# The Expressiveness of Real-Time Temporal Logics

#### Paul Hunter

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(Joint work with Joël Ouaknine and James Worrell)

Logic & Semantics Seminar, Cambridge March 2012

"Que sera, sera"

Jay Livingston and Ray Evans



- ▶ Tense logic introduced by Prior in 1950's
- Used to (automatically) verify reactive and non-terminating systems
  - "Every REQ is followed, at some point, by an ACK"

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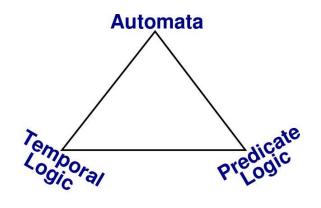
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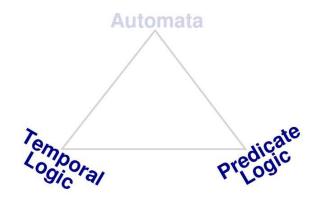
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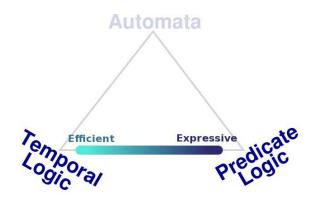
### Overview of Verification



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# **Classic temporal logic**

**Qualitative Extensions** 

**Quantitative Extensions** 

# Classic temporal models

- ► A set MP of propositions: So
- Discrete time model:



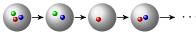
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 $f: \mathbb{N} \to 2^{MP}$  (flow or signal)

#### First-order logic (FO(<)):

$$\varphi ::= \mathbf{x} < \mathbf{y} \mid P(\mathbf{x}) \mid \varphi_1 \land \varphi_2 \mid \varphi_1 \lor \varphi_2 \mid \neg \varphi \mid \forall \mathbf{x} \varphi \mid \exists \mathbf{x} \varphi$$

For example: 
$$\forall x . \mathtt{REQ}(x) \to \exists y . ((y > x) \land \mathtt{ACK}(y))$$

Unable to express:

"P happens at every even position and may or may not hold at odd times,

#### Monadic second-order logic (MSO(<))

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#### Büchi's theorem

Flows over non-negative integer time are infinite words over the alphabet 2<sup>MP</sup>.

Theorem (Büchi 1960)

Any MSO(<) formula  $\varphi$  can be effectively translated into an equivalent automaton  $A_{\varphi}$ .

Corollary (Church 1960)

The satisfiability problems for MSO(<) and FO(<) are decidable.

What about complexity?

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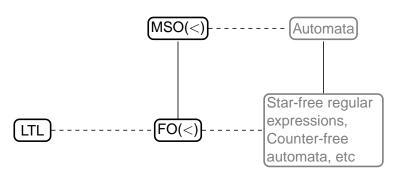
# Other temporal logics

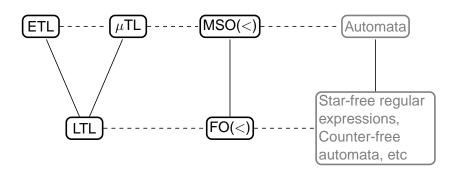
### Towards MSO(<):

- ► ETL: LTL with existential quantification
- $\blacktriangleright$   $\mu$ TL: LTL with fix-points
- ▶ LDL: LTL with regular expressions
- **...**

LTL------(FO(<)







**Classic temporal logic** 

**Qualitative Extensions** 

**Quantitative Extensions** 

Non-negative time makes sense in system verification but not necessarily from a philosophical perspective.

#### Classical:

```
► Flows: f: \rightarrow 2^{MP}
```

Predicate logics: FO(<) and MSO(<)</p>

Temporal logics: LTL, LTL+Past, . . .

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#### Classical+Past:

- ► Flows:  $f: \mathbb{Z} \to 2^{MP}$
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Discrete time makes sense in system verification but not necessarily from a physical perspective.

How to handle semantics?

### Flows:

$$f: \mathbb{Q} o 2^{\mathsf{MP}}$$
 $f: \mathbb{R}_{\geq 0} o 2^{\mathsf{MP}}$ 
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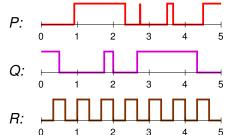
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$$f: \mathbb{R} \to 2^{MP}$$

### Pointwise (time-stamped events):

$$( au_1, p_1), ( au_2, p_2), ( au_3, p_3), \ldots$$
 where  $au_1 < au_2 < \ldots \in \mathbb{Q}$  ( or  $\mathbb{R}$ ) and  $p_i \in \mathbf{MP}$ 

Some good news:

Theorem (Rabin 1969) MSO(<) is decidable over  $\mathbb{Q}$ .

Some bad news:

Theorem (Shelah 1975)

MSO(<) is undecidable over [0, 1)

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# Kamp's theorem again

Some great news:

Kamp's theorem applies over all domains (rationals need Stavi connectives)

Theorem (Kamp 1968; Gabbay et al. 1980)

LTL+Past is as expressive as FO(<) (over  $\mathbb{R}$ ).

# Separation of temporal logics

### A temporal logic formula is

- pure past if it is invariant on flows that agree on the past
- pure present if is invariant on flows that agree on the present
- pure future if is invariant on flows that agree on the future

A temporal logic is separable if all its formulas are equivalent to a boolean combination of pure past, present and future formulas.

Lemma LTL+Past is separable

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#### Lemma

LTL+Past is separable.

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Theorem (Gabbay 1981)
A temporal logic is expressively complete if and only if it is separable.



#### Proof sketch:

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# Qualitative extensions: Summary

	FO(<)	MSO(<)	LTL expressively
	decidable?	decidable?	complete?
Classical	Yes	Yes	Yes
Integer time	Yes	Yes	Yes
Rational time	Yes	Yes	Sort of
Real time	Yes	No	Yes

**Classic temporal logic** 

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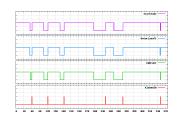
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Want to specify

"If I press the brake pedal then the pads will be applied within 0.1ms.

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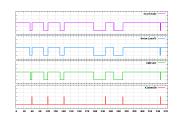


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### Timed systems also occur in:

- Hardware circuits
- Communication protocols
- Cell phones
- Plant controllers
- Aircraft navigation systems
- **•** . . .

### Example: Timed automata

Timed automata were introduced by Rajeev Alur at Stanford during his PhD thesis under David Dill.





Automata with clocks that run over  $\mathbb{R}_{\geq 0}$ , and clock constraints that determine which transitions are available.

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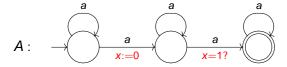
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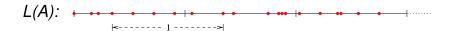




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### Adding time metrics to the models

We want to add a metric to the model so we can enforce certain timing constraints, for example:

"Apply brake pads between 5 to 10 time units after pedal is pushed".

 $\mathbb{N}$ ,  $\mathbb{Z}$ ,  $\mathbb{Q}$ , and  $\mathbb{R}$  all have suitable distance metrics.

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# Metric predicate logic

We add a unary function +1 to the predicate logics to model moving to 1 time unit into the future.

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becomes

$$\forall x. \texttt{PEDAL}(x) \rightarrow \exists y. \ (x+5 < y < x+10) \land \texttt{BRAKE}(y).$$
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a formula of FO(<,+1).

### Temporal logics: MTL

Metric Temporal Logic (MTL) [Koymans; de Roever; Pnueli  $\sim$ 1990] is a central quantitative specification formalism for timed systems.

MTL = LTL + timing constraints on operators:

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Formally,

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### Temporal logics: MTL+Past

We can also add timing constraints to past modalities.

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### Temporal logics: TPTL

Motivated by timed automata, Timed Propositional Temporal Logic (TPTL) [Alur & Henzinger 1994] adds clocks and clock constraints to LTL using *freeze variables*.

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 Formally

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#### Immediately we have

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Over the integers +1 is definable in FO(<)

$$y = x + 1 \equiv y > x \land \forall z.z < x \lor z > y$$

So LTL = FO(<,+1) over  $\mathbb N$  and  $\mathbb Z$ .

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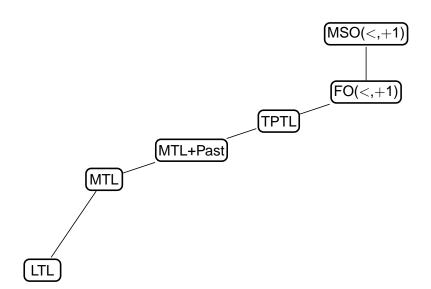
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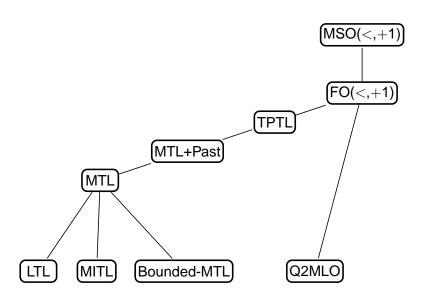
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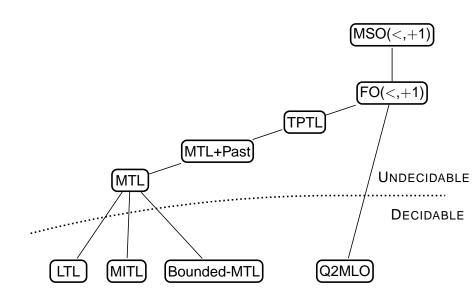
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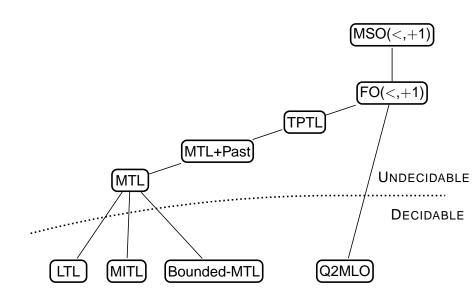
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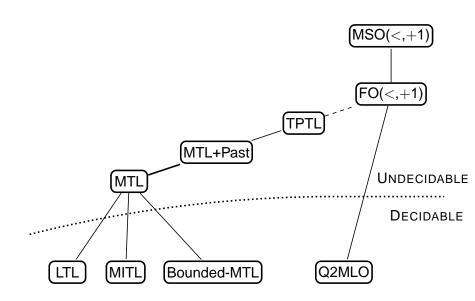
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Let  $\mathcal{L}$  be a temporal logic.

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## Temporal logic: Summary

