

# The Complexity of Graph-Based Reductions for Reachability in MDPs

Stéphane Le Roux and Guillermo A. Pérez

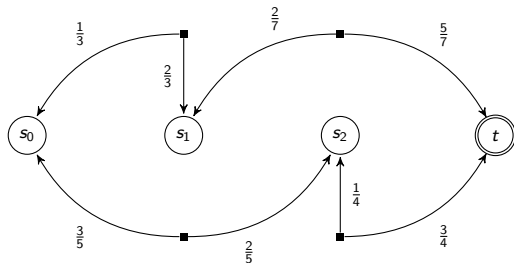
Technische Universität Darmstadt  
Université libre de Bruxelles

FoSSaCS 2018

# Markov decision processes

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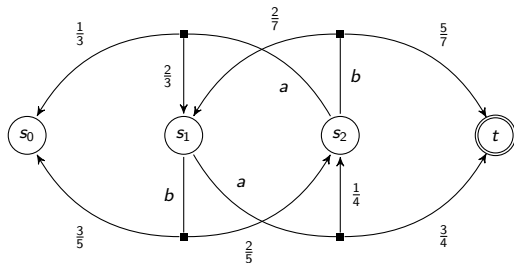
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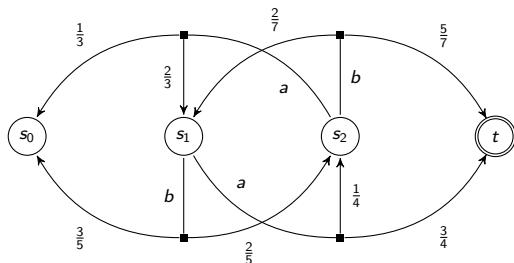
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- ▶ A **(memoryless deterministic) strategy**  $\sigma : S \rightarrow A$ , is a way to choose actions from every state.
- ▶ An MDP restricted to transitions consistent with a given strategy is a **Markov chain**.

# Reachability in MDPs

Consider an MDP  $\mathcal{M} = (S, A, \delta, T)$ .

## Reachability probability value

For  $s \in S$ , we denote by  $\mathbb{P}_{\mathcal{M}\sigma}^s[\diamond T]$  the probability of eventually reaching  $T$  in  $\mathcal{M}$  from  $s$  under  $\sigma$ .

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We are interested in **maximizing** the probability of eventually reaching  $T$  (with a memoryless deterministic strategy)

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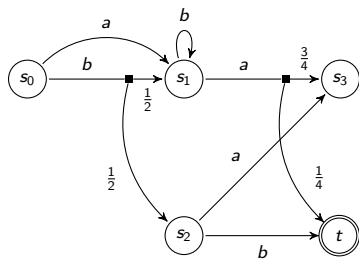
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## Theorem (Filar, Vrieze 97; Puterman 94)

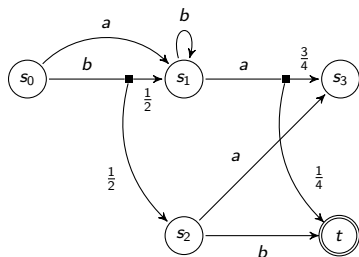
*Given  $\mathcal{M}$ , a state  $s$ , and  $\tau \in \mathbb{Q}$ , determining whether  $\mathbf{Val}_\delta(s) \geq \tau$  is decidable in polynomial time (via an encoding into a linear program).*

# Example 1



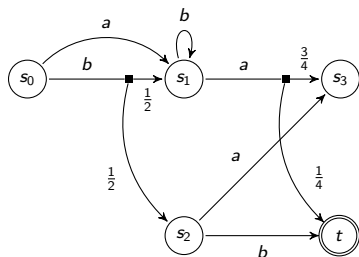


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Since  $\mathbf{Val}(s_2) = 1$  and  $\mathbf{Val}(s_1) = \frac{1}{4}$ ,

$$\mathbf{Val}(s_0) \geq \frac{1}{8} + \frac{1}{2} = \frac{5}{8}$$

# Motivation: why study (redux for) reachability in MDPs?

## Verification

Markov decision processes are perfect models for systems with stochastic and non-deterministic components. Verifying **safety** and **liveness** properties in MDPs reduces to reachability analysis.

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# de Alfaro's end components

Consider an MDP  $\mathcal{M} = (S, A, \delta, T)$ .

## End components

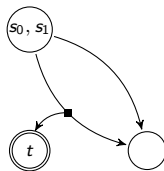
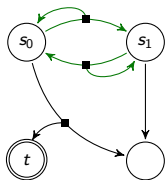
$Q \subseteq S$  and  $\alpha : S \rightarrow \mathcal{P}(A)$  are an end component if playing actions allowed by  $\alpha$  ensures staying in  $Q$  and the induced digraph in  $\mathcal{M}$  is strongly connected

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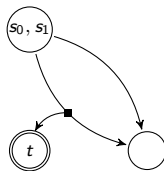
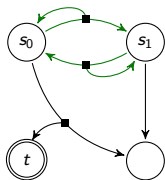


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They are awesome!

All states in an end component have the same value (for all same-support distributions); and they can be “collapsed”. Maximal end components are computable in polynomial time!

# More graph-based reductions

## Efficient reductions [Ciesinski, Baier, Größer, Klein 08]

Before value iteration, one can compute in polynomial time

- ▶ extremal-probability states,
- ▶ essential states [D'Argenio, Jeannet, Jensen, Larsen 02],
- ▶ maximal end components.

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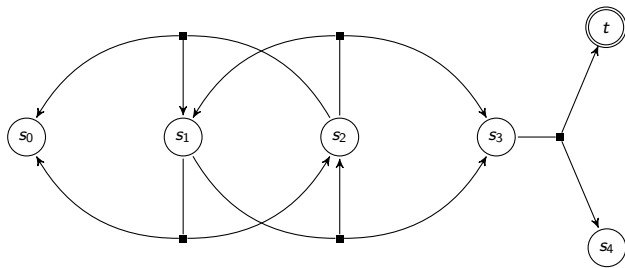
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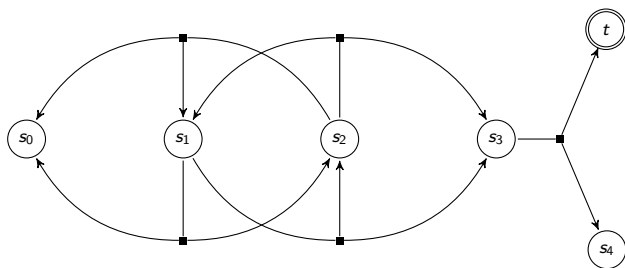
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Can we do better/more?

# Other components

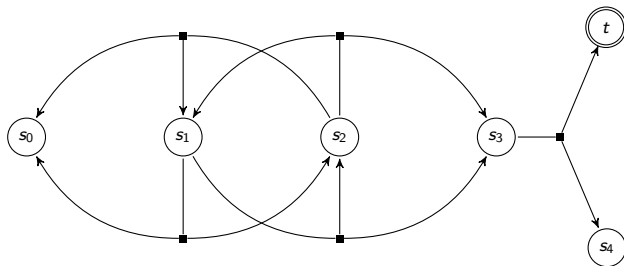


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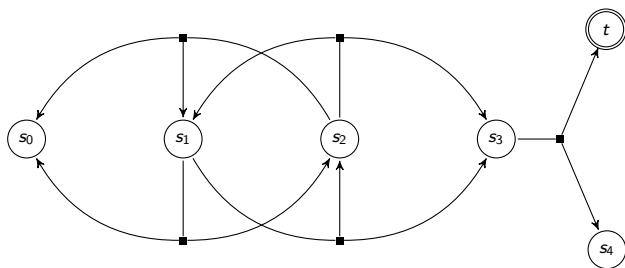
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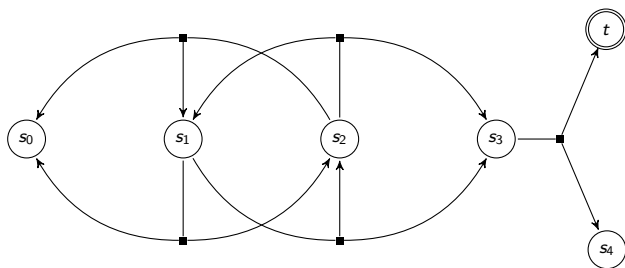
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(the above analysis holds for all same-support  $\delta$ !)



# The never-worse relation

Consider an MDP  $\mathcal{M} = (S, A, \delta, T)$ .

## Never worse

For states  $Q \subseteq S$  and a state  $s$ , we say  $Q$  is **never worse** than  $s$  if

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## Theorem (Removing sub-optimal actions)

*If  $A \setminus \{a\}$  is never worse than  $a$  from  $s$ , then playing  $a$  from  $s$  can be ruled out.*

# First check: captures known reductions

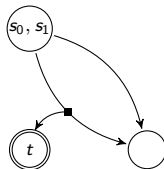
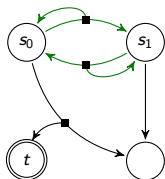
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*Known polynomial-time computable reduction heuristics (end components, extremal-probability states, essential states, . . . ) are all special cases of the NWR.*

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$s_0$  and  $s_1$  are NWR-equivalent

## Second check: captures other gadgets

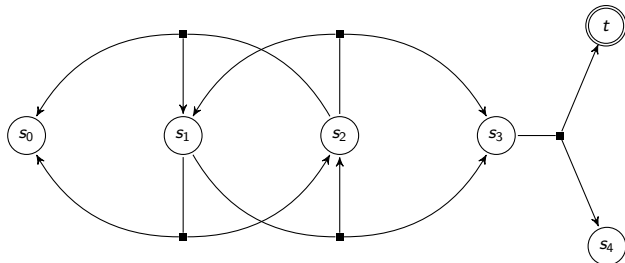
### Proposition

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$s_1$  and  $s_2$  are NWR-equivalent

## Third check: works in practice?

### PRISM: Randomized consensus shared coin protocol

Formula	No reds.	Known reds.	New reds.
$\varphi_1$	400	392	76
$\varphi_2$	400	392	92

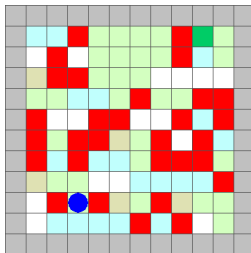
$$\varphi_1 = \diamond (\text{"finished"} \wedge \text{"all coins equal 1"})$$

$$\varphi_2 = \diamond (\text{"finished"} \wedge \neg \text{"all coins equal 1"})$$



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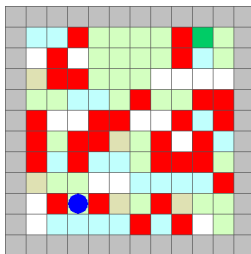
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	No reds.	Known reds.	New reds.
Distributions	400	102	8
Episodes	1,133,243	948,882	83,564
Total steps	11,683,438	7,848,560	734,465

# Graph-based characterization

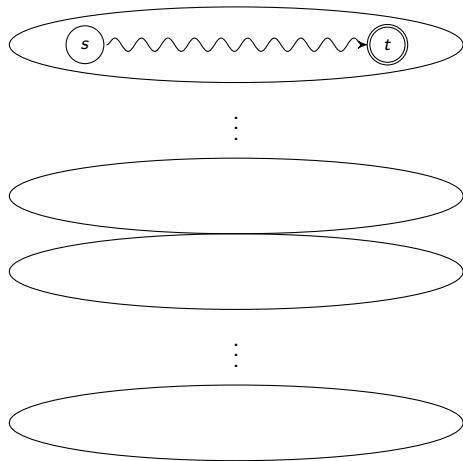
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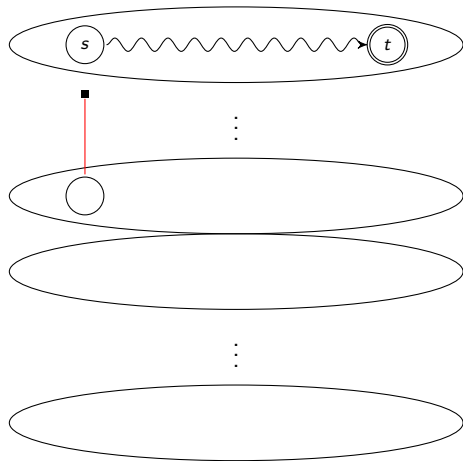
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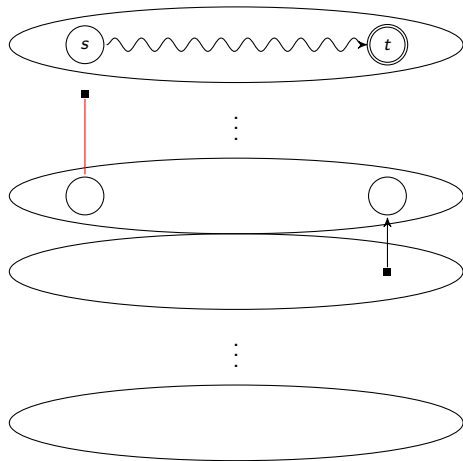
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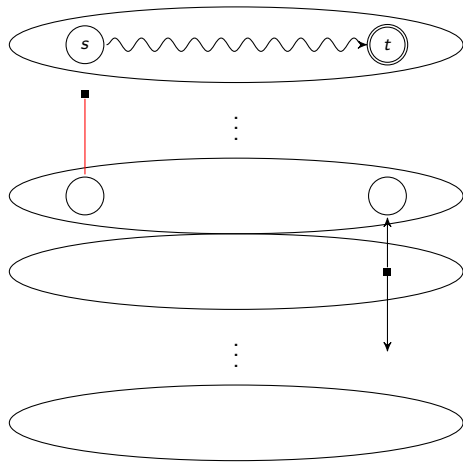
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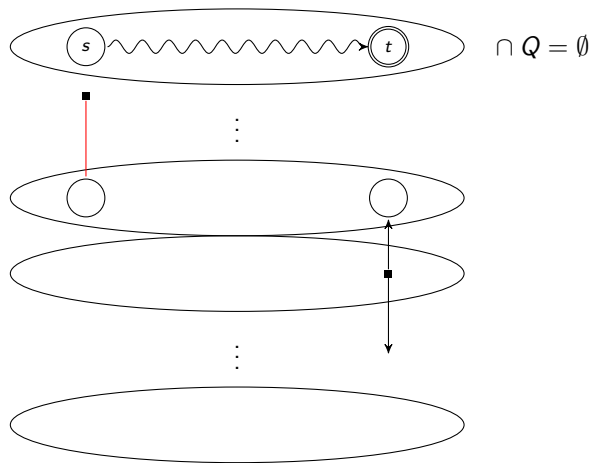
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One can then prove that

- ▶  $\mathbf{Val}_\delta(s) \geq (1 - \varepsilon)^{|S|}$  and
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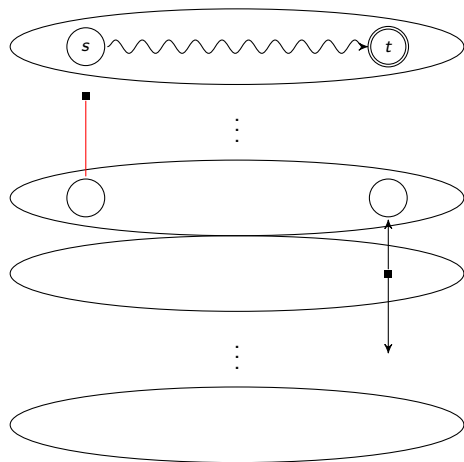
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For sufficiently small  $\varepsilon$ , we get

$$\mathbf{Val}_\delta(s) > \max_{q \in Q} \mathbf{Val}_\delta(q)$$

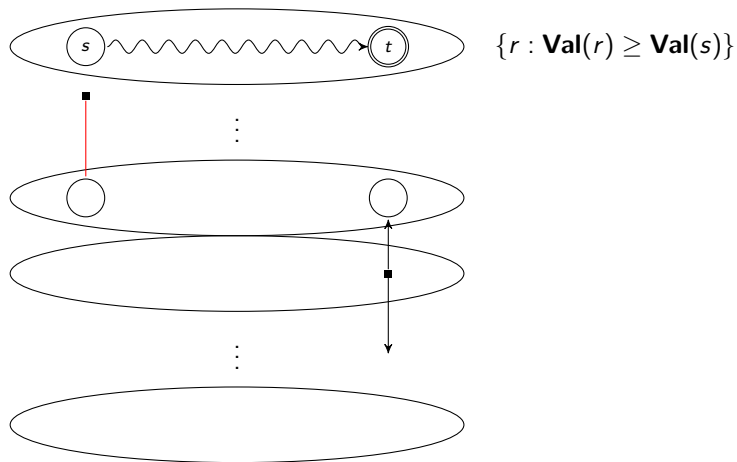
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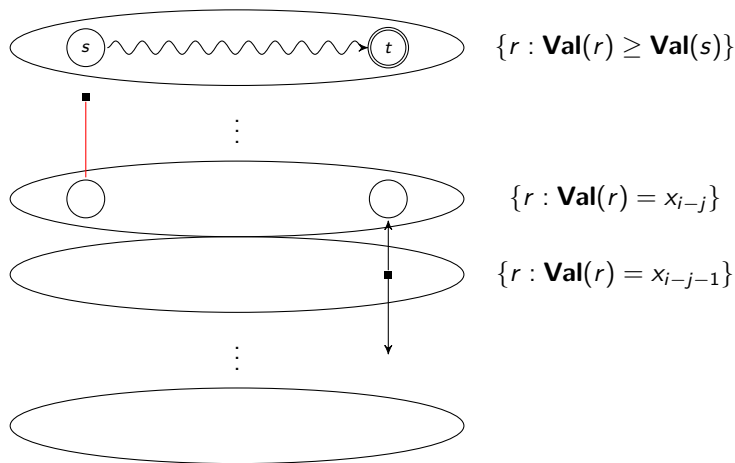
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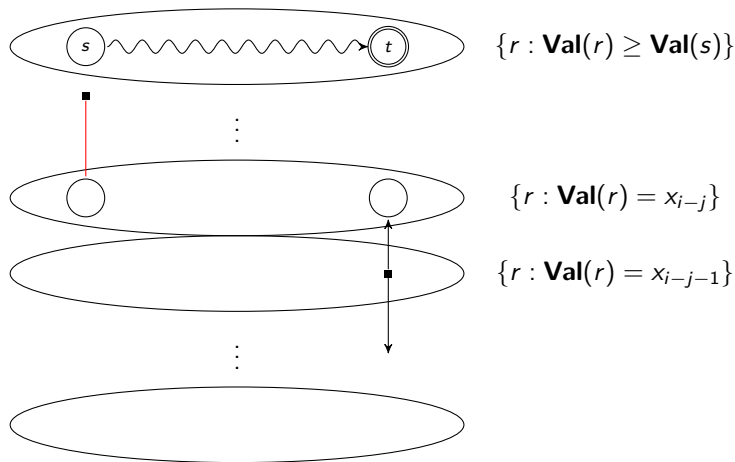
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One can then show this is indeed a  $(Q, s)$ -drift partition.



# The complexity of the NWR

## Theorem (NWR-membership)

*Given an MDP  $\mathcal{M}$ ,  $Q$  and  $s$ , determining if  $Q$  is never worse than  $s$  is coNP-complete.*

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- ▶ Yes! but value iteration is exponential in the worst case.
- ▶ Also, learning the probabilities takes exponentially many experiments.
- ▶ The relation can be queried using a SAT solver.
- ▶ Non-tractability further motivates under-approximating the relation.

# Efficient under-approximations of the NWR

## Iterative algorithm

Let  $\hat{R}$  be the relation containing all NWR-pairs one gets from

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- ▶ essential states,
- ▶ maximal end components.

Repeat until convergence: “grow”  $\hat{R}$  using efficiently-computable rules that imply more NW-pairs.

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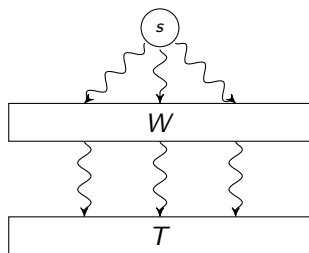
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$$\hat{R} \subseteq \text{NWR}$$

# Rule 1

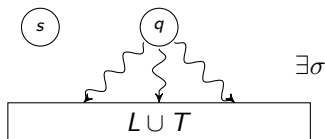


## Proposition (Rule 1)

*Given  $s$  and  $Q \subseteq S$ , if we find the above pattern with  $W = \{r : Q \text{ is NW than } r\}$  then  $Q$  is never worse than  $s$ .*



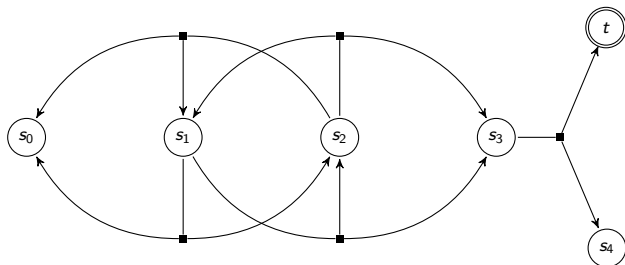
## Rule 2



### Proposition (Rule 2)

*Given  $s$  and  $q$ , if we find the above pattern with  $L = \{r : r \text{ is NW than } s\}$  then  $q$  is never worse than  $s$ .*

## Back to those other components



- ▶ Rule 1:  $s_3$  is never worse than  $s_1, s_2$
- ▶ Rule 2:  $s_1, s_2$  are never worse than  $s_3$

## Conclusions

- ▶ Nice relation giving a sufficient condition for MDP reductions
- ▶ Seems to work in practice (in terms of reduction efficiency)  
[Bharadwaj, Le Roux, P., Topcu IJCAI'17]
- ▶ Exact complexity of the full relation [Le Roux, P. FoSSaCS'18]

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## Future work

- ▶ Relation to “value-preserving sets”?
- ▶ More experiments (SAT-solvers for full relation; impact on MC running time)
- ▶ Extensions
  - ▶ on-the-fly algorithms
  - ▶ finite-horizon reachability
  - ▶ reward MDPs (expected mean payoff, etc.)