

Minimizing Regret in Infinite-Duration Games Played on Graphs

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Université libre de Bruxelles

LiVe 2018

What is this talk about?

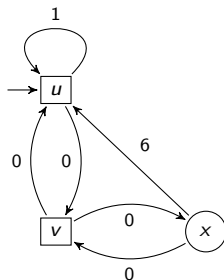
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Weighted graphs, \exists ve, \forall dam, Strategies, Infinite plays, and Payoff functions

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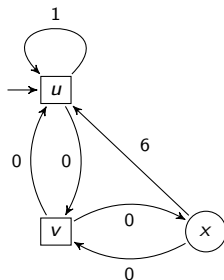
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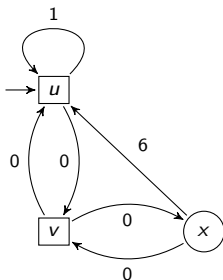
\square \exists ve $\sigma : V^* V_{\exists} \rightarrow V$

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$$\left. \begin{array}{l} \square \quad \exists\text{ve} \\ \circ \quad \forall\text{dam} \end{array} \right\} \begin{array}{l} \sigma : V^* V_{\exists} \rightarrow V \\ \tau : V^* V_{\forall} \rightarrow V \end{array} \quad \pi_{\sigma\tau} = v_0 v_1 \dots$$

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Classical payoff functions

- ▶ parity $\mathbb{N}^\omega \rightarrow \mathbb{B}$, positive energy $\mathbb{Z}^\omega \rightarrow \mathbb{B}$
- ▶ sup, inf, lim sup, lim inf, mean payoff, discounted sum

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We consider the mean-payoff function

$$\mathbf{Val}(x_1, x_2, \dots) = \liminf_{n \geq 1} \frac{1}{n} \sum_{i=1}^n x_i$$

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Denote by $\mathbf{Val}(\sigma, \tau)$ the value $\mathbf{Val}(w(v_0, v_1), w(v_1, v_2), \dots)$ where $\pi_{\sigma\tau} = v_0 v_1 v_2 \dots$

Motivation 1: Modelling power

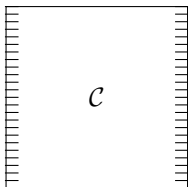
Mean-payoff games

are able to model [Zwick, Paterson 1996]

- ▶ online metrical task systems,
- ▶ finite window online string matching, and
- ▶ selection with limited storage.

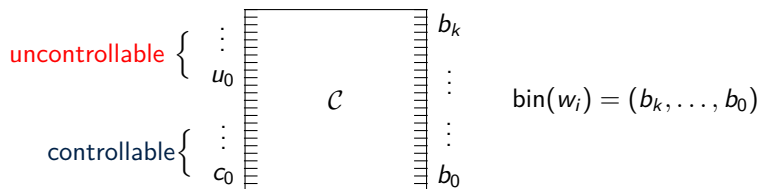
Motivation 2: Reactive synthesis

Consider a sequential circuit \mathcal{C} with input set X partitioned into **uncontrollable** X_u and **controllable** X_c and output set B



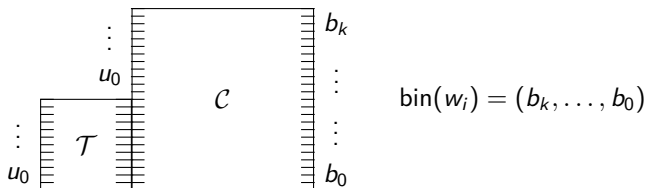
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Synthesis

Does there exist \mathcal{T} such that $\mathbf{Val}(w_1, w_2, \dots) \models_{\text{Spec}}$ for all sequences of valuations of X_u ?

Motivation 3: Interesting open problems

Existence of winning strategies

Does there exist a (finite memory) strategy σ of \exists ve such that

$$\inf_{\tau} \mathbf{Val}(\sigma, \tau) \geq \ell?$$

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Parity games

Given a parity game, to determine if \exists ve has a winning strategy is in $\text{UP} \cap \text{coUP}$ [Jurdziński 1998] as well as in QP [Calude et al. 2017].

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Known reductions [Zwick, Paterson 1996; Jurdziński 1998]

The following hold when graphs are given explicitly; weights (and discount factor), in binary.

$$PGs \leq_P MPGs \leq_P DSGs \leq_P SSGs$$

What do you mean by regret minimization?

In words. . .

We want to find a strategy of \exists ve that minimizes the difference between her actual payoff and the payoff she could have achieved if she had known the strategy of \forall dam in advance.

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- ▶ Automata determinization by pruning [Aminof, Kupferman, Lampert 2010], good-for-games automata [Henzinger, Piterman 2006]

Values of a game

Let \mathcal{G} be a game.

Cooperative value

$$\mathbf{cVal}(\mathcal{G}) := \sup_{\sigma} \sup_{\tau} \mathbf{Val}(\sigma, \tau)$$

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Antagonistic value

$$\mathbf{aVal}(\mathcal{G}) := \sup_{\sigma} \inf_{\tau} \mathbf{Val}(\sigma, \tau)$$

A formal definition of regret

Let Σ_{\exists} be a set of strategies of \exists ve and Σ_{\forall} a set of strategies of \forall dam.

The regret of σ

$$\mathbf{reg}_{\Sigma_{\exists}, \Sigma_{\forall}}^{\sigma}(\mathcal{G}) := \sup_{\tau \in \Sigma_{\forall}} \left(\overbrace{\sup_{\sigma' \in \Sigma_{\exists}} \mathbf{Val}(\sigma', \tau)}^{\text{best-response value}} - \mathbf{Val}(\sigma, \tau) \right)$$

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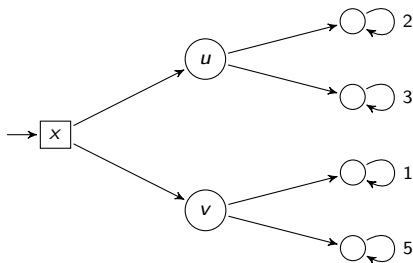
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The regret of \exists ve in \mathcal{G}

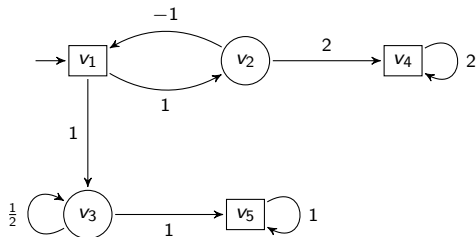
$$\mathbf{Reg}_{\Sigma_{\exists}, \Sigma_{\forall}}(\mathcal{G}) := \inf_{\sigma \in \Sigma_{\exists}} \mathbf{reg}_{\Sigma_{\exists}, \Sigma_{\forall}}^{\sigma}(\mathcal{G})$$

Example: simple tree-like mean-payoff game (MPG)



$$\mathbf{cVal}(\mathcal{G}) = 5, \mathbf{aVal}(\mathcal{G}) = 2, \mathbf{Reg}(\mathcal{G}) = 2$$

Example: it's a trap!



$$\mathbf{cVal}(\mathcal{G}) = 2, \mathbf{aVal}(\mathcal{G}) = \frac{1}{2}, \mathbf{Reg}(\mathcal{G}) = 1$$

Results

Theorem (Hardness)

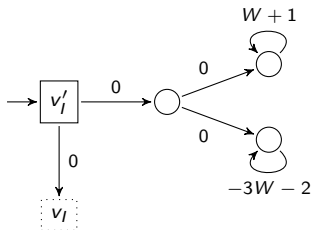
Computing the regret of a game is at least as hard as computing the antagonistic value of a (polynomial-size) game with the same payoff function.

From MPGs to MP Regret games

If $W := \max_{e \in E} |w(e)|$ then $-W \leq \mathbf{aVal}(\mathcal{G}) \leq \mathbf{cVal}(\mathcal{G}) \leq W$

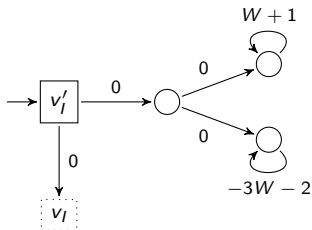
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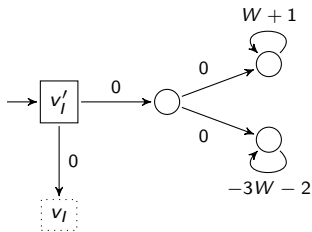
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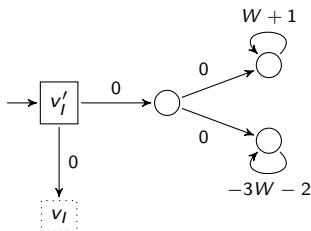
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2. \forall dam plays antagonistically from v_I and allows $W + 1$ from v'_I

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1. \exists ve plays to v_I
2. \forall dam plays antagonistically from v_I and allows $W + 1$ from v'_I
3. the regret of \exists ve in the game is $W + 1 - \mathbf{aVal}(\mathcal{G})$

Results

Theorem (Hardness)

Computing the regret of a game is at least as hard as computing the antagonistic value of a (polynomial-size) game with the same payoff function.

Theorem (Algorithm)

Computing the regret reduces to computing the antagonistic value of a (polynomial-size) game with the same payoff function.

From MP Regret games to MPGs

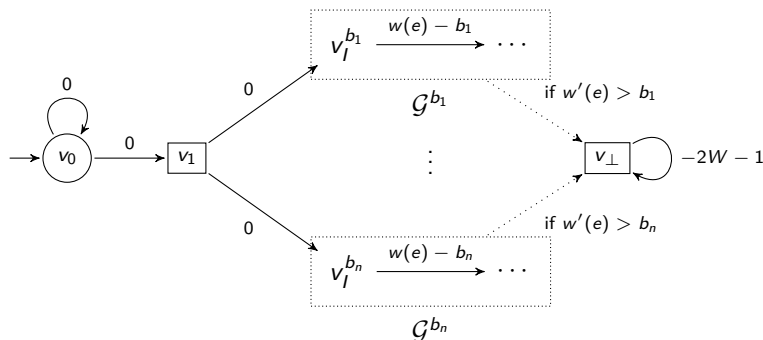
1. Label \forall edges as $w'(e) = -\infty$ and \exists edges as follows:
 $w'(e) = \max\{\mathbf{cVal}^{v'} : (u, v') \in E \setminus \{e\}\}.$

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2. Let \mathcal{G}^b be the restriction of \mathcal{G} to edges e with $w'(e) \leq b$.

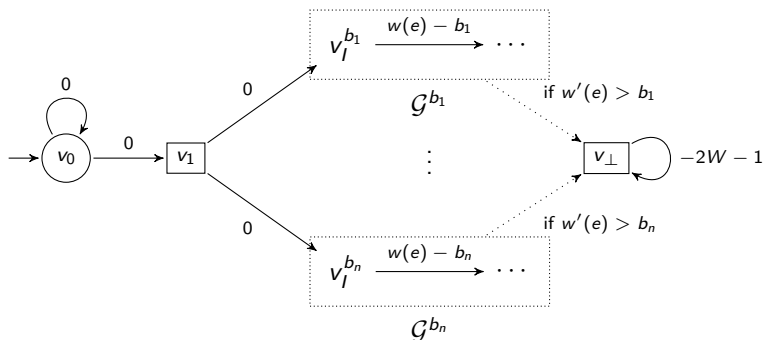
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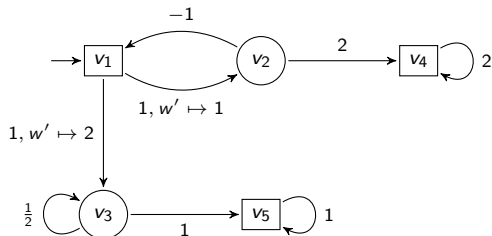
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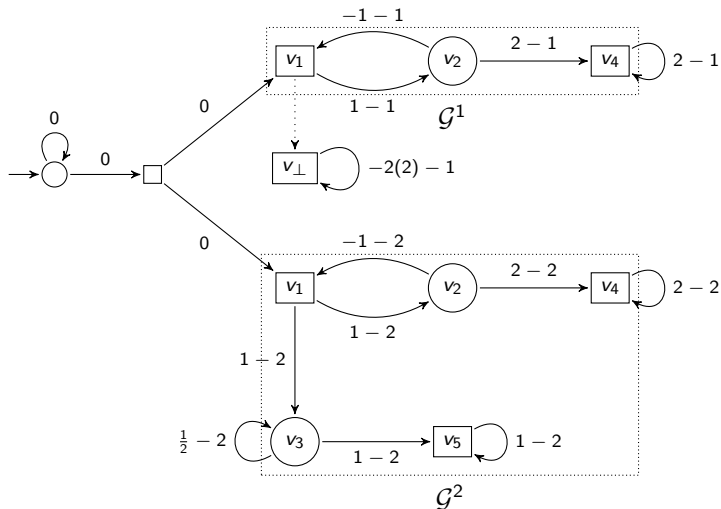
$$\implies \mathbf{aVal}(\mathcal{G}') = -\mathbf{Reg}(\mathcal{G})$$

Example: it's a trap!



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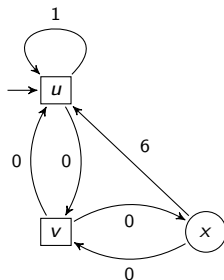
From MP Regret games to MPGs (example)



$$\mathbf{aVal}(\mathcal{G}') = -1$$

Motivating example: Learning in an MPG

Assume \forall dam plays **positionally**.



$$\mathbf{cVal}(\mathcal{G}) = 2, \mathbf{aVal}(\mathcal{G}) = 1, \mathbf{Reg}_{\text{Pos}_\forall}(\mathcal{G}) = 0$$

Results

Theorem (Hardness)

Given $r \in \mathbb{Q}$ and a weighted graph \mathcal{G} , determining whether the regret value is less than r is PSPACE-hard.

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Theorem (Algorithm)

The regret value can be computed using only polynomial space.

From MP Regret games to MPGs

We construct a new graph $\hat{\mathcal{G}}$ where

- ▶ the vertices record the witnessed choices of \forall dam

$$\hat{V} = V \times \mathcal{P}(E)$$

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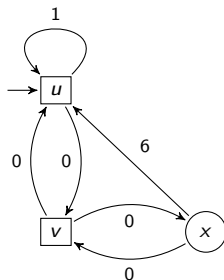
- ▶ the new weight function uses this info to reduce the value of potential alternatives

$$\hat{w}((u, C), (v, D)) = w(u, v) - \mathbf{cVal}(\mathcal{G} \cap D)$$

- ▶ $\mathbf{aVal}(\hat{\mathcal{G}}) = -\mathbf{Reg}_{\text{Pos}\forall}(\mathcal{G})$

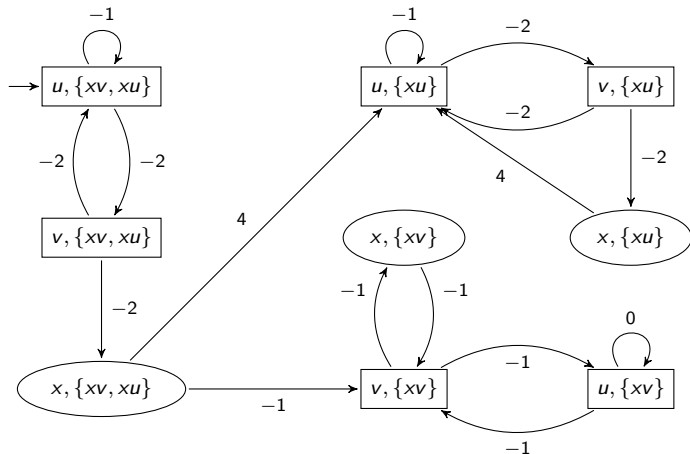
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From MP Regret games to MPGs (example)



$$\mathbf{aVal}(\hat{\mathcal{G}}) = 0$$

Any questions?

	sup	inf	lim sup	lim inf	MP	DS
Any	poly-time equiv to regular game					in NP
Positional	\in PSPACE			PSPACE-c		in EXP

Future work

- ▶ Compare to work on metrical task systems, etc.
- ▶ Improve SOTA for DS-games
- ▶ Compare to ML works on regret minimization

References

- ▶ On Delay and Regret Determinization of Max-Plus Automata. Filiot, Jecker, Lhote, P., Raskin. LICS 2017.
- ▶ Reactive Synthesis Without Regret. Acta Informatica 2017. Hunter, P., Raskin.
- ▶ Minimizing Regret in Discounted-Sum Games. CSL 2016. Hunter, P., Raskin.