The Expressiveness of Metric Temporal Logic

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"If the brake pads were applied then the pedal was pushed."

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Bounded formulas

Metric separation

Corollaries, Conclusions and Continuations

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Temporal models

- A set **MP** of propositions: *P*, *Q*, *R*, ...
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Classic temporal predicate logic

FO(<): First-order logic with < and monadic predicates for each proposition $P \in MP$:

$$\varphi ::= \mathbf{x} < \mathbf{y} \mid \mathbf{P}(\mathbf{x}) \mid \varphi_1 \land \varphi_2 \mid \varphi_1 \lor \varphi_2 \mid \neg \varphi \mid \forall \mathbf{x} \varphi \mid \exists \mathbf{x} \varphi$$

For example:

$$\forall x . \texttt{BRAKE}(x) \rightarrow \exists y . ((y < x) \land \texttt{PEDAL}(y)).$$

Temporal logic: LTL

Linear Temporal Logic (LTL): Propositional logic with temporal modalities:

$$\begin{array}{rcl} \theta & ::= & P \mid \theta_1 \land \theta_2 \mid \theta_1 \lor \theta_2 \mid \neg \theta \\ & \mid \mathbf{F} \ \theta & (\theta \ \text{occurs in the Future}) \\ & \mid \mathbf{G} \ \theta & (\theta \ \text{occurs always (Globally)}) \\ & \mid \theta_1 \ \mathbf{U} \ \theta_2 & (\theta_1 \ \text{holds Until} \ \theta_2) \\ & \mid \mathbf{P} \ \theta & (\theta \ \text{occurred in the Past}) \\ & \mid \mathbf{H} \ \theta & (\theta \ \text{has always occurred (Historically)}) \\ & \mid \theta_1 \ \mathbf{S} \ \theta_2 & (\theta_1 \ \text{has held Since} \ \theta_2) \end{array}$$

For example,

\mathbf{G} (brake $\rightarrow \mathbf{P}$ pedal)

LTL is subsumed by FO(<), for example

 $P \cup Q \equiv \exists x (Q(x) \land \forall y . (y < x) \rightarrow P(y)).$

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$$P \mathbf{U} \mathbf{Q} \equiv \exists x (\mathbf{Q}(x) \land \forall y . (y < x) \rightarrow P(y)).$$

Kamp's theorem

Theorem (Kamp 1968, GPSS 1980) LTL is as expressive as FO(<).



Metric Temporal Logic (MTL) [Koymans; de Roever; Pnueli \sim 1990] is a central quantitative specification formalism for timed systems.

MTL = LTL + timing constraints on operators:

$$G(BRAKE \rightarrow P_{(5,10)} PEDAL)$$

Formally,

where I is an interval of \mathbb{Q} .

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Metric Predicate Logic

We add many unary functions $\{+q : q \in \mathbb{Q}\}$ to FO(<) to model moving *q* time units into the future.

 $\forall x. \texttt{BRAKE}(x) \rightarrow \exists y. (x-10 < y < x-5) \land \texttt{PEDAL}(y),$ a formula of FO(<,+q).

With integral constraints, FO(<,+1) suffices.

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A non-extension of Kamp's theorem





Theorem (Hirshfeld & Rabinovich 2007) MTL with integer end-points is strictly less expressive than FO(<,+1) over \mathbb{R} , even with infinitely many additional modal operators of bounded quantifier depth.

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Theorem (Hirshfeld & Rabinovich 2007)

MTL with integer end-points is strictly less expressive than FO(<,+1) over \mathbb{R} , even with infinitely many additional modal operators of bounded quantifier depth.

Main result

Theorem *MTL* has the same expressive power as FO(<,+q).

Bounded formulas

Metric separation

Corollaries, Conclusions and Continuations

Lemma MTL can express all bounded FO(<,+1)-formulas.

MTL with integer endpoints is unable to express:

"P occurs twice in the next time interval."

In FO(<, +1):

 $\varphi(z) = \exists x. \exists y. (z < x < y < z +) \land \mathbb{P}(x) \land \mathbb{P}(y).$

In MTL:

MTL with integer endpoints is unable to express:

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In FO(<, +1):

 $\varphi(z) = \exists x. \exists y. (z < x < y < z + 1) \land \mathbb{P}(x) \land \mathbb{P}(y).$

In MTL:

$$\begin{array}{l} \red{scalar} \red{scalar} \red{scalar} (F_{(0,1)} \mathbb{P} \wedge F_{(1,2)} \mathbb{P}) \quad \lor \\ F_{=2} \Big(P_{(0,1)} \big(\mathbb{P} \wedge P_{(0,1)} \mathbb{P} \big) \Big) \end{array}$$

MTL with integer endpoints is able to express:

"P occurs twice in the next two time intervals." In FO(<, +1): $\varphi(z) = \exists x. \exists y. (z < x < y < z + 2) \land P(x) \land P(y).$ In MTL: $\varphi = \mathbf{F}_{(0,1)}(P \land \mathbf{F}_{(0,1)}P) \lor$ $(\mathbf{F}_{(0,1)}P \land \mathbf{F}_{(1,2)}P) \lor$ $\mathbf{F}_{=2}(\mathbf{P}_{(0,1)}(P \land \mathbf{P}_{(0,1)}P))$

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$$= \mathbf{F}_{(0,1)}(\mathbb{P} \land \mathbf{F}_{(0,1)}\mathbb{P}) \lor \\ (\mathbf{F}_{(0,1)}\mathbb{P} \land \mathbf{F}_{(1,2)}\mathbb{P}) \lor \\ \mathbf{F}_{=2}(\mathbf{P}_{(0,1)}(\mathbb{P} \land \mathbf{P}_{(0,1)}\mathbb{P}))$$

Adding granularity

$$\varphi = \mathbf{F}_{(0,1)} \left(\mathbb{P} \wedge \mathbf{F}_{(0,1)} \ \mathbb{P} \right) \lor$$

$$\left(\mathbf{F}_{(0,1)} \ \mathbb{P} \wedge \mathbf{F}_{(1,2)} \ \mathbb{P} \right) \lor$$

$$\mathbf{F}_{=2} \left(\mathbf{P}_{(0,1)} \ \left(\mathbb{P} \wedge \mathbf{P}_{(0,1)} \ \mathbb{P} \right) \right)$$

Corollary

"P occurs twice in the next time interval" is expressible in MTL with rational end-points.

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Separability is a key property for showing LTL and FO have the same expressive power.

A temporal logic formula is

- pure past if it is invariant on flows that agree on the past
- pure present if is invariant on flows that agree on the present
- pure future if is invariant on flows that agree on the future

A temporal logic is separable if all its formulas are equivalent to a boolean combination of pure past, present and future formulas.

 ${f G}({f BRAKE} o {f P}{f PEDAL})$ = P pedal (-brake U pedal) v ${f G}(-brake)$

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$$\begin{split} & \textbf{G}(\texttt{BRAKE} \rightarrow \textbf{P} \texttt{PEDAL}) \\ = \textbf{P} \texttt{PEDAL} ~\lor~ (\neg \texttt{BRAKE}~\textbf{U}~\texttt{PEDAL}) ~\lor~ \textbf{G}(\neg \texttt{BRAKE}) \end{split}$$

Lemma LTL is separable.

Theorem (Gabbay 1981)

A temporal logic is expressively complete if and only if it is separable.



Corollary (Kamp's theorem) LTL is expressively complete.

Separation does not hold in the quantitative setting.

For example,

$$G(\texttt{BRAKE}
ightarrow \mathbf{P}_{(5,10)}\texttt{PEDAL})$$

A metric temporal formula is:

- pure distant past if it is invariant on flows that agree on $(-\infty, -1)$
- ► pure distant future if it is invariant on flows that agree on (1,∞)
- ▶ bounded if there is an N such that it is invariant on all flows that agree on (-N, N)

A temporal logic is metrically separable if every formula is equivalent to a boolean combination of pure distant past, pure distant future and bounded formulas.

Lemma MTL is metrically separable.

 $\begin{array}{lll} \textbf{G}(\text{BRAKE} \rightarrow \textbf{P}_{(5,10)}\text{PEDAL}) &= & \textbf{G}_{(0,11]}(\text{BRAKE} \rightarrow \textbf{P}_{(5,10)}\text{PEDAL}) \land \\ & \textbf{G}_{(11,\infty)}(\text{BRAKE} \rightarrow \textbf{P}_{(5,10)}\text{PEDAL}) \end{array}$

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An extension of Gabbay's theorem

Corollary

MTL can express FO(<,+1) if and only if it can express all bounded formulas.

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Conclusions and further work

- First generalization of Kamp's theorem to the quantitative setting.
- Generalization of Gabbay's theorem to the quantitative setting.

Recent results (CSL 2013):

- Other sets of constants (e.g. $\mathbb{R}, \mathbb{Z}[\sqrt{2}]$).
- Expressive completeness for MTL with counting.

Still to do:

- Cost of expressibility.
- ▶ Better generalization of Gabbay's Theorem.
- Extension to more expressive metric temporal logics.

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