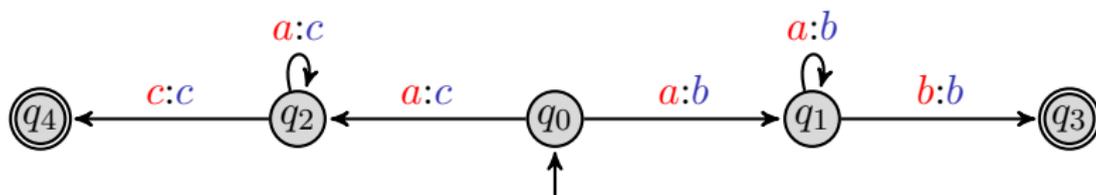
## Subset construction fails ...



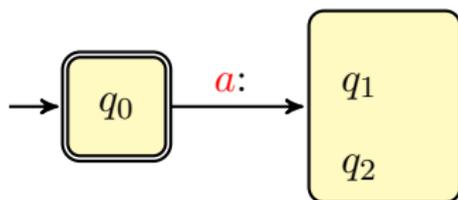
**Subset construction:**



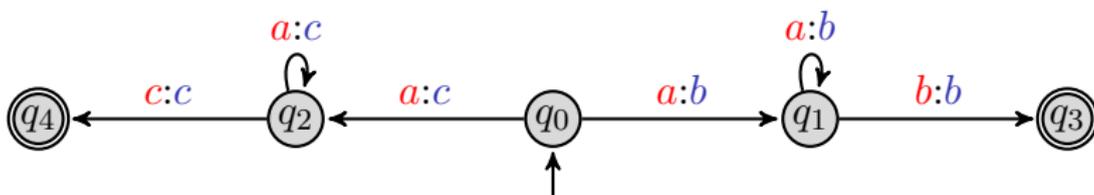
# Subset construction fails ...



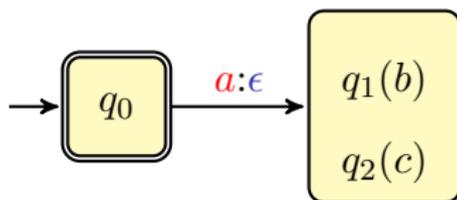
## Subset construction:



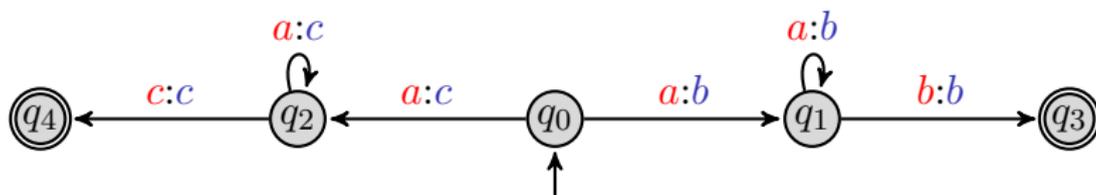
# Subset construction fails ...



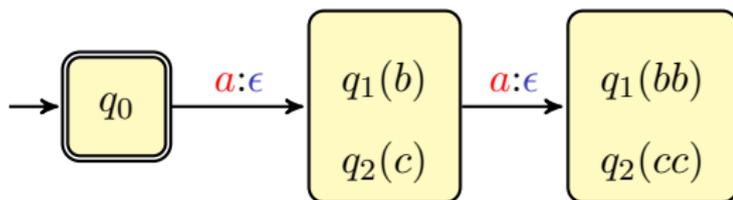
## Subset construction:



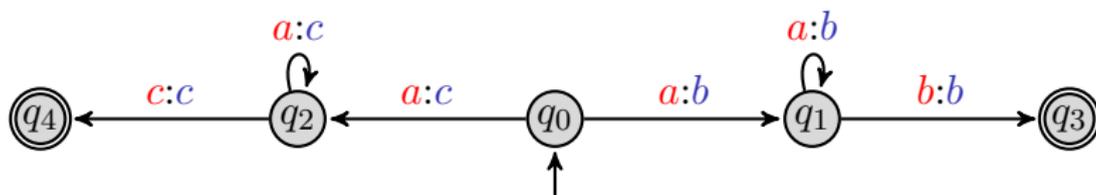
# Subset construction fails ...



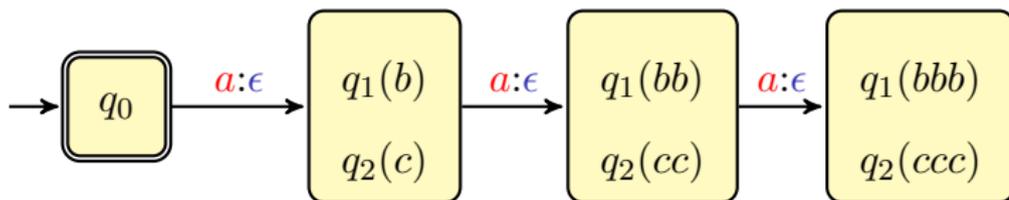
## Subset construction:



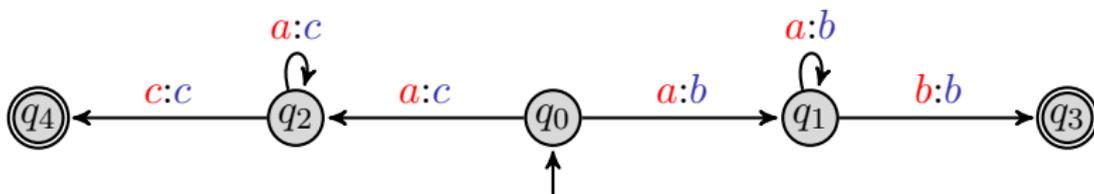
# Subset construction fails ...



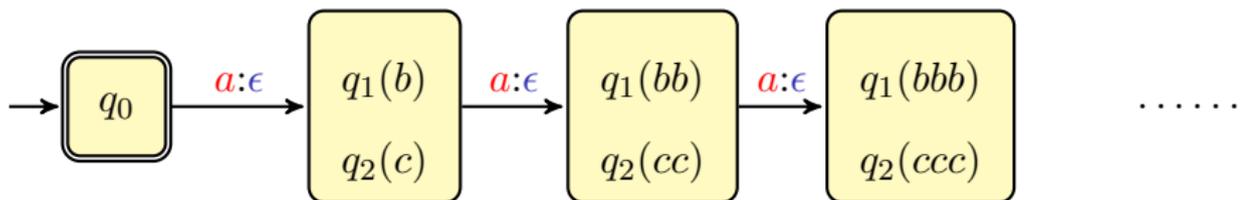
## Subset construction:



# Subset construction fails ...



## Subset construction:



## How to guarantee termination of subset construction?

Reminder:

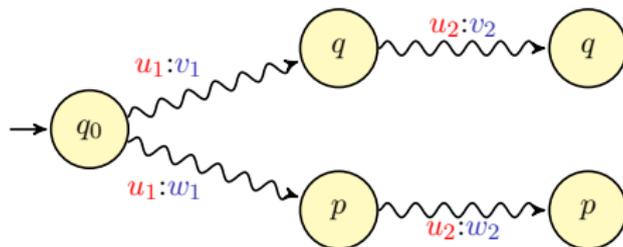
$\text{delay}(u, v) = (u', v')$  such that  $u = \ell u'$ ,  $v = \ell v'$  and  $\ell = u \wedge v$ .

# How to guarantee termination of subset construction?

Reminder:

$\text{delay}(u, v) = (u', v')$  such that  $u = \ell u'$ ,  $v = \ell v'$  and  $\ell = u \wedge v$ .

We say that  $T$  satisfies the Twinning Property iff for all situations



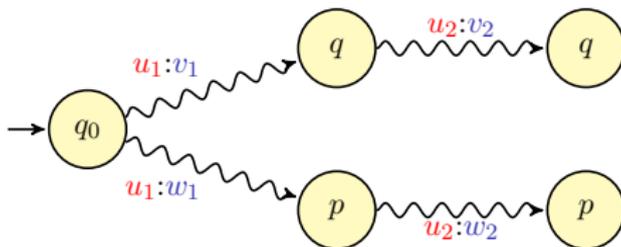
it is the case that  $\text{delay}(v_1, w_1) = \text{delay}(v_1v_2, w_1w_2)$ .

# How to guarantee termination of subset construction?

Reminder:

$\text{delay}(u, v) = (u', v')$  such that  $u = \ell u'$ ,  $v = \ell v'$  and  $\ell = u \wedge v$ .

We say that  $T$  satisfies the Twinning Property iff for all situations



it is the case that  $\text{delay}(v_1, w_1) = \text{delay}(v_1 v_2, w_1 w_2)$ .

**Lemma**[Characterization]  $T$  is determinizable iff it satisfies the Twinning Property.

## Proof of the characterization ( $T \models \text{TP} \Rightarrow T \text{ det.}$ )

( $n$ : number of states,  $M$ : maximal length of output word)

**Lemma** If  $T$  satisfies the Twinning Property, then for all runs  $p_0 \xrightarrow{u:v} p$  and  $q_0 \xrightarrow{u:w} q$ , we have  $|\text{delay}(v, w)| \leq 2n^2M$ .

## Proof of the characterization ( $T \models \text{TP} \Rightarrow T \text{ det.}$ )

( $n$ : number of states,  $M$ : maximal length of output word)

**Lemma** If  $T$  satisfies the Twinning Property, then for all runs  $p_0 \xrightarrow{u:v} p$  and  $q_0 \xrightarrow{u:w} q$ , we have  $|\text{delay}(v, w)| \leq 2n^2M$ .

**Proof:** We proceed by contradiction, and consider a counter-example of minimal length, with input word  $u$ . Two cases:

- ▶ If  $|u| \leq n^2$ , then  $|\text{delay}(v, w)| \leq |v| + |w| \leq 2n^2M$ .
- ▶ If  $|u| > n^2$ , then there is a loop. By the twinning property, and the compositionality of  $\text{delay}$ , we obtain a shorter counter-example. Contradiction. □

## Proof of the characterization ( $T \models \text{TP} \Rightarrow T \text{ det.}$ )

( $n$ : number of states,  $M$ : maximal length of output word)

**Lemma** If  $T$  satisfies the Twinning Property, then for all runs  $p_0 \xrightarrow{u:v} p$  and  $q_0 \xrightarrow{u:w} q$ , we have  $|\text{delay}(v, w)| \leq 2n^2M$ .

**Proof:** We proceed by contradiction, and consider a counter-example of minimal length, with input word  $u$ . Two cases:

- ▶ If  $|u| \leq n^2$ , then  $|\text{delay}(v, w)| \leq |v| + |w| \leq 2n^2M$ .
- ▶ If  $|u| > n^2$ , then there is a loop. By the twinning property, and the compositionality of  $\text{delay}$ , we obtain a shorter counter-example. Contradiction. □

We have:  $T \models \text{Twinning Property} \Rightarrow \text{Subset constr. terminates}$   
 $\Rightarrow T \text{ determinizable}$

## Proof of the characterization ( $T \text{ det.} \Rightarrow T \models \text{TP}$ )

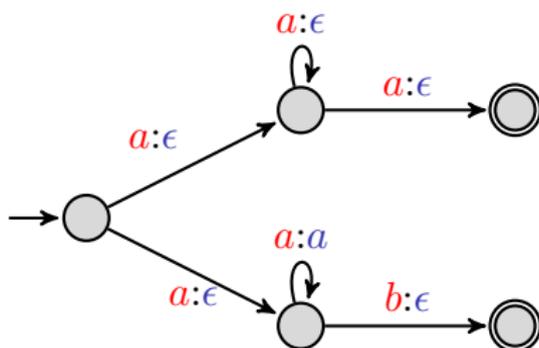
We only give some intuition.

# Proof of the characterization ( $T \text{ det.} \Rightarrow T \models \text{TP}$ )

We only give some intuition.

By contraposition, suppose that  $T \not\models$  Twinning Property.

For instance:

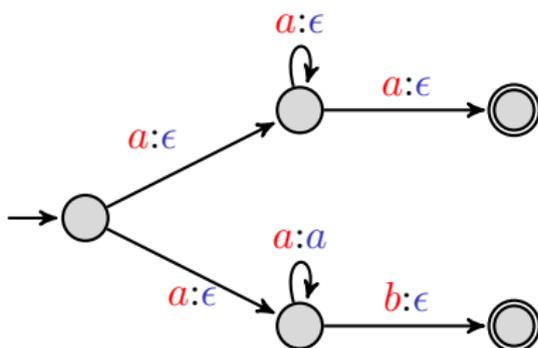


## Proof of the characterization ( $T \text{ det.} \Rightarrow T \models \text{TP}$ )

We only give some intuition.

By contraposition, suppose that  $T \not\models$  Twinning Property.

For instance:



Iterating the loop yields an infinite number of distinct delays.

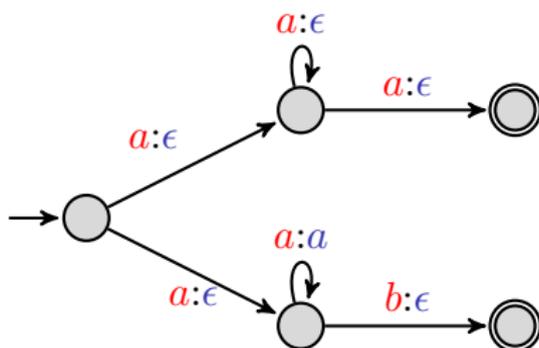
$(\epsilon, a), (\epsilon, aa), (\epsilon, aaa) \dots$

## Proof of the characterization ( $T \text{ det.} \Rightarrow T \models \text{TP}$ )

We only give some intuition.

By contraposition, suppose that  $T \not\models$  Twinning Property.

For instance:



Iterating the loop yields an infinite number of distinct delays.

$(\epsilon, a), (\epsilon, aa), (\epsilon, aaa) \dots$

Any equivalent input-deterministic transducer should store them, impossible with finitely many states.

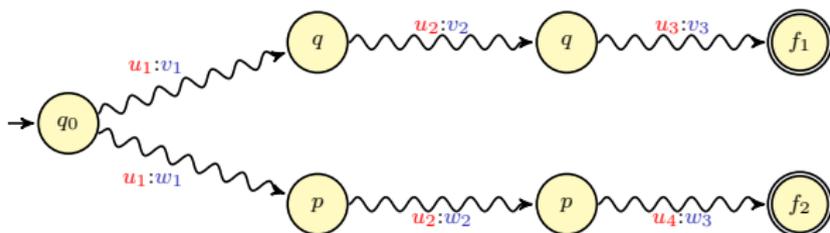
## Proof of the characterization ( $T$ det. $\Rightarrow T \models \text{TP}$ )

We prove now  $T$  determinizable  $\Rightarrow T \models \text{Twinning Property}$ .

# Proof of the characterization ( $T \text{ det.} \Rightarrow T \models \text{TP}$ )

We prove now  $T$  determinizable  $\Rightarrow T \models$  Twinning Property.

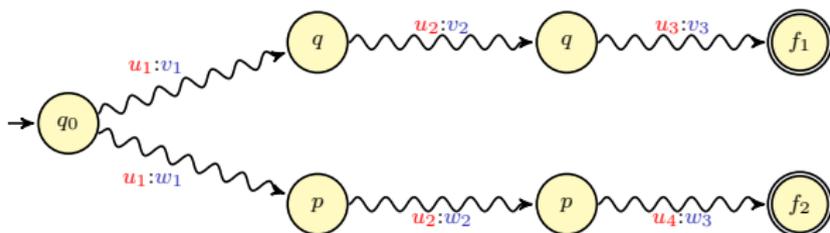
Consider an input-deterministic transducer  $D$  s.t.  $\llbracket T \rrbracket = \llbracket D \rrbracket$  and an instance of the Twinning Property:



# Proof of the characterization ( $T \text{ det.} \Rightarrow T \models \text{TP}$ )

We prove now  $T$  determinizable  $\Rightarrow T \models$  Twinning Property.

Consider an input-deterministic transducer  $D$  s.t.  $\llbracket T \rrbracket = \llbracket D \rrbracket$  and an instance of the Twinning Property:

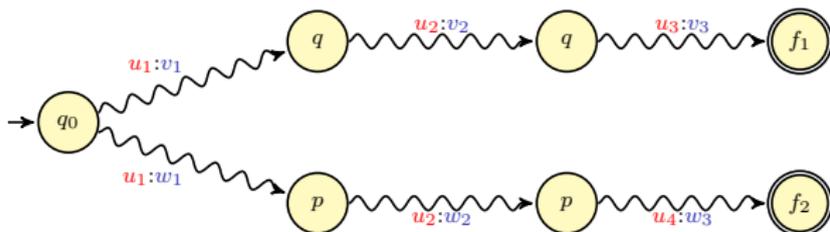


$\forall i, u_1 u_2^i u_3 \in \text{dom}(\llbracket T \rrbracket) \Rightarrow \exists i \geq 1, j \geq 0 \mid$  there is a loop in  $D$  on  $u_2^i$  after  $u_1 u_2^j$

# Proof of the characterization ( $T \text{ det.} \Rightarrow T \models \text{TP}$ )

We prove now  $T$  determinizable  $\Rightarrow T \models$  Twinning Property.

Consider an input-deterministic transducer  $D$  s.t.  $\llbracket T \rrbracket = \llbracket D \rrbracket$  and an instance of the Twinning Property:



$\forall i, u_1 u_2^i u_3 \in \text{dom}(\llbracket T \rrbracket) \Rightarrow \exists i \geq 1, j \geq 0 \mid$  there is a loop in  $D$  on  $u_2^i$  after  $u_1 u_2^j$

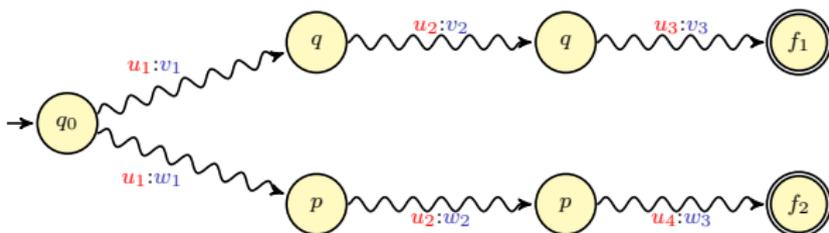
We obtain : (for some output words  $x_1, x_2, x_3, y_3$  in  $D$ )

$$\begin{aligned} \forall \ell \geq 0, \quad \llbracket T \rrbracket(u_1 u_2^j u_2^{\ell i} u_3) &= v_1 v_2^j v_2^{\ell i} v_3 &= x_1 x_2^\ell x_3 \\ \llbracket T \rrbracket(u_1 u_2^j u_2^{\ell i} u_4) &= w_1 w_2^j w_2^{\ell i} w_3 &= x_1 x_2^\ell y_3 \end{aligned}$$

# Proof of the characterization ( $T \text{ det.} \Rightarrow T \models \text{TP}$ )

We prove now  $T$  determinizable  $\Rightarrow T \models$  Twinning Property.

Consider an input-deterministic transducer  $D$  s.t.  $\llbracket T \rrbracket = \llbracket D \rrbracket$  and an instance of the Twinning Property:



$\forall i, u_1 u_2^i u_3 \in \text{dom}(\llbracket T \rrbracket) \Rightarrow \exists i \geq 1, j \geq 0 \mid$  there is a loop in  $D$  on  $u_2^i$  after  $u_1 u_2^j$

We obtain : (for some output words  $x_1, x_2, x_3, y_3$  in  $D$ )

$$\begin{aligned} \forall \ell \geq 0, \quad \llbracket T \rrbracket(u_1 u_2^j u_2^{\ell i} u_3) &= v_1 v_2^j v_2^{\ell i} v_3 &= x_1 x_2^\ell x_3 \\ \llbracket T \rrbracket(u_1 u_2^j u_2^{\ell i} u_4) &= w_1 w_2^j w_2^{\ell i} w_3 &= x_1 x_2^\ell y_3 \end{aligned}$$

Thus  $v_1 v_2^\omega = x_1 x_2^\omega = w_1 w_2^\omega$  and  $|v_2| = |w_2|$ .

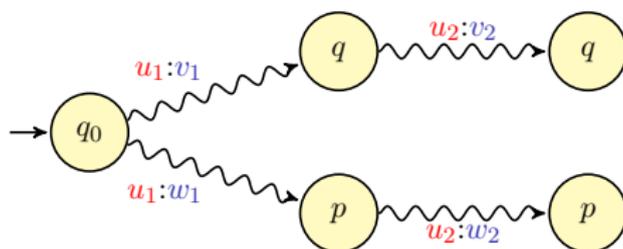
This entails  $\text{delay}(v_1, w_1) = \text{delay}(v_1 v_2, w_1 w_2)$ .

□

## Decidability of determinizability

**Lemma**[Characterization]  $T$  is determinizable iff it satisfies the Twinning Property.

For all situations

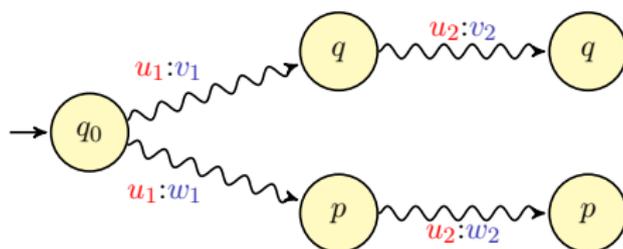


it is the case that  $\text{delay}(v_1, w_1) = \text{delay}(v_1v_2, w_1w_2)$ .

## Decidability of determinizability

**Lemma**[Characterization]  $T$  is determinizable iff it satisfies the Twinning Property.

For all situations



it is the case that  $\text{delay}(v_1, w_1) = \text{delay}(v_1v_2, w_1w_2)$ .

**Claim:**  $T$  violates the TP iff there exists situation as above such that:

1.  $|v_2| \neq |w_2|$ , or
2.  $|v_2| = |w_2| \neq 0$  and there is a mismatch between  $v_1$  and  $w_1$

## Decidability of determinizability (2)

$T$  violates the TP iff there exists situation as above such that:

1.  $|v_2| \neq |w_2|$ , or
2.  $|v_2| = |w_2| \neq 0$  and there is a mismatch between  $v_1$  and  $w_1$

## Decidability of determinizability (2)

$T$  violates the TP iff there exists situation as above such that:

1.  $|v_2| \neq |w_2|$ , or
2.  $|v_2| = |w_2| \neq 0$  and there is a mismatch between  $v_1$  and  $w_1$

To decide 1.:

consider a weighted graph with vertices  $(p, q)$  such that  $(p, q) \xrightarrow{n} (p', q')$  iff  $\exists \sigma$ ,  
 $p \xrightarrow{\sigma:v} p'$ ,  $q \xrightarrow{\sigma:w} q'$  and  $n = |v| - |w|$

$\rightsquigarrow$  verify that every cycle has weight 0

## Decidability of determinizability (2)

$T$  violates the TP iff there exists situation as above such that:

1.  $|v_2| \neq |w_2|$ , or
2.  $|v_2| = |w_2| \neq 0$  and there is a mismatch between  $v_1$  and  $w_1$

To decide 1.:

consider a weighted graph with vertices  $(p, q)$  such that  $(p, q) \xrightarrow{n} (p', q')$  iff  $\exists \sigma$ ,  
 $p \xrightarrow{\sigma:v} p'$ ,  $q \xrightarrow{\sigma:w} q'$  and  $n = |v| - |w|$   
 $\rightsquigarrow$  verify that every cycle has weight 0

To decide 2.:

- ▶ Compute  $X = \{(p, q) \text{ s.t. } \exists u_2. (p, q) \xrightarrow{u_2:(v_2, w_2)} (p, q), |v_2| = |w_2| \neq 0\}$

## Decidability of determinizability (2)

$T$  violates the TP iff there exists situation as above such that:

1.  $|v_2| \neq |w_2|$ , or
2.  $|v_2| = |w_2| \neq 0$  and there is a mismatch between  $v_1$  and  $w_1$

To decide 1.:

consider a weighted graph with vertices  $(p, q)$  such that  $(p, q) \xrightarrow{n} (p', q')$  iff  $\exists \sigma$ ,  
 $p \xrightarrow{\sigma:v} p'$ ,  $q \xrightarrow{\sigma:w} q'$  and  $n = |v| - |w|$   
 $\rightsquigarrow$  verify that every cycle has weight 0

To decide 2.:

- ▶ Compute  $X = \{(p, q) \text{ s.t. } \exists u_2. (p, q) \xrightarrow{u_2:(v_2, w_2)} (p, q), |v_2| = |w_2| \neq 0\}$
- ▶ non-deterministically guess a path  $(p_0, p_0) \xrightarrow{u_1:(v_1, w_1)} (p, q) \in X$  such that there is a mismatch between  $v_1$  and  $w_1$

## Decidability of determinizability (2)

$T$  violates the TP iff there exists situation as above such that:

1.  $|v_2| \neq |w_2|$ , or
2.  $|v_2| = |w_2| \neq 0$  and there is a mismatch between  $v_1$  and  $w_1$

To decide 1.:

consider a weighted graph with vertices  $(p, q)$  such that  $(p, q) \xrightarrow{n} (p', q')$  iff  $\exists \sigma$ ,  
 $p \xrightarrow{\sigma:v} p'$ ,  $q \xrightarrow{\sigma:w} q'$  and  $n = |v| - |w|$   
 $\rightsquigarrow$  verify that every cycle has weight 0

To decide 2.:

- ▶ Compute  $X = \{(p, q) \text{ s.t. } \exists u_2. (p, q) \xrightarrow{u_2:(v_2, w_2)} (p, q), |v_2| = |w_2| \neq 0\}$
- ▶ non-deterministically guess a path  $(p_0, p_0) \xrightarrow{u_1:(v_1, w_1)} (p, q) \in X$  such that there is a mismatch between  $v_1$  and  $w_1$ 
  - ▶ its length can be bounded by  $2n^2$
  - ▶ non-deterministically guess the mismatch
  - ▶ position of the mismatch stored using two registers, whose values are bounded by  $2n^2M$
  - ▶  $\rightsquigarrow$  NLogSpace

## Decidability of determinizability (2)

$T$  violates the TP iff there exists situation as above such that:

1.  $|v_2| \neq |w_2|$ , or
2.  $|v_2| = |w_2| \neq 0$  and there is a mismatch between  $v_1$  and  $w_1$

To decide 1.:

consider a weighted graph with vertices  $(p, q)$  such that  $(p, q) \xrightarrow{n} (p', q')$  iff  $\exists \sigma$ ,  
 $p \xrightarrow{\sigma:v} p'$ ,  $q \xrightarrow{\sigma:w} q'$  and  $n = |v| - |w|$   
 $\rightsquigarrow$  verify that every cycle has weight 0

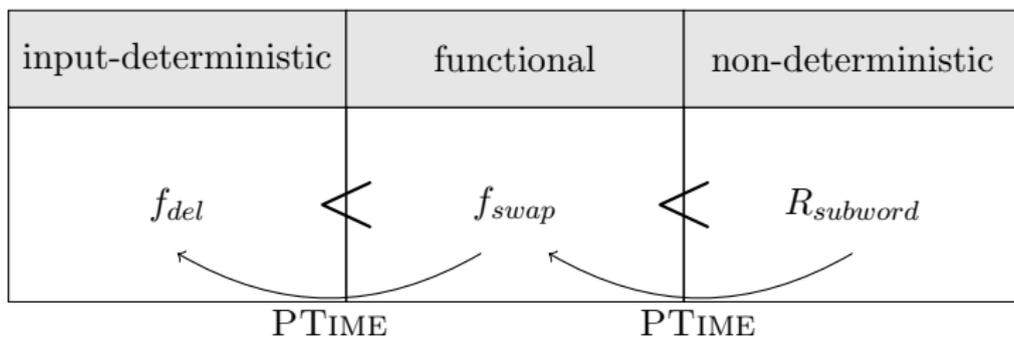
To decide 2.:

- ▶ Compute  $X = \{(p, q) \text{ s.t. } \exists u_2. (p, q) \xrightarrow{u_2:(v_2, w_2)} (p, q), |v_2| = |w_2| \neq 0\}$
- ▶ non-deterministically guess a path  $(p_0, p_0) \xrightarrow{u_1:(v_1, w_1)} (p, q) \in X$  such that there is a mismatch between  $v_1$  and  $w_1$ 
  - ▶ its length can be bounded by  $2n^2$
  - ▶ non-deterministically guess the mismatch
  - ▶ position of the mismatch stored using two registers, whose values are bounded by  $2n^2M$
  - ▶  $\rightsquigarrow$  NLogSpace

All together: decidable in PTime (and even in NLogSpace)

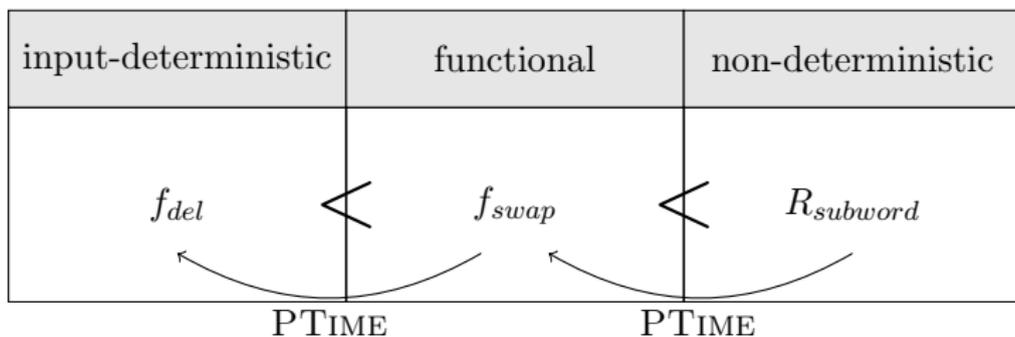
# Summary – Transducers

Expressiveness:



# Summary – Transducers

Expressiveness:



Equivalence: ( $dom(T_1) = dom(T_2)$  is known)

input-deterministic	functional	non-deterministic
PTIME	PTIME	undec

# Logics for transductions

## MSO on words

Over some finite alphabet  $\Sigma$ :

$$\varphi ::= \varphi \wedge \varphi \mid \neg\varphi \mid \exists x\varphi \mid \exists X\varphi \mid x \in X \mid \sigma(x) \mid S(x, y) \quad \sigma \in \Sigma$$

Over finite words, (set) variables interpreted by (sets of) positions.

Notation:  $\leq$  is the transitive closure of  $S$

## MSO on words

Over some finite alphabet  $\Sigma$ :

$$\varphi ::= \varphi \wedge \varphi \mid \neg\varphi \mid \exists x\varphi \mid \exists X\varphi \mid x \in X \mid \sigma(x) \mid S(x, y) \quad \sigma \in \Sigma$$

Over finite words, (set) variables interpreted by (sets of) positions.

Notation:  $\leq$  is the transitive closure of  $S$

### Some examples

- ▶ first position is an  $a$ :  $\exists x a(x) \wedge \forall y(x \leq y)$
- ▶ does not contain  $ab$ :  $\neg\exists x\exists y.S(x, y) \wedge a(x) \wedge b(y)$
- ▶ counting modulo: odd number of  $a$ , even length, ...

## MSO on words

Over some finite alphabet  $\Sigma$ :

$$\varphi ::= \varphi \wedge \varphi \mid \neg\varphi \mid \exists x\varphi \mid \exists X\varphi \mid x \in X \mid \sigma(x) \mid \mathcal{S}(x, y) \quad \sigma \in \Sigma$$

Over finite words, (set) variables interpreted by (sets of) positions.

Notation:  $\leq$  is the transitive closure of  $S$

### Some examples

- ▶ first position is an  $a$ :  $\exists x a(x) \wedge \forall y(x \leq y)$
- ▶ does not contain  $ab$ :  $\neg\exists x\exists y.S(x, y) \wedge a(x) \wedge b(y)$
- ▶ counting modulo: odd number of  $a$ , even length, ...

$$L_\phi = \{w \in \Sigma^* \mid w \models \phi\}$$

## MSO on words

Over some finite alphabet  $\Sigma$ :

$$\varphi ::= \varphi \wedge \varphi \mid \neg\varphi \mid \exists x\varphi \mid \exists X\varphi \mid x \in X \mid \sigma(x) \mid \mathcal{S}(x, y) \quad \sigma \in \Sigma$$

Over finite words, (set) variables interpreted by (sets of) positions.

Notation:  $\leq$  is the transitive closure of  $S$

### Some examples

- ▶ first position is an  $a$ :  $\exists x a(x) \wedge \forall y(x \leq y)$
- ▶ does not contain  $ab$ :  $\neg\exists x\exists y.S(x, y) \wedge a(x) \wedge b(y)$
- ▶ counting modulo: odd number of  $a$ , even length, ...

$$L_\phi = \{w \in \Sigma^* \mid w \models \phi\}$$

### Büchi-Elgot-Trakhenbrot

$L \subseteq \Sigma^*$  is MSO-definable iff it is recognisable by some FA.

# Examples of MSO formulae

- ▶ The first position:

$$\phi_{first}(x) =$$

## Examples of MSO formulae

- ▶ The first position:

$$\phi_{first}(x) =$$

- ▶ Sets  $X, Y$  partition the set of positions:

$$\phi_{partition}(X, Y) =$$

## Examples of MSO formulae

- ▶ The first position:

$$\phi_{first}(x) =$$

- ▶ Sets  $X, Y$  partition the set of positions:

$$\phi_{partition}(X, Y) =$$

- ▶ Set  $X$  is the set of even positions:

$$\phi_{even}(X) =$$

## Extension to transductions

$\phi(x)$ : MSO formula with one free FO variable  $x$

$w \in \Sigma^*$ ,  $i \in \{1, \dots, |w|\}$

Notation:  $w, i \models \phi(x)$ :  $\phi(x)$  evaluates to True at position  $i$  in  $w$

## Extension to transductions

$\phi(x)$ : MSO formula with one free FO variable  $x$

$w \in \Sigma^*$ ,  $i \in \{1, \dots, |w|\}$

Notation:  $w, i \models \phi(x)$ :  $\phi(x)$  evaluates to True at position  $i$  in  $w$

Consider formula  $\phi_{v_1}, \dots, \phi_{v_k}$ :

$w = a_1 \dots a_n \rightsquigarrow v_{j_1} \dots v_{j_n} \iff \forall i \in \{1, \dots, n\}, w, i \models \phi_{v_{j_i}}(x)$

## Extension to transductions

$\phi(x)$ : MSO formula with one free FO variable  $x$

$w \in \Sigma^*$ ,  $i \in \{1, \dots, |w|\}$

Notation:  $w, i \models \phi(x)$ :  $\phi(x)$  evaluates to True at position  $i$  in  $w$

Consider formula  $\phi_{v_1}, \dots, \phi_{v_k}$ :

$w = a_1 \dots a_n \rightsquigarrow v_{j_1} \dots v_{j_n} \iff \forall i \in \{1, \dots, n\}, w, i \models \phi_{v_{j_i}}(x)$

Example (Delete  $a$ 's)

$$\phi_b(x) \equiv b(x)$$

$$\phi_\epsilon(x) \equiv a(x)$$

Realizes the function  $f : u \in \{a, b\}^* \mapsto b^{|u|_b}$

## Extension to transductions

### Example (Append #)

- ▶ replace label  $\sigma$  of  $x$  by  $\sigma$  if  $x$  is **not** the last position
  
  
  
  
  
  
  
  
  
  
- ▶ replace label  $\sigma$  of  $x$  by  $\sigma\#$  if  $x$  is the last position

## Extension to transductions

### Example (Append #)

- ▶ replace label  $\sigma$  of  $x$  by  $\sigma$  if  $x$  is **not** the last position

$$\phi_{\sigma}(x) \equiv \sigma(x) \wedge \exists y S(x, y)$$

- ▶ replace label  $\sigma$  of  $x$  by  $\sigma\#$  if  $x$  is the last position

## Extension to transductions

### Example (Append #)

- ▶ replace label  $\sigma$  of  $x$  by  $\sigma$  if  $x$  is **not** the last position

$$\phi_{\sigma}(x) \equiv \sigma(x) \wedge \exists y S(x, y)$$

- ▶ replace label  $\sigma$  of  $x$  by  $\sigma\#$  if  $x$  is the last position

$$\phi_{\sigma\#}(x) \equiv \sigma(x) \wedge \forall y \neg S(x, y)$$

## Extension to transductions

### Example (Add a parity bit)

- ▶ replace label  $\sigma$  of  $x$  by  $1\sigma$  if  $x$  is the first position and odd number of 1
- ▶ replace label  $\sigma$  of  $x$  by  $0\sigma$  if  $x$  is the first position and even number of 1
- ▶ replace label  $\sigma$  of  $x$  by  $\sigma$  if  $x$  is not the first position

## Extension to transductions

### Example (Add a parity bit)

- ▶ replace label  $\sigma$  of  $x$  by  $1\sigma$  if  $x$  is the first position and odd number of 1

$$\phi_{1\sigma}(x) \equiv \sigma(x) \wedge \forall y \neg S(y, x) \wedge \phi_{\text{odd}_1}$$

- ▶ replace label  $\sigma$  of  $x$  by  $0\sigma$  if  $x$  is the first position and even number of 1
  
- ▶ replace label  $\sigma$  of  $x$  by  $\sigma$  if  $x$  is not the first position

## Extension to transductions

### Example (Add a parity bit)

- ▶ replace label  $\sigma$  of  $x$  by  $1\sigma$  if  $x$  is the first position and odd number of 1

$$\phi_{1\sigma}(x) \equiv \sigma(x) \wedge \forall y \neg S(y, x) \wedge \phi_{odd_1}$$

- ▶ replace label  $\sigma$  of  $x$  by  $0\sigma$  if  $x$  is the first position and even number of 1

$$\phi_{0\sigma}(x) \equiv \sigma(x) \wedge \forall y \neg S(y, x) \wedge \phi_{even_1}$$

- ▶ replace label  $\sigma$  of  $x$  by  $\sigma$  if  $x$  is not the first position

## Extension to transductions

### Example (Add a parity bit)

- ▶ replace label  $\sigma$  of  $x$  by  $1\sigma$  if  $x$  is the first position and odd number of 1

$$\phi_{1\sigma}(x) \equiv \sigma(x) \wedge \forall y \neg S(y, x) \wedge \phi_{odd_1}$$

- ▶ replace label  $\sigma$  of  $x$  by  $0\sigma$  if  $x$  is the first position and even number of 1

$$\phi_{0\sigma}(x) \equiv \sigma(x) \wedge \forall y \neg S(y, x) \wedge \phi_{even_1}$$

- ▶ replace label  $\sigma$  of  $x$  by  $\sigma$  if  $x$  is not the first position

$$\phi_{\sigma}(x) \equiv \sigma(x) \wedge \exists y S(y, x)$$

# Büchi Theorem for Rational Transductions

**Def**  $f : \Sigma^* \leftrightarrow \Sigma^*$  is MSO-definable if it can be “described” by a finite set of formulas  $\phi_{v_1}(x), \dots, \phi_{v_k}(x)$  ( $v_1, \dots, v_k \in \Sigma^*$ ).

$$w = a_1 \dots a_n \rightsquigarrow v_{j_1} \dots v_{j_n} \iff \forall i \in \{1, \dots, n\}, w, i \models \phi_{v_{j_i}}(x)$$

## Büchi Theorem for Rational Transductions

**Def**  $f : \Sigma^* \hookrightarrow \Sigma^*$  is MSO-definable if it can be “described” by a finite set of formulas  $\phi_{v_1}(x), \dots, \phi_{v_k}(x)$  ( $v_1, \dots, v_k \in \Sigma^*$ ).

$$w = a_1 \dots a_n \rightsquigarrow v_{j_1} \dots v_{j_n} \iff \forall i \in \{1, \dots, n\}, w, i \models \phi_{v_{j_i}}(x)$$

**Thm**  $f : \Sigma^* \hookrightarrow \Sigma^*$  is MSO-definable iff it is realisable by a finite state transducer.

# Büchi Theorem for Rational Transductions

**Def**  $f : \Sigma^* \hookrightarrow \Sigma^*$  is MSO-definable if it can be “described” by a finite set of formulas  $\phi_{v_1}(x), \dots, \phi_{v_k}(x)$  ( $v_1, \dots, v_k \in \Sigma^*$ ).

$$w = a_1 \dots a_n \rightsquigarrow v_{j_1} \dots v_{j_n} \iff \forall i \in \{1, \dots, n\}, w, i \models \phi_{v_{j_i}}(x)$$

**Thm**  $f : \Sigma^* \hookrightarrow \Sigma^*$  is MSO-definable iff it is realisable by a finite state transducer.

What about mirror ?

*ejcim*  $\mapsto$  *micje*

# Büchi Theorem for Rational Transductions

**Def**  $f : \Sigma^* \hookrightarrow \Sigma^*$  is MSO-definable if it can be “described” by a finite set of formulas  $\phi_{v_1}(x), \dots, \phi_{v_k}(x)$  ( $v_1, \dots, v_k \in \Sigma^*$ ).

$$w = a_1 \dots a_n \rightsquigarrow v_{j_1} \dots v_{j_n} \iff \forall i \in \{1, \dots, n\}, w, i \models \phi_{v_{j_i}}(x)$$

**Thm**  $f : \Sigma^* \hookrightarrow \Sigma^*$  is MSO-definable iff it is realisable by a finite state transducer.

What about mirror ?

$$ejcim \mapsto micje$$

Replace label of position  $x$  by  $\sigma$  if *last* –  $x$  is labeled  $\sigma$ .

# Büchi Theorem for Rational Transductions

**Def**  $f : \Sigma^* \hookrightarrow \Sigma^*$  is MSO-definable if it can be “described” by a finite set of formulas  $\phi_{v_1}(x), \dots, \phi_{v_k}(x)$  ( $v_1, \dots, v_k \in \Sigma^*$ ).

$$w = a_1 \dots a_n \rightsquigarrow v_{j_1} \dots v_{j_n} \iff \forall i \in \{1, \dots, n\}, w, i \models \phi_{v_{j_i}}(x)$$

**Thm**  $f : \Sigma^* \hookrightarrow \Sigma^*$  is MSO-definable iff it is realisable by a finite state transducer.

What about mirror ?

$ejcim \mapsto micje$

Replace label of position  $x$  by  $\sigma$  if *last* –  $x$  is labeled  $\sigma$ .

Not MSO-definable.

## Proof: from transducers to MSO

W.l.o.g., we assume  $T$  unambiguous.

For each transition  $t = (p, a, v, q)$  of  $T$ , we define the language  $L_t \subseteq (\Sigma \times \{0, 1\})^*$  such that:

$$\bar{w} \in L_t \iff \exists \text{ run } q_0 \xrightarrow{u|v} q_f \text{ s.t. } \pi_2(\bar{w})[i] = 1 \text{ iff } t \text{ used at position } i$$

## Proof: from transducers to MSO

W.l.o.g., we assume  $T$  unambiguous.

For each transition  $t = (p, a, v, q)$  of  $T$ , we define the language  $L_t \subseteq (\Sigma \times \{0, 1\})^*$  such that:

$\bar{w} \in L_t \iff \exists \text{ run } q_0 \xrightarrow{u|v} q_f \text{ s.t. } \pi_2(\bar{w})[i] = 1 \text{ iff } t \text{ used at position } i$

$L_t$  is regular, recognized by  $A_t$ , obtained as follows:

- ▶  $p \xrightarrow{(a,1)} q$
- ▶  $p' \xrightarrow{(b,0)} q'$  for each transition  $t' = (p', b, v', q') \neq t$

## Proof: from transducers to MSO

W.l.o.g., we assume  $T$  unambiguous.

For each transition  $t = (p, a, v, q)$  of  $T$ , we define the language  $L_t \subseteq (\Sigma \times \{0, 1\})^*$  such that:

$$\bar{w} \in L_t \iff \exists \text{ run } q_0 \xrightarrow{u|v} q_f \text{ s.t. } \pi_2(\bar{w})[i] = 1 \text{ iff } t \text{ used at position } i$$

$L_t$  is regular, recognized by  $A_t$ , obtained as follows:

- ▶  $p \xrightarrow{(a,1)} q$
- ▶  $p' \xrightarrow{(b,0)} q'$  for each transition  $t' = (p', b, v', q') \neq t$

By the previous result,  $L_t$  can be translated into  $\phi_t(x)$ .

## Proof: from transducers to MSO

W.l.o.g., we assume  $T$  unambiguous.

For each transition  $t = (p, a, v, q)$  of  $T$ , we define the language  $L_t \subseteq (\Sigma \times \{0, 1\})^*$  such that:

$\bar{w} \in L_t \iff \exists \text{ run } q_0 \xrightarrow{u|v} q_f \text{ s.t. } \pi_2(\bar{w})[i] = 1 \text{ iff } t \text{ used at position } i$

$L_t$  is regular, recognized by  $A_t$ , obtained as follows:

- ▶  $p \xrightarrow{(a,1)} q$
- ▶  $p' \xrightarrow{(b,0)} q'$  for each transition  $t' = (p', b, v', q') \neq t$

By the previous result,  $L_t$  can be translated into  $\phi_t(x)$ .

We let  $\phi_v(x) = \bigvee_{t=(p,a,v,q)} \phi_t(x)$ .

## Proof: from MSO to transducers

For each  $\phi_v(x)$ , build an automaton  $A_v$  that recognizes words  $\bar{w} \in (\Sigma \times \{0, 1\})^*$  such that  $\pi_2(\bar{w})[i] = 1$  iff  $w, i \models \phi_v(x)$ .

## Proof: from MSO to transducers

For each  $\phi_v(x)$ , build an automaton  $A_v$  that recognizes words  $\bar{w} \in (\Sigma \times \{0, 1\})^*$  such that  $\pi_2(\bar{w})[i] = 1$  iff  $w, i \models \phi_v(x)$ .

**Claim:** As  $\phi_{v_1}, \dots, \phi_{v_k}$  define a function  $f$ , for each word  $w \in \text{dom}(f)$ , and for each position  $i \in \{1, \dots, |w|\}$ , there is exactly one  $j$  such that  $w, i \models \phi_{v_j}$ .

## Proof: from MSO to transducers

For each  $\phi_v(x)$ , build an automaton  $A_v$  that recognizes words  $\bar{w} \in (\Sigma \times \{0, 1\})^*$  such that  $\pi_2(\bar{w})[i] = 1$  iff  $w, i \models \phi_v(x)$ .

**Claim:** As  $\phi_{v_1}, \dots, \phi_{v_k}$  define a function  $f$ , for each word  $w \in \text{dom}(f)$ , and for each position  $i \in \{1, \dots, |w|\}$ , there is exactly one  $j$  such that  $w, i \models \phi_{v_j}$ .

Consider the automaton  $A = \prod_{j=1}^k A_{v_j}$ , synchronised on  $\Sigma$ . Transform it into a transducer by outputting  $v_j$  if transition  $(a, 1)$  is used in  $A_{v_j}$ .

## Proof: from MSO to transducers

For each  $\phi_v(x)$ , build an automaton  $A_v$  that recognizes words  $\bar{w} \in (\Sigma \times \{0, 1\})^*$  such that  $\pi_2(\bar{w})[i] = 1$  iff  $w, i \models \phi_v(x)$ .

**Claim:** As  $\phi_{v_1}, \dots, \phi_{v_k}$  define a function  $f$ , for each word  $w \in \text{dom}(f)$ , and for each position  $i \in \{1, \dots, |w|\}$ , there is exactly one  $j$  such that  $w, i \models \phi_{v_j}$ .

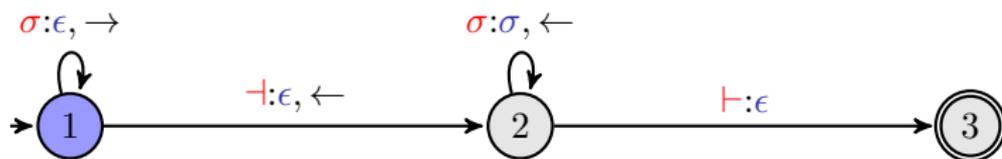
Consider the automaton  $A = \prod_{j=1}^k A_{v_j}$ , synchronised on  $\Sigma$ . Transform it into a transducer by outputting  $v_j$  if transition  $(a, 1)$  is used in  $A_{v_j}$ .

This construction is correct thanks to previous claim. □

# The class of regular functions

# Two-way finite transducers (2FT)

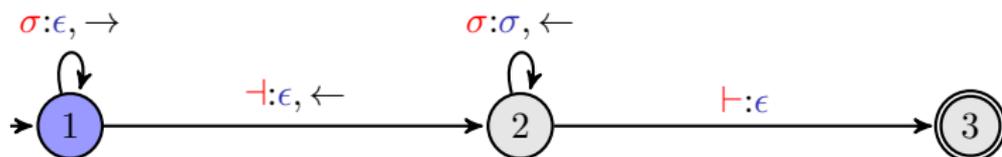
input  $\vdash$  *a d o s s n o b*  $\vdash$   
 $\blacktriangle$



output  
 $\blacktriangle$

# Two-way finite transducers (2FT)

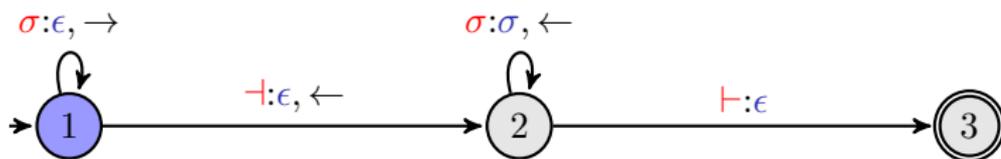
input  $\vdash$  a d o s s n o b  $\vdash$   
 $\blacktriangle$



output  
 $\blacktriangle$

# Two-way finite transducers (2FT)

input  $\vdash$  a d o s s n o b  $\vdash$

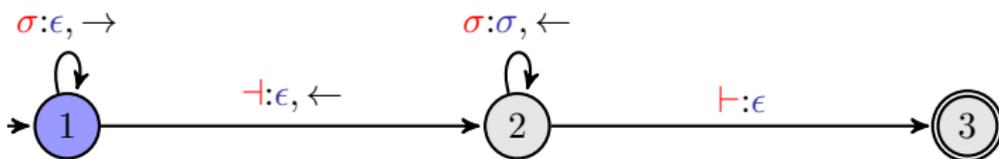


output



# Two-way finite transducers (2FT)

input  $\vdash$  *a* *d* *o* *s* *s* *n* *o* *b*  $\vdash$



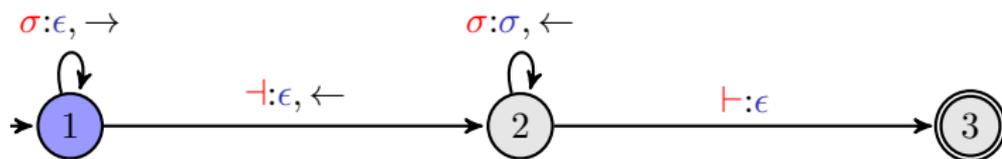
output



# Two-way finite transducers (2FT)

input  $\vdash$  *a* *d* *o* *s* *s* *n* *o* *b*  $\vdash$

▲



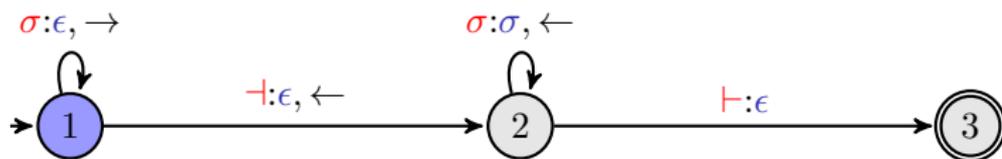
output

▲

# Two-way finite transducers (2FT)

input  $\vdash$  *a* *d* *o* *s* *s* *n* *o* *b*  $\vdash$

▲



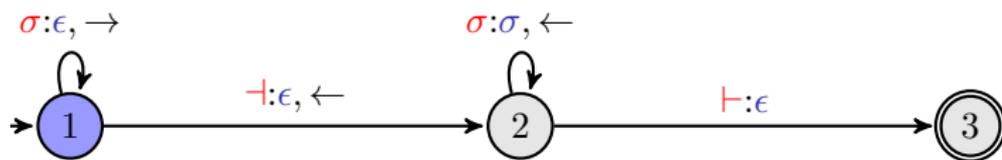
output

▲

# Two-way finite transducers (2FT)

input  $\vdash$  *a* *d* *o* *s* *s* *n* *o* *b*  $\vdash$

▲

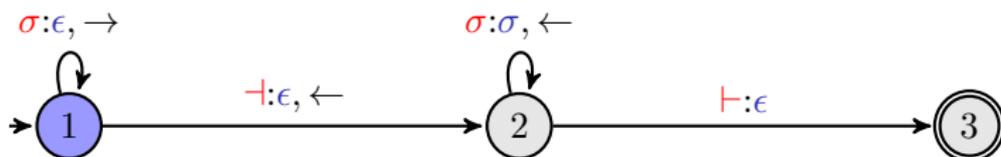


output

▲

# Two-way finite transducers (2FT)

input  $\vdash$  *a* *d* *o* *s* *s* *n* *o* *b*  $\vdash$

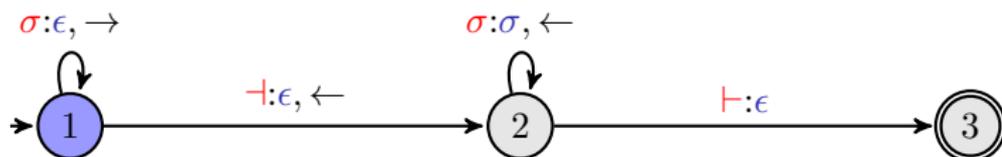


output



# Two-way finite transducers (2FT)

input  $\vdash$  *a d o s s n o b*  $\vdash$   
▲



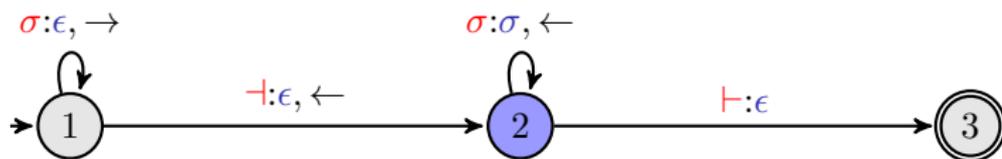
output

▲

# Two-way finite transducers (2FT)

input  $\vdash$  *a* *d* *o* *s* *s* *n* *o* *b*  $\vdash$

▲

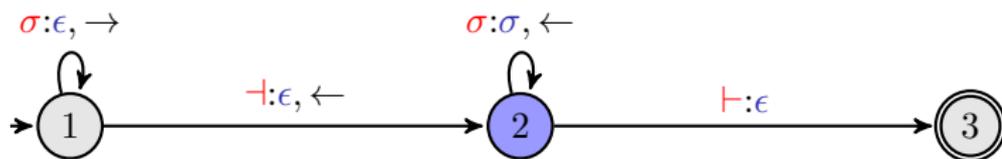


output

▲

# Two-way finite transducers (2FT)

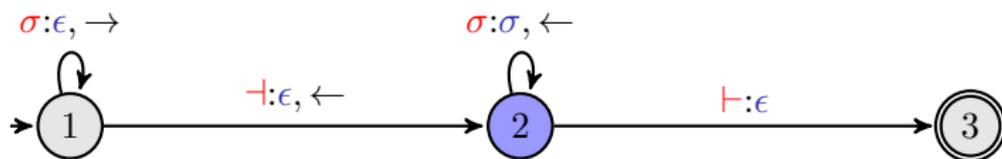
input  $\vdash$  *a* *d* *o* *s* *s* *n* *o* *b*  $\vdash$   
▲



output *b*  
▲

# Two-way finite transducers (2FT)

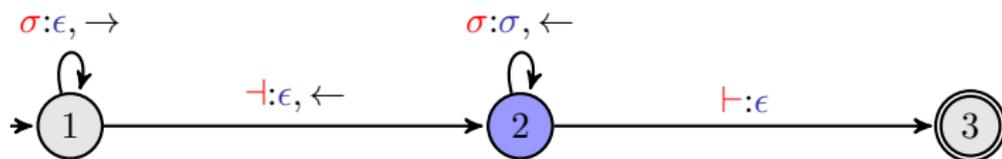
input  $\vdash$  *a* *d* *o* *s* *s* *n* *o* *b*  $\vdash$   
▲



output *b* *o*  
▲

# Two-way finite transducers (2FT)

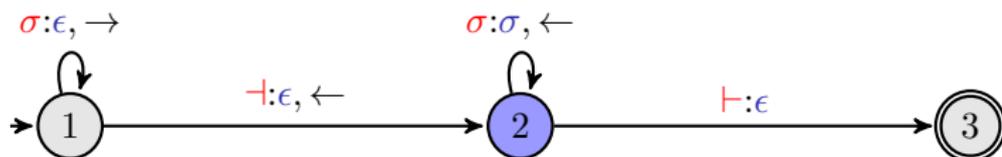
input  $\vdash$  *a* *d* *o* *s* *s* *n* *o* *b*  $\vdash$   
▲



output *b* *o* *n*  
▲

# Two-way finite transducers (2FT)

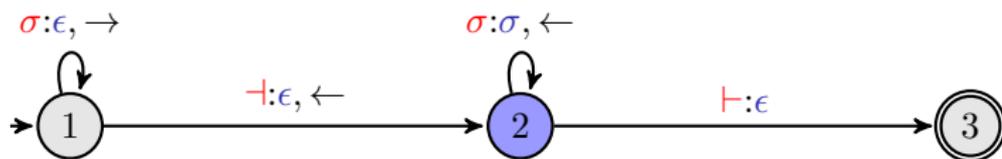
input  $\vdash$  *a* *d* *o* *s* *s* *n* *o* *b*  $\vdash$   
 $\blacktriangle$



output *b* *o* *n* *s*  
 $\blacktriangle$

# Two-way finite transducers (2FT)

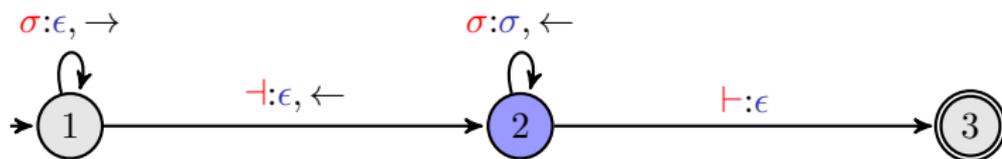
input  $\vdash$  a d o s s n o b  $\vdash$   
 $\blacktriangle$



output b o n s s  
 $\blacktriangle$

# Two-way finite transducers (2FT)

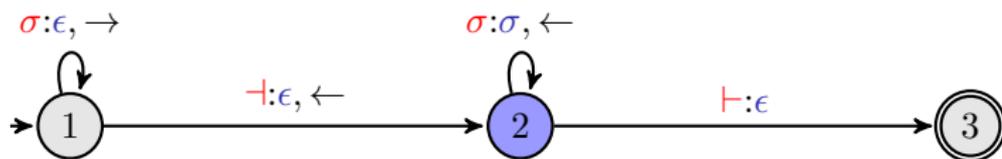
input  $\vdash$  *a* *d* *o* *s* *s* *n* *o* *b*  $\vdash$   
▲



output *b* *o* *n* *s* *s* *o*  
▲

# Two-way finite transducers (2FT)

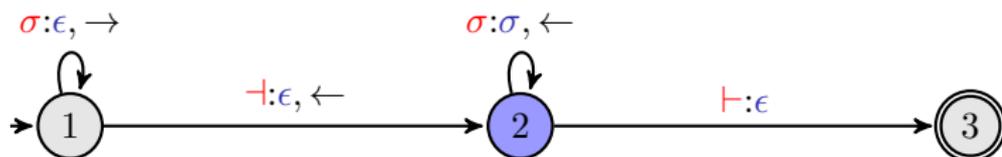
input  $\vdash$  *a d o s s n o b*  $\vdash$   
 $\blacktriangle$



output *b o n s s o d*  
 $\blacktriangle$

# Two-way finite transducers (2FT)

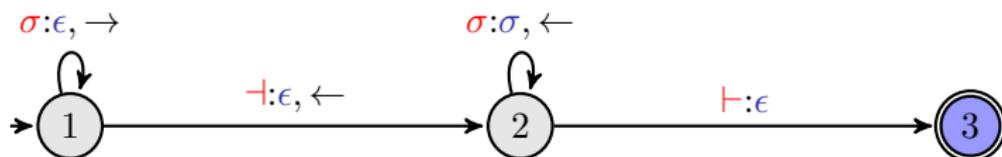
input  $\vdash$  a d o s s n o b  $\vdash$   
 $\blacktriangle$



output b o n s s o d a  
 $\blacktriangle$

# Two-way finite transducers (2FT)

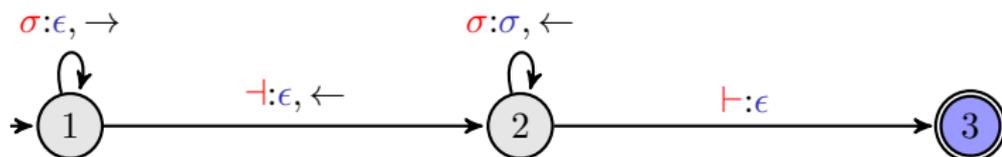
input  $\vdash$  *a d o s s n o b*  $\vdash$   
 $\blacktriangle$



output *b o n s s o d a*  
 $\blacktriangle$

# Two-way finite transducers (2FT)

input  $\vdash$  a d o s s n o b  $\vdash$   
 $\blacktriangle$



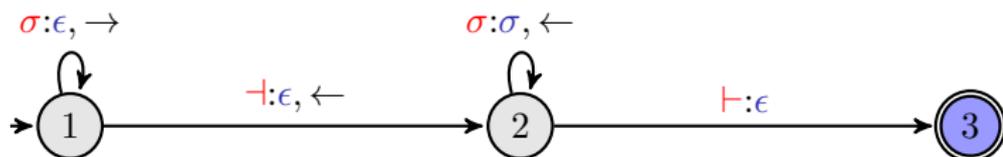
output b o n s s o d a  
 $\blacktriangle$

Other examples

*march, 2019*  $\mapsto$  2019, *march*

# Two-way finite transducers (2FT)

input  $\vdash$  a d o s s n o b  $\vdash$   
 $\blacktriangle$



output b o n s s o d a  
 $\blacktriangle$

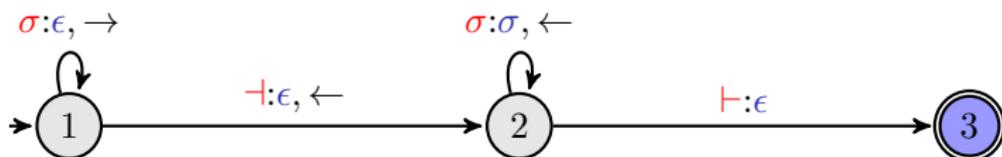
Other examples

*march, 2019*  $\mapsto$  2019, *march*

*u*  $\mapsto$  *uu* (copy)

# Two-way finite transducers (2FT)

input  $\vdash$  a d o s s n o b  $\vdash$   
 $\blacktriangle$



output b o n s s o d a  
 $\blacktriangle$

## Other examples

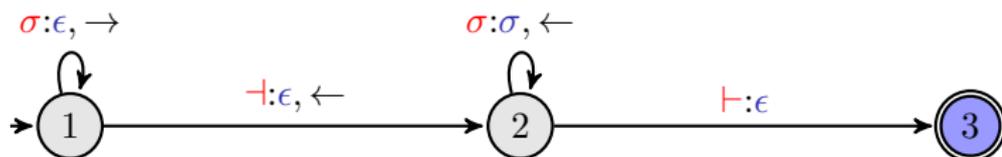
*march, 2019*  $\mapsto$  2019, *march*

*u*  $\mapsto$  *uu* (copy)

*u*  $\mapsto$   $f_1(u)f_2(u)$  (copy+trans)

# Two-way finite transducers (2FT)

input  $\vdash$  a d o s s n o b  $\vdash$   
 $\blacktriangle$



output b o n s s o d a  
 $\blacktriangle$

## Other examples

*march, 2019*  $\mapsto$  2019, *march*

$u \mapsto uu$  (copy)

$u \mapsto f_1(u)f_2(u)$  (copy+trans)

$u_1\#u_2\#\dots\#u_k \mapsto \overline{u_1}\#\dots\#\overline{u_k}$  (local reverse)

## Some important results on two-way transducers

Over (functional) transductions:

- ▶ equivalence is **decidable** in PSPACE

(Gurari 82) (Culik, Karhumäki,87)

---

<sup>2</sup> $\Sigma^* a \Sigma^*$  is not definable by any one-way reversible automaton

# Some important results on two-way transducers

Over (functional) transductions:

- ▶ equivalence is **decidable** in PSPACE

(Gurari 82) (Culik, Karhumäki,87)

- ▶ **closed** under composition

(Chytil, Jakl, 77)

---

<sup>2</sup> $\Sigma^* a \Sigma^*$  is not definable by any one-way reversible automaton

# Some important results on two-way transducers

Over (functional) transductions:

- ▶ equivalence is **decidable** in PSPACE

(Gurari 82) (Culik, Karhumäki,87)

- ▶ **closed** under composition

(Chytil, Jakl, 77)

- ▶ equivalent to **reversible**<sup>2</sup> two-way transducers

(Dartois,Fournier,Jecker,Lhote,17)

---

<sup>2</sup> $\Sigma^* a \Sigma^*$  is not definable by any one-way reversible automaton

# Some important results on two-way transducers

Over (functional) transductions:

- ▶ equivalence is **decidable** in PSPACE

(Gurari 82) (Culik, Karhumäki,87)

- ▶ **closed** under composition

(Chytil, Jakl, 77)

- ▶ equivalent to **reversible**<sup>2</sup> two-way transducers

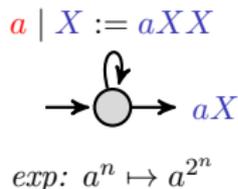
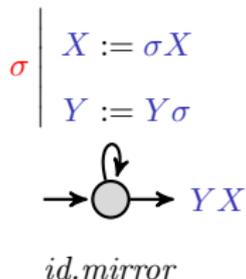
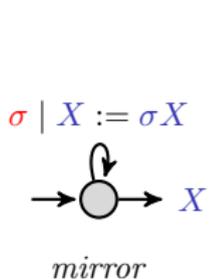
(Dartois,Fournier,Jecker,Lhote,17)

- ▶ and to many other models ...

---

<sup>2</sup> $\Sigma^* a \Sigma^*$  is not definable by any one-way reversible automaton

# Transducers with registers



- ▶ deterministic one-way
- ▶ equivalent to 2FT if linear updates
- ▶ decidable equivalence problem

(Alur, Cerny, 10)

(F., R.,17) (Benedikt et. al., 17)

## (Courcelle) MSO Transducers

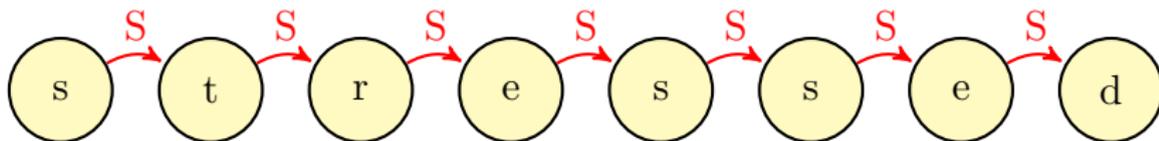
*“interpreting the output structure in the input structure”*

- ▶ output predicates defined by MSO formulas interpreted over the input structure

## (Courcelle) MSO Transducers

*“interpreting the output structure in the input structure”*

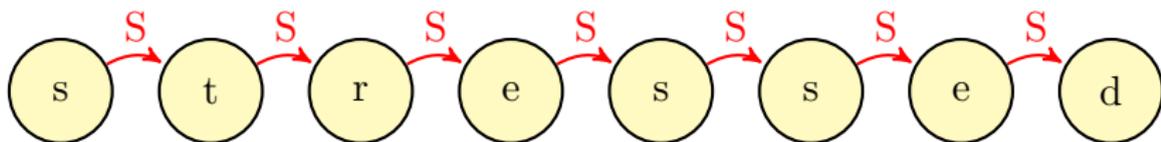
- ▶ output predicates defined by MSO formulas interpreted over the input structure



## (Courcelle) MSO Transducers

*“interpreting the output structure in the input structure”*

- ▶ output predicates defined by MSO formulas interpreted over the input structure



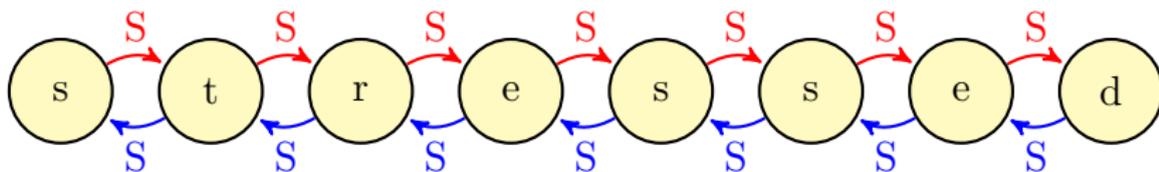
$$\phi_S(x, y) \equiv S(y, x)$$

$$\phi_\sigma(x) \equiv \sigma(x)$$

## (Courcelle) MSO Transducers

*“interpreting the output structure in the input structure”*

- ▶ output predicates defined by MSO formulas interpreted over the input structure



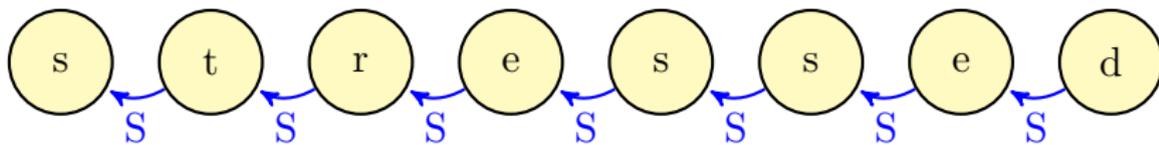
$$\phi_S(x, y) \equiv S(y, x)$$

$$\phi_\sigma(x) \equiv \sigma(x)$$

## (Courcelle) MSO Transducers

*“interpreting the output structure in the input structure”*

- ▶ output predicates defined by MSO formulas interpreted over the input structure



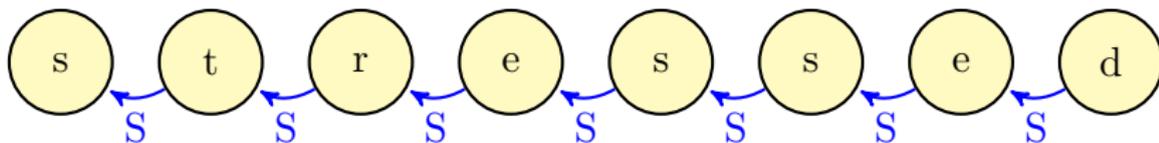
$$\phi_S(x, y) \equiv S(y, x)$$

$$\phi_\sigma(x) \equiv \sigma(x)$$

## (Courcelle) MSO Transducers

*“interpreting the output structure in the input structure”*

- ▶ output predicates defined by MSO formulas interpreted over the input structure

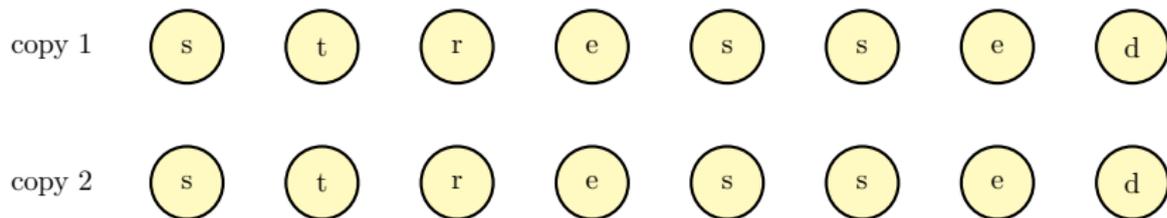


$$\phi_S(x, y) \equiv S(y, x)$$

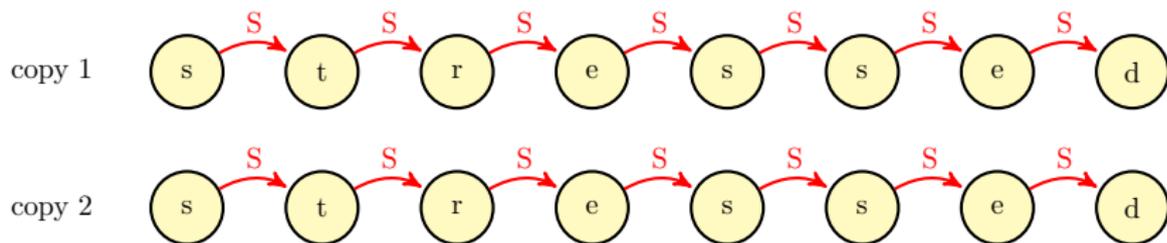
$$\phi_\sigma(x) \equiv \sigma(x)$$

- ▶ input structure can be copied a fixed number of times:  
 $u \mapsto uu$ , or  $u \mapsto u.\text{mirror}(u)$ .

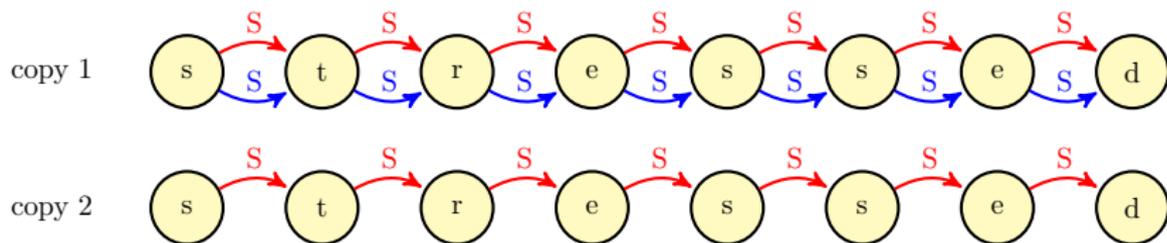
Other example :  $u \mapsto u.\text{mirror}(u)$



Other example :  $u \mapsto u.\text{mirror}(u)$



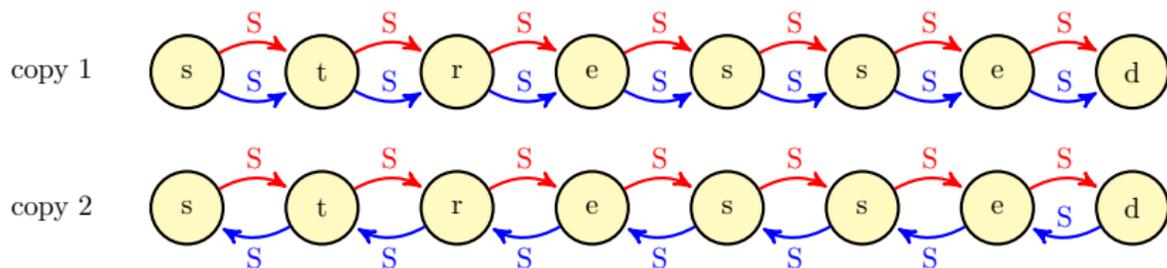
Other example :  $u \mapsto u.\text{mirror}(u)$



## Formulas

**copy 1:**  $\phi_S^1(x, y) \equiv S(x, y)$

Other example :  $u \mapsto u.\text{mirror}(u)$

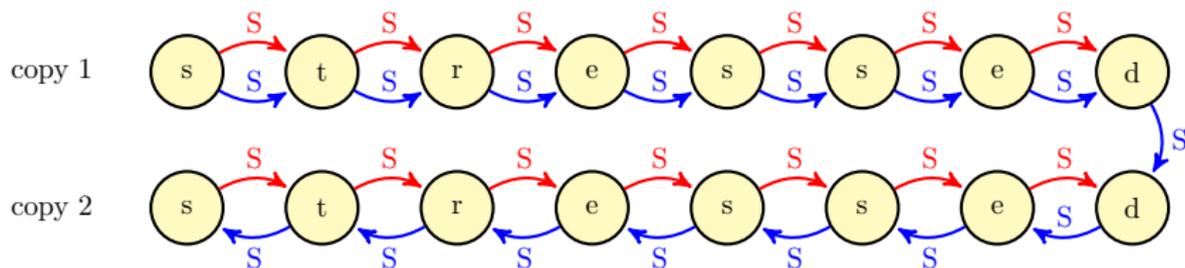


## Formulas

$$\text{copy 1: } \phi_S^1(x, y) \equiv S(x, y)$$

$$\text{copy 2: } \phi_S^2(x, y) \equiv S(y, x)$$

Other example :  $u \mapsto u.\text{mirror}(u)$



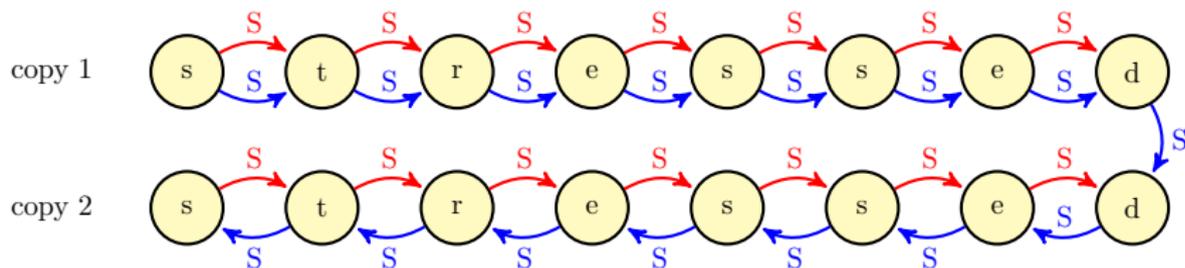
## Formulas

$$\text{copy 1: } \phi_S^1(x, y) \equiv S(x, y)$$

$$\text{copy 2: } \phi_S^2(x, y) \equiv S(y, x)$$

$$\text{copy 1 to copy 2: } \phi_S^{1 \rightarrow 2}(x, y) \equiv x = y \wedge \text{last}(x)$$

Other example :  $u \mapsto u.\text{mirror}(u)$



## Formulas

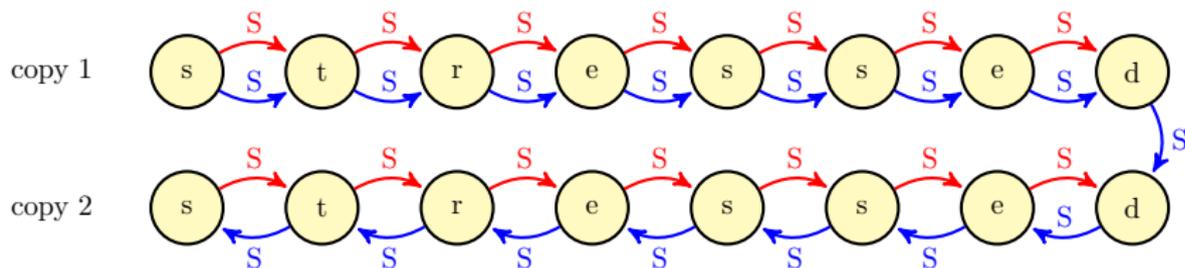
$$\text{copy 1: } \phi_S^1(x, y) \equiv S(x, y)$$

$$\text{copy 2: } \phi_S^2(x, y) \equiv S(y, x)$$

$$\text{copy 1 to copy 2: } \phi_S^{1 \rightarrow 2}(x, y) \equiv x = y \wedge \text{last}(x)$$

$$\text{copy 2 to copy 1: } \phi_S^{2 \rightarrow 1}(x, y) \equiv \perp$$

Other example :  $u \mapsto u.\text{mirror}(u)$



## Formulas

$$\text{copy 1: } \phi_S^1(x, y) \equiv S(x, y)$$

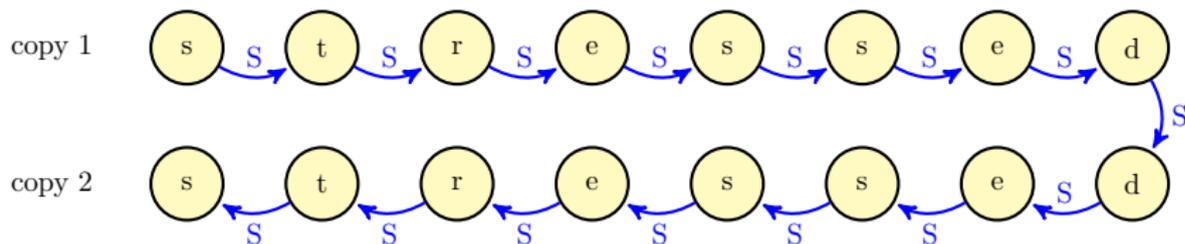
$$\text{copy 2: } \phi_S^2(x, y) \equiv S(y, x)$$

$$\text{copy 1 to copy 2: } \phi_S^{1 \rightarrow 2}(x, y) \equiv x = y \wedge \text{last}(x)$$

$$\text{copy 2 to copy 1: } \phi_S^{2 \rightarrow 1}(x, y) \equiv \perp$$

$$\text{for all copies } i: \phi_\sigma^i(x) \equiv \sigma(x)$$

Other example :  $u \mapsto u.\text{mirror}(u)$



## Formulas

$$\text{copy 1: } \phi_S^1(x, y) \equiv S(x, y)$$

$$\text{copy 2: } \phi_S^2(x, y) \equiv S(y, x)$$

$$\text{copy 1 to copy 2: } \phi_S^{1 \rightarrow 2}(x, y) \equiv x = y \wedge \text{last}(x)$$

$$\text{copy 2 to copy 1: } \phi_S^{2 \rightarrow 1}(x, y) \equiv \perp$$

$$\text{for all copies } i: \phi_\sigma^i(x) \equiv \sigma(x)$$

## Büchi Theorem for Regular Transductions

Let  $f : \Sigma^* \leftrightarrow \Sigma^*$ .

Theorem (Engelfriet, Hoogeboom, 01)

*The following are equivalent:*

1.  *$f$  is definable by a deterministic two-way transducer*
2.  *$f$  is MSO-definable.*

## Büchi Theorem for Regular Transductions

Let  $f : \Sigma^* \leftrightarrow \Sigma^*$ .

Theorem (Engelfriet, Hoogeboom, 01)

*The following are equivalent:*

1.  *$f$  is definable by a deterministic two-way transducer*
2.  *$f$  is MSO-definable.*

**Consequence** Equivalence is decidable for MSO-transducers, and they are closed under composition.

# Büchi Theorem for Regular Transductions

Let  $f : \Sigma^* \hookrightarrow \Sigma^*$ .

**Theorem** (Engelfriet, Hoogeboom, 01)

*The following are equivalent:*

1.  $f$  is definable by a deterministic two-way transducer
2.  $f$  is MSO-definable.

**Consequence** Equivalence is decidable for MSO-transducers, and they are closed under composition.

**Proof ideas:** MSO-transducers are 2-way transducers with MSO jumps  $\phi_S^{c \rightarrow c'}(x, y)$

- ▶ turn jumps into walks
- ▶ hold enough information to decide MSO-formulas locally:  
states = MSO-types

$$f = \hat{f} \circ f_{types} \quad (\text{use composition closure of 2-way trans})$$

# Summary – Expressiveness

	input-deterministic	functional	non-deterministic
1-way (rational)		$\prec$	$\prec$
2-way (regular)	$\wedge$	$=$	$\prec$

# Summary – Expressiveness

	input-deterministic	functional	non-deterministic
1-way (rational)		← PTIME	← PTIME
2-way (regular)			← PSPACE

# Summary – Expressiveness

	input-deterministic	functional	non-deterministic
1-way (rational)		← PTIME	← PTIME ↑ UNDEC
2-way (regular)		↑ DEC	← PSPACE ↑ UNDEC

(F., Gauwin, R., Servais, 13)

(Baschenis, Gauwin, Muscholl, Puppis,17)

## Summary – Equivalence problem

$dom(T_1) = dom(T_2)$  is known.

	input-deterministic	functional	non-deterministic
1-way (rational)	P <sub>TIME</sub>	P <sub>TIME</sub>	undec
2-way (regular)	P <sub>SPACE</sub>	P <sub>SPACE</sub>	undec

Some other (recent) results

## Other specification languages

- ▶ **FO**-transducers
  - ▶ equivalent to aperiodic transducers with registers (F., Krishna, Trivedi, 14)
  - ▶ and to aperiodic 2-way transducers (Dartois, Jecker, R., 16)

## Other specification languages

- ▶ **FO**-transducers
  - ▶ equivalent to aperiodic transducers with registers (F., Krishna, Trivedi, 14)
  - ▶ and to aperiodic 2-way transducers (Dartois, Jecker, R., 16)
- ▶ regular function expressions
  - ▶ iterated sum  $f^*(u) = f(u_1)f(u_2)\dots f(u_n)$  for  $u = u_1\dots u_n$
  - ▶ chain sum  $f^c(u) = f(u_1u_2)f(u_2u_3)\dots f(u_{n-1}u_n)$
  - ▶ introduced by Alur, Freilich, Raghothaman in 14
  - ▶ direct construction from 2FT by Baudru, R. in 18
  - ▶ extended to infinite words by Dave, Gastin, Krishna in 18
  - ▶ non-deterministic 2FT by Choffrut, Guillon in 14

## Other specification languages

- ▶ **FO**-transducers
  - ▶ equivalent to aperiodic transducers with registers (F., Krishna, Trivedi, 14)
  - ▶ and to aperiodic 2-way transducers (Dartois, Jecker, R., 16)
- ▶ regular function expressions
  - ▶ iterated sum  $f^*(u) = f(u_1)f(u_2)\dots f(u_n)$  for  $u = u_1\dots u_n$
  - ▶ chain sum  $f^c(u) = f(u_1u_2)f(u_2u_3)\dots f(u_{n-1}u_n)$
  - ▶ introduced by Alur, Freilich, Raghothaman in 14
  - ▶ direct construction from 2FT by Baudru, R. in 18
  - ▶ extended to infinite words by Dave, Gastin, Krishna in 18
  - ▶ non-deterministic 2FT by Choffrut, Guillon in 14
- ▶ functions on lists, equipped with function composition  $\circ$  by Bojanczyk, Daviaud and Krishna in 18

## Other specification languages

- ▶ **FO**-transducers
  - ▶ equivalent to aperiodic transducers with registers (F., Krishna, Trivedi, 14)
  - ▶ and to aperiodic 2-way transducers (Dartois, Jecker, R., 16)
- ▶ regular function expressions
  - ▶ iterated sum  $f^*(u) = f(u_1)f(u_2)\dots f(u_n)$  for  $u = u_1\dots u_n$
  - ▶ chain sum  $f^c(u) = f(u_1u_2)f(u_2u_3)\dots f(u_{n-1}u_n)$
  - ▶ introduced by Alur, Freilich, Raghothaman in 14
  - ▶ direct construction from 2FT by Baudru, R. in 18
  - ▶ extended to infinite words by Dave, Gastin, Krishna in 18
  - ▶ non-deterministic 2FT by Choffrut, Guillon in 14
- ▶ functions on lists, equipped with function composition  $\circ$  by Bojanczyk, Daviaud and Krishna in 18
- ▶ an expressive decidable logic tailored to (non-functional) transductions Dartois, F., Lhote, 18

# Definability Problems

## Definition

$\mathcal{F}$ : logical fragment of MSOT (e.g. FOT)

**Input:**  $T$  an MSOT

**Output:** Is  $\llbracket T \rrbracket$  FO-definable ?

# Definability Problems

## Definition

$\mathcal{F}$ : logical fragment of MSOT (e.g. FOT)

**Input:**  $T$  an MSOT

**Output:** Is  $\llbracket T \rrbracket$  FO-definable ?

## Results

- ▶ **Decidable** for "rational" MSOT (=rational functions)  
F., Gauwin, Lhote, 16
- ▶ **Open** for MSOT

# Register Minimization Problems

Rational functions = Register transd. with updates  $X := Yu$

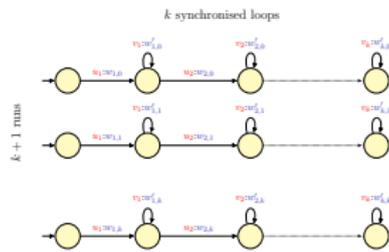
# Register Minimization Problems

Rational functions = Register transd. with updates  $X := Yu$

Theorem (Daviaud, R., Talbot, 16)

*A transducer  $T$  can be expressed using  $k$  registers iff it satisfies the Twinning Property of order  $k$ .*

For all situations like:



there are two runs  $0 \leq i < j \leq k$  s.t. for every loop  $\ell$ ,

we have  $\text{delay}(w_{1,i} \dots w_{\ell,i}, w_{1,j} \dots w_{\ell,j}) = \text{delay}(w_{1,i} \dots w_{\ell,i}, w_{1,j} \dots w_{\ell,j})$

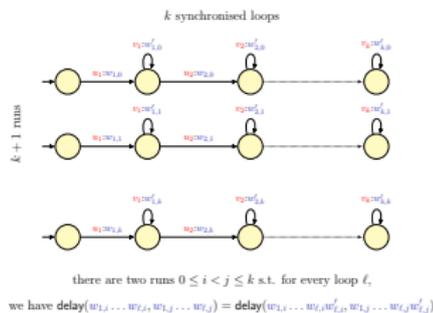
# Register Minimization Problems

Rational functions = Register transd. with updates  $X := Yu$

Theorem (Daviaud, R., Talbot, 16)

*A transducer  $T$  can be expressed using  $k$  registers iff it satisfies the Twinning Property of order  $k$ .*

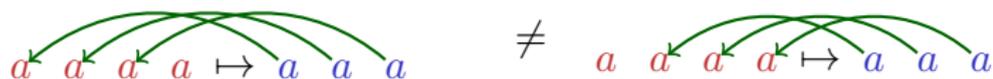
For all situations like:



Other results:

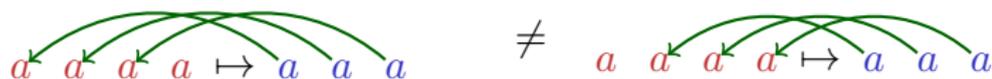
- ▶ multi-sequential transducers Daviaud, Jecker, R., Villevalois, 17
- ▶ concatenation-free non-det. reg. transducers Baschenis, Gauwin, Muscholl, Puppis, 16
- ▶ concatenation-free **det.** reg transducers R., Villevalois, 19

# Origin semantics (Bojanczyk, 14)



Origin semantics  $\llbracket T \rrbracket_o$  inherent to most transducer models  $T$  !

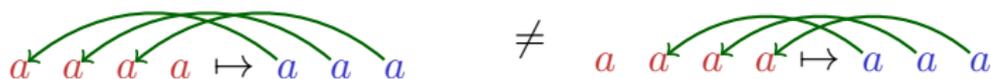
## Origin semantics (Bojanczyk, 14)



Origin semantics  $\llbracket T \rrbracket_o$  inherent to most transducer models  $T$  !

- ▶ existence of a canonical transducer if *origin* is taken into account (Bojanczyk, 14)
- ▶ decidable FO-definability of MSOT *with* origin

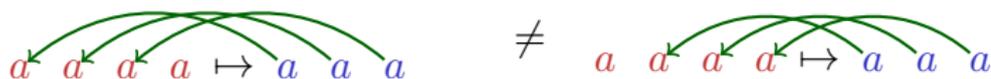
## Origin semantics (Bojanczyk, 14)



Origin semantics  $\llbracket T \rrbracket_o$  inherent to most transducer models  $T$  !

- ▶ existence of a canonical transducer if *origin* is taken into account (Bojanczyk, 14)
- ▶ decidable FO-definability of MSOT *with* origin
- ▶ algorithmic problems modulo origin ( $\llbracket T_1 \rrbracket_o = \llbracket T_2 \rrbracket_o$ )
- ▶ extended to "similar" origins through resynchronisers (F., Maneth, R., Talbot, 15) (F., Jecker, Löding, Winter, 16), (Bose, Muscholl, Penelle, Puppis, 18)

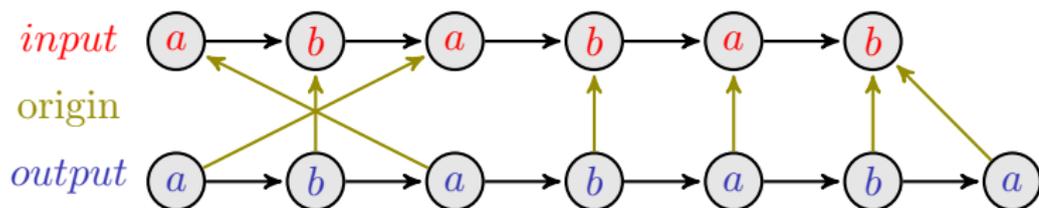
## Origin semantics (Bojanczyk, 14)



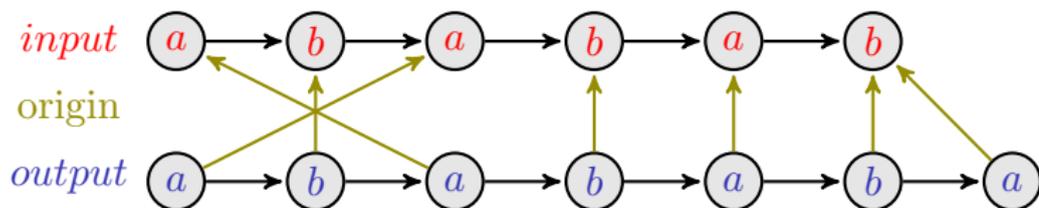
Origin semantics  $\llbracket T \rrbracket_o$  inherent to most transducer models  $T$  !

- ▶ existence of a canonical transducer if *origin* is taken into account (Bojanczyk, 14)
- ▶ decidable FO-definability of MSOT *with* origin
- ▶ algorithmic problems modulo origin ( $\llbracket T_1 \rrbracket_o = \llbracket T_2 \rrbracket_o$ )
- ▶ extended to "similar" origins through resynchronisers (F., Maneth, R., Talbot, 15) (F., Jecker, Löding, Winter, 16), (Bose, Muscholl, Penelle, Puppis, 18)
- ▶ study of rational relation subclasses by control languages  $REL(C)$ ,  $C \subseteq \{\text{in}, \text{out}\}^*$  (Descotte, Figueira, Libkin, Puppis)

# An expressive origin-based logic tailored to transductions (Dartois, F., Lhote, 18)

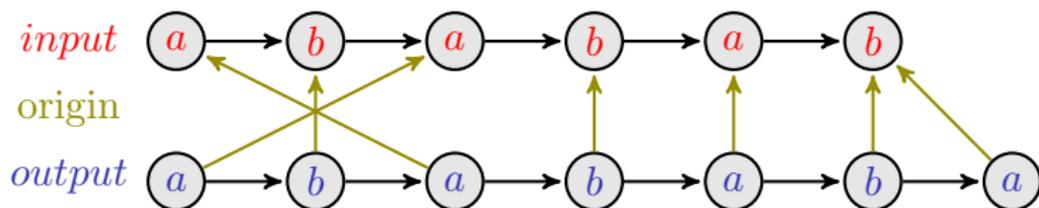


# An expressive origin-based logic tailored to transductions (Dartois, F., Lhote, 18)



transduction  $\approx$  set of origin graphs

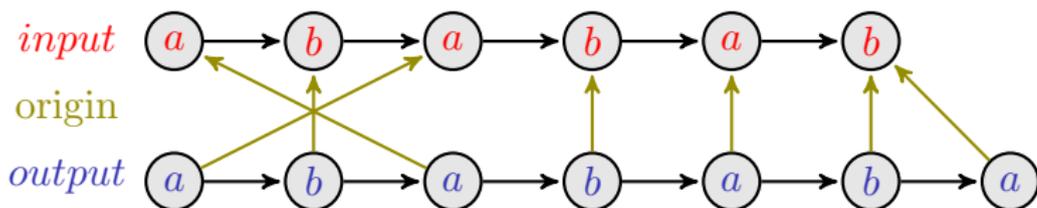
# An expressive origin-based logic tailored to transductions (Dartois, F., Lhote, 18)



transduction  $\approx$  set of origin graphs

$$\text{MSO}[\leq_{in}, \leq_{out}, o]$$

# An expressive origin-based logic tailored to transductions (Dartois, F., Lhote, 18)



transduction  $\approx$  set of origin graphs

$$\text{MSO}[\leq_{in}, \leq_{out}, o]$$

## Results

- ▶  $T \models \phi$  decidable for 2-way transducers
- ▶ undecidable satisfiability
- ▶ decidable fragment with regular synthesis
- ▶ correspondence with data words

## Some Other Results

- ▶ machine-independent characterisations

Cadilhac, Krebs, Ludwig, Paperman, 15

## Some Other Results

- ▶ machine-independent characterisations

Cadilhac, Krebs, Ludwig, Paperman, 15

- ▶ uniformisation problems (Ismaël's Jecker and Sarah Winter's PhD thesis). E.g. given  $R$  rational, is there  $f$  sequential such that

- ▶  $f \subseteq R$
- ▶  $\text{dom}(f) = \text{dom}(R)$

## Some Other Results

- ▶ machine-independent characterisations

Cadilhac, Krebs, Ludwig, Paperman, 15

- ▶ uniformisation problems (Ismaël's Jecker and Sarah Winter's PhD thesis). E.g. given  $R$  rational, is there  $f$  sequential such that

- ▶  $f \subseteq R$

- ▶  $dom(f) = dom(R)$

- ▶ learning

Boiret, Lemay, Niehren 12

## Some Other Results

- ▶ machine-independent characterisations  
Cadilhac, Krebs, Ludwig, Paperman, 15
- ▶ uniformisation problems (Ismaël's Jecker and Sarah Winter's PhD thesis). E.g. given  $R$  rational, is there  $f$  sequential such that
  - ▶  $f \subseteq R$
  - ▶  $\text{dom}(f) = \text{dom}(R)$
- ▶ learning  
Boiret, Lemay, Niehren 12
- ▶ data word transducers Léo Exibard's PhD thesis

## Some Other Results

- ▶ machine-independent characterisations  
Cadilhac, Krebs, Ludwig, Paperman, 15
- ▶ uniformisation problems (Ismaël's Jecker and Sarah Winter's PhD thesis). E.g. given  $R$  rational, is there  $f$  sequential such that
  - ▶  $f \subseteq R$
  - ▶  $\text{dom}(f) = \text{dom}(R)$
- ▶ learning  
Boiret, Lemay, Niehren 12
- ▶ data word transducers Léo Exibard's PhD thesis
- ▶ other structures: infinite strings, nested words, trees, graphs, data words ...

## A Few Applications

- ▶ language and speech processing (M. Mohri)
- ▶ regular model-checking
- ▶ text analysis, document transformation
- ▶ reactive synthesis
- ▶ **Tools:** OpenFST, Vaucanson, DreX (Alur, d'Antoni, Raghothaman)
- ▶ line of works on symbolic transducers (d'Antoni, Veanes ...)

Thanks!

Thanks for your attention!

# Announcements

## RP'19, September 11-13, Brussels

- ▶ conference on reachability problems
- ▶ talks with submitted papers or w/o
- ▶ best papers invited for a journal issue
- ▶ deadline in June
- ▶ invited speakers: Henzinger, Protasov, Lasota, Sriram S., Raskin.

# Announcements

## RP'19, September 11-13, Brussels

- ▶ conference on reachability problems
- ▶ talks with submitted papers or w/o
- ▶ best papers invited for a journal issue
- ▶ deadline in June
- ▶ invited speakers: Henzinger, Protasov, Lasota, Sriram S., Raskin.

## 1 PostDoc position at ULB

- ▶ transducer and synthesis problems
- ▶ up to 2 years
- ▶ flexible starting date